

Adaptive Extra-Gradient Methods for Min-Max Optimization and Games

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joint with

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Problem setup

- ▶ $\mathcal{X} \subset \mathbb{R}^d$ *convex*
- ▶ $A : \mathcal{X} \rightarrow \mathcal{X}^*$ **monotone**:

$$\langle A(x) - A(x') | x - x' \rangle \geq 0 \text{ for all } x, x' \in \mathcal{X}$$

Main goal:

$$\text{Find } x^* \in \mathcal{X} \text{ s.t. } \langle A(x^*) | x - x^* \rangle \geq 0 \text{ for all } x \in \mathcal{X} \quad (\text{VI})$$

Applications: Convex Minimization, Saddle points, Nash equilibria...

Performance Evaluation

Restricted gap function [Auslender, . . .]

$$\text{Gap}_{\mathcal{C}}(x) = \sup_{x' \in \mathcal{C}} \langle A(x') | x - x' \rangle \quad (\text{RGF})$$

for every \mathcal{C} compact neighbourhood x^*

Its zeros characterize the solution of (VI)

Standard regularity conditions

▶ **Boundedness:**

$$\|A(x)\|_* \leq G \text{ for all } x \in \mathcal{X}$$

▶ **Smoothness:**

$$\|A(x) - A(x')\|_* \leq L\|x - x'\|$$

▶ Boundedness:

$$\text{Gap}(X_T) = \mathcal{O}(1/\sqrt{T}) \quad \text{[tight]}$$

▶ Smoothness: Nemirovski [2004], Nesterov [2007]

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▶ **Adaptive:** Bach and Levy [2019]

Best of both worlds!

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examples: Poisson Inverse Problems, D-Optimal Design, Support Vector Machines etc

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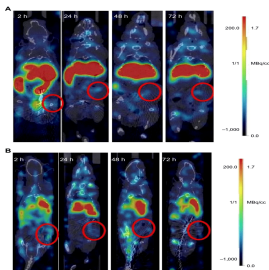
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- ▶ Boundedness of the domain for **adaptive methods**

Inappropriate for problems with unbounded and/or non-compact domains

Why bother?

Various **real-life** problems are not "bounded"!



Positron emission tomography



Portfolio selection



Image denoising

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Design a **adaptive** algorithm that transcends the limitations of SOTA

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Design a **adaptive** algorithm that transcends the limitations of SOTA

Our approach:

- ▶ A broader class to account problems with singularities!
- ▶ A tailor-made Bregman methods to achieve order **optimal** rate interpolation/ domain indifference!

Metric Boundedness and Smoothness

Key observations

- ▶ Lipschitz continuity is a **metric space property**
- ▶ Add geometry awareness via a suitable family of local norms

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- ▶ Add geometry awareness via a suitable family of local norms

- ▶ **Metric Boundedness:** (A, Belmega, Mertikopoulos, ICLR 2020)

$$\|A(x)\|_{x,*} \leq G \quad (\text{MB})$$

- ▶ **Metric Smoothness:** (A, Belmega, Mertikopoulos, NeurIPS 2019)

$$\|A(x) - A(x')\|_{x,*} \leq L\|x - x'\|_{x'} \quad (\text{MS})$$

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AdaProx = Mirror-Prox + Local Norm Twist + Adaptive step-size

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$$\begin{aligned} x_{t+1/2} &= \arg \min_{x \in \mathcal{X}} \left\{ \langle A(X_t) | x - X_t \rangle + \frac{1}{\gamma_t} D_h(x, X_t) \right\} \\ x_{t+1} &= \arg \min_{x \in \mathcal{X}} \left\{ \langle A(X_{t+1/2}) | x - x_t \rangle + \frac{1}{\gamma_t} D_h(x, x_t) \right\} \end{aligned} \quad (\text{MP})$$

Bregman divergence: $D(x', x) = h(x') - h(x) - \langle \nabla h(x), x' - x \rangle$

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Local Norm twist: Take h strongly convex w.r.t. the local norms, i.e.

$$h(x') \geq h(x) + \langle \nabla h(x), x' - x \rangle + \frac{K}{2} \|x - x'\|_x^2$$

Defining the adaptive step-size

Adaptive Step-size:

$$\gamma_t = \frac{1}{\sqrt{1 + \sum_{j=1}^{t-1} \|A(X_j) - A(X_{j+1/2})\|_{X_{j+1/2},*}^2}} \quad (1)$$

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► "Worst Case" (MB)

$$\|A(X_j) - A(X_{j+1/2})\|_{X_{j+1/2},*}^2 \approx \text{"constant"}$$

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► "Best Case" (MS)

$$\|A(X_j) - A(X_{j+1/2})\|_{X_{j+1/2},*}^2 \propto \|X_{j+1/2} - X_j\|_{X_j}$$

which **converges** to 0 if the algorithm converges \rightarrow **Bigger step-size**

Results

Theorem

If $\bar{X}_T = (\sum_{t=1}^T \gamma_t)^{-1} \sum_{t=1}^T \gamma_t X_{t+1/2}$, then:

- ▶ Under (MB), then:

$$\text{Gap}_C(\bar{X}_T) = \mathcal{O}(1/\sqrt{T})$$

- ▶ Under (MS) then:

$$\text{Gap}_C(\bar{X}_T) = \mathcal{O}(1/T)$$

- ▶ Under (MB) or (MS), the iterates of **(AdaProx)** converge to the solution set \mathcal{X}^* :

$$\text{dist}(X_t, \mathcal{X}^*) \rightarrow 0 \quad \text{dist}(X_{t+1/2}, \mathcal{X}^*)$$

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