

# Sharper Bounds for Uniformly Stable Algorithms with Stationary Mixing Process

Shi Fu<sup>1</sup>, Yunwen Lei<sup>2</sup>, Qiong Cao<sup>3</sup>, Xinmei Tian<sup>1</sup> and Dacheng Tao<sup>3,4</sup>

<sup>1</sup>University of Science and Technology of China

<sup>2</sup>Hong Kong Baptist University

<sup>3</sup>JD Explore Academy

<sup>4</sup>University of Sydney

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# Motivation

- **Generalization analysis** of learning algorithms often builds on a critical assumption that training examples are **independently identically distributed**, which is often violated in practical problems such as time series prediction.
- A widely used relaxation of the i.i.d. assumption is to assume the observations are drawn from a **mixing process**, where the dependency between observations weakens over time.
- In this paper, we use **algorithmic stability** to study the generalization performance of learning algorithms with  **$\psi$ -mixing data**.

# Stationary Mixing Process

Let  $\mathbf{Z} = \{Z_t\}_{t=-\infty}^{\infty}$  be a stationary sequence of random variables. For any  $i, j \in \mathbb{N}$ , let  $\sigma_i^j$  denote the  $\sigma$ -algebra generated by the random variables  $Z_k, i \leq k \leq j$ .

- ①  **$\varphi$ -Mixing Sequence:** For any  $k \in \mathbb{N}$ , the  $\varphi$ -mixing coefficient of  $\mathbf{Z}$  is defined as

$$\varphi(k) = \sup_{n, A \in \sigma_{n+k}^{\infty}, B \in \sigma_{-\infty}^n} |\Pr(A|B) - \Pr(A)|.$$

$\mathbf{Z}$  is said to be  $\varphi$ -mixing if  $\varphi(k) \rightarrow 0$  as  $k \rightarrow \infty$ .

- ②  **$\psi$ -Mixing Sequence:** For any  $k \in \mathbb{N}$ , the  $\psi$ -mixing coefficient of the stochastic process  $\mathbf{Z}$  is defined as

$$\psi(k) = \sup_{n, A \in \sigma_{n+k}^{\infty}, B \in \sigma_{-\infty}^n} |\Pr(A \cap B) / \Pr(A)\Pr(B) - 1|.$$

$\mathbf{Z}$  is said to be  $\psi$ -mixing if  $\psi(k) \rightarrow 0$  as  $k \rightarrow \infty$ .

- ③  **$\varphi'$ -Mixing Coefficient:** Our stability analysis requires a different mixing coefficient defined as follows

$$\varphi'(k) = \sup_{n, A \in \sigma_{-\infty}^{n-k}, z_n \in \sigma_n^n, B \in \sigma_{n+k}^{\infty}} |\Pr(z_n|A, B) - \Pr(z_n)|.$$

# Definitions

Let  $L, \gamma > 0$  and  $\mu \geq 0$ . Let  $f : \mathcal{W} \times \mathcal{Z} \mapsto \mathbb{R}$ .

**Lipschitzness:** We say  $f$  is  $L$ -Lipschitz continuous if  $|f(\mathbf{w}; z) - f(\mathbf{w}'; z)| \leq L\|\mathbf{w} - \mathbf{w}'\|$  for any  $\mathbf{w}, \mathbf{w}', z$ .

**Smoothness:** We say  $f$  is  $\gamma$ -smooth if  $\|\nabla f(\mathbf{w}; z) - \nabla f(\mathbf{w}'; z)\| \leq \gamma\|\mathbf{w} - \mathbf{w}'\|$  for any  $\mathbf{w}, \mathbf{w}', z$ .

**Convexity:** We say  $f$  is  $\mu$ -strongly convex if for any  $\mathbf{w}, \mathbf{w}', z$  we have  $f(\mathbf{w}; z) - f(\mathbf{w}'; z) - \langle \mathbf{w} - \mathbf{w}', \nabla f(\mathbf{w}'; z) \rangle \geq \frac{\mu}{2}\|\mathbf{w} - \mathbf{w}'\|^2$ . We say  $f$  is convex if it is  $\mu$ -strongly convex with  $\mu = 0$ .

## Algorithmic Stability

Let  $S = \{z_1, \dots, z_n\}, S' = \{z'_1, \dots, z'_n\}$  be independently drawn from sample space.

We say  $A$  is  $\epsilon$ -uniformly stable if for any datasets  $S, \hat{S} \in \mathcal{Z}^n$  that differ by at most a single example we have

$$\sup_z [f(\mathbf{w}_S; z) - f(\mathbf{w}_{\hat{S}}; z)] \leq \epsilon.$$

# Moment Bound For $\varphi$ -Mixing Sequence

## Moment Bound

Let  $X_1, \dots, X_n$  be a finite contiguous subsequence from a  $\varphi$ -mixing sequence. Let  $Z_i$  be a function of  $X_i$  with  $\mathbb{E}[Z_i] = 0$  and  $\Pr\{|Z_i| > \tilde{\epsilon}\} \leq 2 \exp(-\tilde{\epsilon}^2/b)$ . Then for any  $p \geq 1$  we have

$$\left\| \sum_{i=1}^n Z_i \right\|_p \leq (9 + \log(n)) p \Delta_n \sqrt{2nb}.$$

The bound matches the existing moment bounds for i.i.d. random variables up to a logarithmic factor

# Concentration Inequality For $\varphi$ -Mixing Sequence

## Concentration Inequality

Let  $Z_1, \dots, Z_n$  be a finite contiguous subsequence from a  $\varphi$ -mixing sequence. Let  $g_1, \dots, g_n$  be some functions  $g_i : \mathcal{Z}^n \mapsto \mathbb{R}$  such that the following holds for any  $i \in [n]$

- $|\mathbb{E}_{Z_{[n] \setminus [i]}}[g_i(Z)|Z_i]| \leq M$  almost surely,
- $\mathbb{E}_{Z_i}[g_i(Z)|Z_{[n] \setminus [i]}] = 0$  a.s.,
- $g_i$  is  $\beta$ -Lipschitz.

Then for any  $p \geq 1$  we have

$$\left\| \sum_{i=1}^n g_i \right\|_p \leq 3M\Delta_n \sqrt{2pn} + 2^k p\beta \sum_{l=0}^{k-1} (9+l)\Delta_{2^l}^2.$$

- Our bound recovers the existing result in the **i.i.d. case**.
- The concentration inequality is developed for  $\varphi$ -mixing sequence and can be directly applied to  $\psi$ -mixing sequence.

## Error Decomposition

let  $S_{i,b}^i = \{z_1, \dots, z_{i-b-1}, z_i', z_{i+b+1}, \dots, z_{n-b}\}$ . We then define the following random variables

$$g_i = \mathbb{E}_{z_i'} [\mathbb{E}_{z_i''} [f(\mathbf{w}_{S_{i,b}^i}; z_i'')]] - f(\mathbf{w}_{S_{i,b}^i}; z_i), \quad \forall i \in [n].$$

### Error Decomposition

Let  $S$  be drawn from a  $\psi$ -mixing distribution. If the algorithm  $A$  is  $\beta$ -uniformly stable and the loss function is bounded by  $M > 0$ , then

$$|n(F(\mathbf{w}_S) - F_S(\mathbf{w}_S))| \leq 2n(3b+1)\beta + nM(\varphi(b) + \varphi'(b)) + \left| \sum_{i=1}^n g_i \right|.$$

# Stability and Generalization

## General Mixing Stability Bound

Let  $S$  be drawn from a  $\psi$ -mixing distribution. Then for any  $b \in \{0, \dots, n\}$  and any  $\delta \in (0, 1)$ , the following inequality holds with probability at least  $1 - \delta$

$$|F(\mathbf{w}_S) - F_S(\mathbf{w}_S)| = O\left(\varphi'(b) + \Delta_n \sqrt{n^{-1} \log(1/\delta)} + \beta(b + \Delta_n^2 \log^2 n \log(1/\delta))\right).$$

- In the i.i.d. case, stability bound becomes

$$|F(\mathbf{w}_S) - F_S(\mathbf{w}_S)| = O\left(\sqrt{n^{-1} \log(1/\delta)} + \beta \log^2 n \log(1/\delta)\right),$$

which matches existing stability-based bounds up to a logarithmic factor.

- Our stability bound improves on previous state-of-the-art results by a factor of  $O(\sqrt{n})$ .



*Thank you!*