

When Source-Free Domain Adaptation Meets Learning with Noisy Labels

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ICLR'23 - May 2023
Presenter: Gezheng Xu

UDA and SFDA

Unsupervised Domain Adaptation (UDA)

$$D_S = \{(\mathbf{x}_i^S, y_i^S)\}_{i=1}^N + D_T = \{(\mathbf{x}_i^T)\}_{i=1}^M$$

$$\Downarrow$$

$$f_T(\mathbf{x})$$


(a) Clipart: Clipart Images

Source-Free Domain Adaptation (SFDA)

$$D_S = \{(\mathbf{x}_i^S, y_i^S)\}_{i=1}^N$$

$$\Downarrow \text{Source Training}$$

$$f_S(\mathbf{x}) + D_T = \{(\mathbf{x}_i^T)\}_{i=1}^M$$

$$\Downarrow \text{Target Adaptation}$$

$$f_T(\mathbf{x})$$


(b) Real World: Regular Images captured with a Camera

Figure 1: Examples of Office-Home Dataset ¹: $p_S(X, Y) \neq p_T(X, Y)$

¹Source: Venkateswara et al., Deep Hashing Network for Unsupervised Domain Adaptation. CVPR 2017.

Label Noise in SFDA

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$$f_S(\mathbf{x}) + D_T = \{(\mathbf{x}_i^T)\}_{i=1}^M$$

↓ Target Adaptation

$$f_T(\mathbf{x})$$

- **Two-Stage Training process:**
Source Training \Rightarrow Target Adaptation
- **Key Point: Quality of the Pseudo-Labels**
 - Domain Shift \Rightarrow Severe Noise in Pseudo Labels
 - Incorrect Neighborhood/Cluster Information \Rightarrow Noise Accumulation (Fig2)

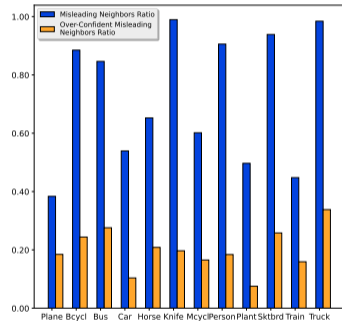


Figure 2: Neighbors Label Noise in SFDA Problem

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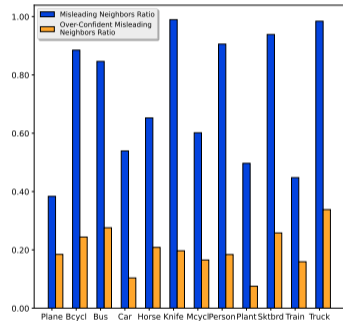


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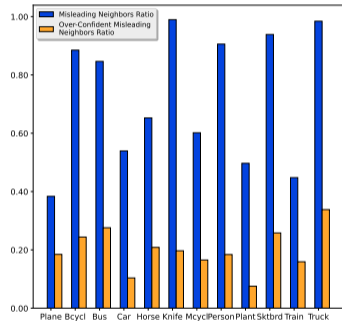


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Incorrectly Assigned Pseudo Labels = Noisy Labels

We propose to **formulate SFDA as a Learning with Label Noise (LLN) problem.**

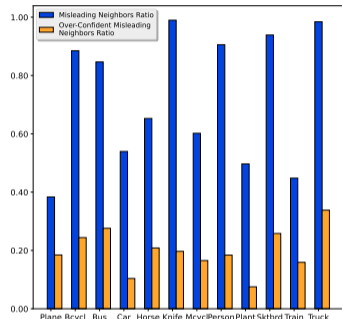


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LLN

Learning with Label Noise (LLN)

- Given a set of **NOISY** training data \bar{S}
 - $\bar{S} = (\mathbf{x}_i, \bar{y}_i)_{i=1}^n$
 - \mathbf{x}_i : input data
 - \bar{y}_i : possibly corrupted label
 - y_i : ground-truth label
- To learn a **Noise-Robust** classifier
⇒ correctly label the new input data.



Figure 3: Example of Learning with Label Noise on Office-Home Dataset. The first row represents the ground-truth label; the second row is the possibly corrupted label.

Current Limitations of LLN methods in SFDA

Different Label Noises in LLN and in SFDA Settings

- Label Noise in **LLN** (Xiao et al., 2015):
 - generated by *human annotators* or *image search engines*
 - mislabeling rate for a sample is **bounded**
 - general LLN methods: **Noise-Robust** Losses
- Label Noise in **SFDA**:
 - generated by the *source model* due to the distribution shift
 - mislabeling rate can be out of control and **unbounded**

TWO **PROBLEMS** for *correctly* applying **LLN approaches** to **SFDA**:

- ① Can general noise-robust LLN methods, based on the *Bounded Noise*, be effective for SFDA problems where the label noise has different properties?
- ② If NOT, what kinds of LLN methods can be helpful?

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Unbounded Label Noise in SFDA

Theoretical Analysis 1 - Unbounded Label Noise in Source Free Domain Adaptation

Definition: Bounded and Unbounded Label Noises

With X as the input feature, Y as the ground-truth label, and \tilde{Y} as the noisy label, we define the **Bounded Label Noise** scenario as:

$$\Pr[\tilde{Y} = i | Y = i, X = \mathbf{x}] > \Pr[\tilde{Y} = j | Y = i, X = \mathbf{x}], \quad \forall \mathbf{x} \in \mathcal{X}, i \neq j$$

, and the **Unbounded Label Noise** scenario as:

$$\Pr[\tilde{Y} = j | Y = i, X = \mathbf{x}] \rightarrow 1, \quad \exists \mathcal{S} \subset \mathcal{X}, \forall \mathbf{x} \in \mathcal{S}, i \neq j$$

- **Bounded**: A sample \mathbf{x} has the highest probability of being in the correct class (i)
- **Unbounded**: Mislabeled rate of a sample \mathbf{x} can be very high.

Existence of Unbounded Label Noise In SFDA (Th 3.1)

Under some mild assumptions, there exists a non-empty region $\mathbf{R} \subset \mathcal{X}$, for $(\mathbf{x}, y) \sim \mathcal{D}_T$, if $\mathbf{x} \in \mathbf{R}$, then

$$\Pr[f_S(\mathbf{x}) \neq y] \geq 1 - \delta,$$

where $\delta \in (0, 1)$ (i.e., $\delta = 0.01$), f_S is the optimal source classifier.

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where $\delta \in (0, 1)$ (i.e., $\delta = 0.01$), f_S is the optimal source classifier.

- **Theorem 3.1:** Due to the **Domain Shift**, **Unbounded Label Noise** exists in SFDA.

Theoretical Analysis 1 - Unbounded Label Noise in Source Free Domain Adaptation

Unsuitable LLN Losses for Unbounded Label Noise (Lemma 3.2)

Given a **bounded noise-robust loss** ℓ_{LLN} and an input sample x , we have:

$$\Pr[f_T^\star(x) \neq \tilde{f}_T^\star(x)] \geq 1 - \delta, \forall x \in \mathbf{R}$$

where f_T^\star and \tilde{f}_T^\star are the global minimizers of $R(f_T)$ and $\tilde{R}(f_T)$, the risks of the function f_T under **clean data** and **unbounded noisy data**, respectively.

- **Lemma 3.2:** many existing **Noise-Robust Loss based LLN methods**, which rely on the Bounded Label Noise assumption, are **NOT** the most suitable solutions for **SFDA**.

TWO **PROBLEMS** for *correctly* applying **LLN approaches** to **SFDA**:

- ① Can general noise-robust LLN methods, based on the *Bounded Noise*, be effective for SFDA problems where the label noise has different properties? \Rightarrow NO
- ② If NOT, what kinds of LLN methods can be helpful?

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Unsuitable LLN Losses for Unbounded Label Noise (Lemma 3.2)

Given a **bounded noise-robust loss** ℓ_{LLN} and an input sample x , we have:

$$\Pr[f_T^*(x) \neq \tilde{f}_T^*(x)] \geq 1 - \delta, \forall x \in \mathbf{R}$$

where f_T^* and \tilde{f}_T^* are the global minimizers of $R(f_T)$ and $\tilde{R}(f_T)$, the risks of the function f_T under **clean data** and **unbounded noisy data**, respectively.

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TWO **PROBLEMS** for *correctly* applying **LLN approaches** to **SFDA**:

- 1 **Can general noise-robust LLN methods, based on the Bounded Noise, be effective for SFDA problems where the label noise has different properties? ⇒ NO**
- 2 If NOT, what kinds of LLN methods can be helpful?

Theoretical Analysis 1 - Unbounded Label Noise in Source Free Domain Adaptation

Unsuitable LLN Losses for Unbounded Label Noise (Lemma 3.2)

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TWO PROBLEMS for *correctly* applying **LLN approaches** to **SFDA**:

- 1 Can general **noise-robust LLN methods**, based on the *Bounded Noise*, be effective for **SFDA** problems where the label noise has different properties? \Rightarrow **NO**
- 2 **If NOT, what kinds of LLN methods can be helpful?**

Early-Time Training Phenomenon in SFDA

Theoretical Analysis 2 - Early-time Training Phenomenon (ETP) exists in Unbounded Label Noise Scenario

ETP - Early-time Training Phenomenon

The **Early-time Training Phenomenon** describes the training dynamics of the classifier that preferentially **fits the clean samples** and therefore has **higher prediction accuracy for mislabeled samples during the early-training stage**. (Liu et al., 2020)

Existence of ETP in SFDA (Th 4.1)

In the **Unbounded Label Noise** scenario, given a set of mislabeled samples, $B = \{(\mathbf{x}, \tilde{y})\}$, and a classifier θ , there exists a proper time T , and a constant c_0 such that for any $0 < \sigma < c_0$, the **prediction accuracy** $\kappa(B; \theta_T)$ can satisfy the following inequality with probability $1 - o_p(1)$:

$$\kappa(B; \theta_T) \geq 1 - \exp\left\{-\frac{1}{200}g(\sigma)^2\right\},$$

where $g(\sigma)$ is a monotone decreasing function with $g(\sigma) \rightarrow \infty$ ($\sigma \rightarrow 0$), and σ is the cluster variance.

⇒ In **SFDA**,

- the **Early Adaptation Phase** is critical;
- the **Early-Time Predictions** for some easily mislabeled data could be **more promising**.

Method

Early Learning Regularization (ELR) Term (Liu et al., 2020)

$$\mathcal{L}_{\text{ELR}}(\theta_t) = \log(1 - \bar{y}_t^\top f(\mathbf{x}; \theta_t))$$

where $f(\mathbf{x}; \theta_t)$ is the probabilistic output for the sample \mathbf{x} , and $\bar{y}_t = \beta \bar{y}_{t-1} + (1 - \beta) f(\mathbf{x}; \theta_t)$ is the moving average prediction for \mathbf{x} .

Final Method Proposed in SFDA

Given *any* SFDA objective function $\mathcal{L}_{\text{SFDA}}$, the overall objective function is given by:

$$\mathcal{L} = \mathcal{L}_{\text{SFDA}} + \lambda \mathcal{L}_{\text{ELR}},$$

Gradient Analysis in SFDA

$$\frac{d\mathcal{L}_{\text{ELR}}(\theta_t)}{df(\mathbf{x}; \theta_t)} = -\frac{\bar{y}_t}{1 - \bar{y}_t^\top f(\mathbf{x}; \theta_t)}$$

- $\mathcal{L}_{\text{ELR}} \downarrow \Rightarrow \left| \frac{d\mathcal{L}_{\text{ELR}}(\theta_t)}{df(\mathbf{x}; \theta_t)} \right| \uparrow \Rightarrow \mathcal{L}_{\text{ELR}}$ dominates param updating
 \Rightarrow Enforce the alignment of $f(\mathbf{x}; \theta_t)$ with \bar{y}_t rather than **noisy labels**

Experimental Results

Observation of Performance Drop

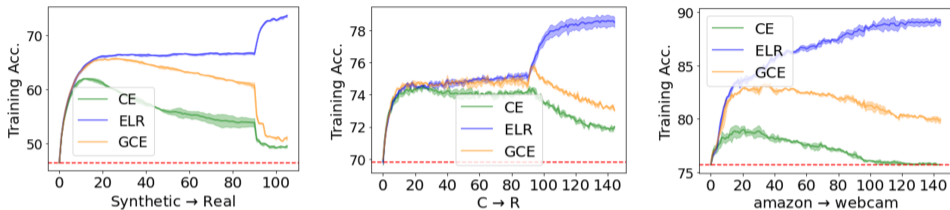


Figure 4: Performance Drop of LLN methods in Adaptation process (VisDA, DomainNet, Office-31)

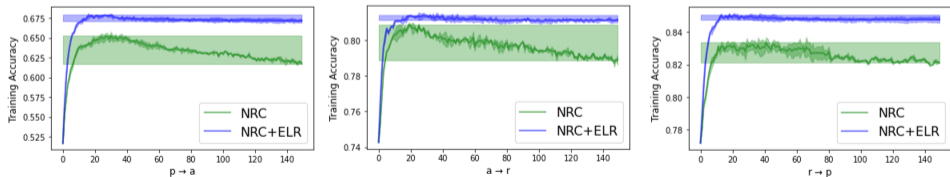


Figure 5: Performance Drop of SFDA methods in Adaptation process (Office-Home)

Main Experimental Results

- Office-Home
- VisDA-2017
- DomainNet

Method	SF	Ar→Cl	Ar→Pr	Ar→Rw	Cl→Ar	Cl→Pr	Cl→Rw	Pr→Ar	Pr→Cl	Pr→Rw	Rw→Ar	Rw→Cl	Rw→Pr	Avg
MCD (Saito et al., 2018b)	✗	48.9	68.3	74.6	61.3	67.6	68.8	57.0	47.1	75.1	69.1	52.2	79.6	64.1
CDAN (Long et al., 2018)	✗	50.7	70.6	76.0	57.6	70.0	70.0	57.4	50.9	77.3	70.9	56.7	81.6	65.8
SAFN (Xu et al., 2019a)	✗	52.0	71.7	76.3	64.2	69.9	71.9	63.7	51.4	77.1	70.9	57.1	81.5	67.3
Symnets (Zhang et al., 2019a)	✗	47.7	72.9	78.5	64.2	71.3	74.2	64.2	48.8	79.5	74.5	52.6	82.7	67.6
MDD (Zhang et al., 2019b)	✗	54.9	73.7	77.8	60.0	71.4	71.8	61.2	53.6	78.1	72.5	60.2	82.3	68.1
TADA (Wang et al., 2019a)	✗	53.1	72.3	77.2	59.1	71.2	72.1	59.7	53.1	78.4	72.4	60.0	82.9	67.6
BNM (Cui et al., 2020)	✗	52.3	73.9	80.0	63.3	72.9	74.9	61.7	49.5	79.7	70.5	53.6	82.2	67.9
BDG (Yang et al., 2020)	✗	51.5	73.4	78.7	65.3	71.5	73.7	65.1	49.7	81.1	74.6	55.1	84.8	68.7
SRDC (Tang et al., 2020)	✗	52.3	76.3	81.0	69.5	76.2	78.0	68.7	53.8	81.7	76.3	57.1	85.0	71.3
RSDA-MSTN (Gu et al., 2020)	✗	53.2	77.7	81.3	66.4	74.0	76.5	67.9	53.0	82.0	75.8	57.8	85.4	70.9
Source Only	✓	44.6	67.3	74.8	52.7	62.7	64.8	53.0	40.6	73.2	65.3	45.4	78.0	60.2
+ELR	✓	<u>52.4</u>	<u>73.5</u>	<u>77.3</u>	<u>62.5</u>	<u>70.6</u>	<u>71.0</u>	<u>61.1</u>	<u>50.8</u>	<u>78.9</u>	<u>71.7</u>	<u>56.7</u>	<u>81.6</u>	<u>67.3</u>
SHOT (Liang et al., 2020)	✓	57.1	78.1	81.5	68.0	78.2	78.1	67.4	54.9	82.2	73.3	58.8	84.3	71.8
+ELR	✓	58.7	78.9	82.1	<u>68.5</u>	<u>79.0</u>	<u>77.5</u>	<u>68.2</u>	<u>57.1</u>	81.9	<u>74.2</u>	<u>59.5</u>	<u>84.9</u>	72.6
G-SFDA (Yang et al., 2021b)	✓	55.8	77.1	80.5	66.4	74.9	77.3	66.5	53.9	80.8	72.4	59.7	83.2	70.7
+ELR	✓	<u>56.4</u>	<u>77.6</u>	<u>81.1</u>	<u>67.1</u>	<u>75.2</u>	<u>77.9</u>	65.9	<u>55.0</u>	<u>81.2</u>	72.1	<u>60.0</u>	<u>83.6</u>	<u>71.1</u>
NRC (Yang et al., 2021a)	✓	56.3	77.6	81.0	65.3	78.3	77.5	64.5	56.0	82.4	70.0	57.1	82.9	70.8
+ELR	✓	<u>58.4</u>	<u>78.7</u>	<u>81.5</u>	<u>69.2</u>	79.5	79.3	66.3	58.0	82.6	<u>73.4</u>	<u>59.8</u>	<u>85.1</u>	72.6

Figure 6: Accuracies (%) on Office-Home for ResNet50-based methods

Main Experimental Results

- Office-Home
- VisDA-2017
- DomainNet

Method	SF	plane	bcycl	bus	car	horse	knife	mcycl	person	plant	sktbrd	train	truck	Per-class
DANN (Ganin et al., 2016)	✗	81.9	77.7	82.8	44.3	81.2	29.5	65.1	28.6	51.9	54.6	82.8	7.8	57.4
DAN (Long et al., 2015)	✗	87.1	63.0	76.5	42.0	90.3	42.9	85.9	53.1	49.7	36.3	85.8	20.7	61.1
ADR (Saito et al., 2018a)	✗	94.2	48.5	84.0	72.9	90.1	74.2	92.6	72.5	80.8	61.8	82.2	28.8	73.5
CDAN (Long et al., 2018)	✗	85.2	66.9	83.0	50.8	84.2	74.9	88.1	74.5	83.4	76.0	81.9	38.0	73.9
SAFN (Xu et al., 2019a)	✗	93.6	61.3	84.1	70.6	94.1	79.0	91.8	79.6	89.9	55.6	89.0	24.4	76.1
SWD (Lee et al., 2019)	✗	90.8	82.5	81.7	70.5	91.7	69.5	86.3	77.5	87.4	63.6	85.6	29.2	76.4
MDD (Zhang et al., 2019b)	✗	-	-	-	-	-	-	-	-	-	-	-	-	74.6
MCC (Jin et al., 2020)	✗	88.7	80.3	80.5	71.5	90.1	93.2	85.0	71.6	89.4	73.8	85.0	36.9	78.8
STAR (Lu et al., 2020)	✗	95.0	84.0	84.6	73.0	91.6	91.8	85.9	78.4	94.4	84.7	87.0	42.2	82.7
RWOT (Xu et al., 2020)	✗	95.1	80.3	83.7	90.0	92.4	68.0	92.5	82.2	87.9	78.4	90.4	68.2	84.0
Source Only	✓	60.9	21.6	50.9	67.6	65.8	6.3	82.2	23.2	57.3	30.6	84.6	8.0	46.6
+ELR	✓	<u>95.4</u>	<u>45.7</u>	<u>89.7</u>	<u>69.8</u>	<u>94.1</u>	<u>97.1</u>	92.9	<u>80.1</u>	<u>89.7</u>	<u>52.8</u>	<u>83.3</u>	<u>4.3</u>	<u>74.6</u>
SHOT (Liang et al., 2020)	✓	94.3	88.5	80.1	57.3	93.1	94.9	80.7	80.3	91.5	89.1	86.3	58.2	82.9
+ELR	✓	<u>95.8</u>	<u>84.1</u>	<u>83.3</u>	<u>67.9</u>	<u>93.9</u>	97.6	<u>89.2</u>	80.1	90.6	<u>90.4</u>	<u>87.2</u>	<u>48.2</u>	<u>84.1</u>
G-SFDA (Yang et al., 2021b)	✓	96.0	87.6	85.3	72.8	95.9	94.7	88.4	79.0	92.7	93.9	87.2	43.7	84.8
+ELR	✓	97.3	<u>89.1</u>	89.8	<u>79.2</u>	96.9	<u>97.5</u>	<u>92.2</u>	82.5	95.8	94.5	<u>87.3</u>	34.5	86.4
NRC (Yang et al., 2021a)	✓	96.9	89.7	84.0	59.8	95.9	96.6	86.5	80.9	92.8	92.6	90.2	60.2	85.4
+ELR	✓	<u>97.1</u>	89.7	<u>82.7</u>	<u>62.0</u>	<u>96.2</u>	<u>97.0</u>	<u>87.6</u>	<u>81.2</u>	<u>93.7</u>	<u>94.1</u>	90.2	58.6	<u>85.8</u>

Figure 6: Accuracies (%) on VisDA-C (Synthesis → Real) for ResNet101-based methods

Main Experimental Results

- Office-Home
- VisDA-2017
- DomainNet

Method		SFR	→CR	→PR	→SC	→RC	→PC	→SP	→RP	→CP	→SS	→RS	→CS	→P	Avg
MCD (Saito et al., 2018b)	✗	61.9	69.3	56.2	79.7	56.6	53.6	83.3	58.3	60.9	81.7	56.2	66.7	65.4	
DANN (Ganin et al., 2016)	✗	63.4	73.6	72.6	86.5	65.7	70.6	86.9	73.2	70.2	85.7	75.2	70.0	74.5	
DAN (Long et al., 2015)	✗	64.3	70.6	58.4	79.4	56.7	60.0	84.5	61.6	62.2	79.7	65.0	62.0	67.0	
COAL (Tan et al., 2020)	✗	73.9	75.4	70.5	89.6	70.0	71.3	89.8	68.0	70.5	88.0	73.2	70.5	75.9	
MDD (Zhang et al., 2019b)	✗	77.6	75.7	74.2	89.5	74.2	75.6	90.2	76.0	74.6	86.7	72.9	73.2	78.4	
Source Only	✓	53.7	71.6	52.9	70.8	49.5	58.3	85.2	59.6	59.1	30.6	74.8	65.7	61.0	
+ELR	✓	<u>70.2</u>	<u>81.7</u>	<u>61.7</u>	<u>79.9</u>	<u>63.8</u>	<u>67.0</u>	<u>90.0</u>	<u>72.1</u>	<u>66.8</u>	<u>85.1</u>	<u>78.5</u>	<u>68.8</u>	<u>73.8</u>	
SHOT (Liang et al., 2020)	✓	73.3	80.1	65.8	91.4	74.3	69.2	91.9	77.0	66.2	87.4	81.3	75.0	77.7	
+ELR	✓	78.0	81.9	<u>67.4</u>	91.1	75.9	<u>71.0</u>	<u>92.6</u>	<u>79.3</u>	<u>68.0</u>	<u>88.7</u>	<u>84.8</u>	<u>77.0</u>	79.7	
G-SFDA (Yang et al., 2021b)	✓	65.8	78.9	60.2	80.5	64.7	64.6	89.3	69.9	63.6	86.4	78.8	71.1	72.8	
+ELR	✓	<u>69.4</u>	<u>80.9</u>	<u>60.6</u>	<u>81.3</u>	<u>67.2</u>	<u>66.4</u>	<u>90.2</u>	<u>73.2</u>	<u>64.9</u>	<u>87.6</u>	<u>82.1</u>	71.0	<u>74.6</u>	
NRC (Yang et al., 2021a)	✓	69.8	81.1	62.9	83.4	74.4	66.3	90.3	73.4	65.2	88.2	82.2	75.8	76.4	
+ELR	✓	<u>75.6</u>	82.2	<u>65.7</u>	<u>91.2</u>	<u>77.2</u>	<u>68.5</u>	92.7	79.8	<u>67.5</u>	89.3	85.1	77.6	<u>79.4</u>	

Figure 6: Accuracies (%) on DomainNet for ResNet50-based methods

Summary

In this work, we

- 1 *Distinguish* Label Noises in **SFDA** from **Traditional LLN Settings**;
- 2 *Justify* the existence of **ETP** in **Unbound Label Noise**;
- 3 *Identify* **effective** LLN methods for **SFDA**;
- 4 *Introduce* the **ELR** term to enhance SFDA performance.

We hope this work can **INSPIRE** more research on

- Exploring the Training Dynamic of Early-Time Adaptation
- and Utilizing the Early-Time Training Phenomenon in Unbounded Label Noise.

Thanks!

Poster Session 4: May 2, 16:30 - 18:30 #144



Project Code