

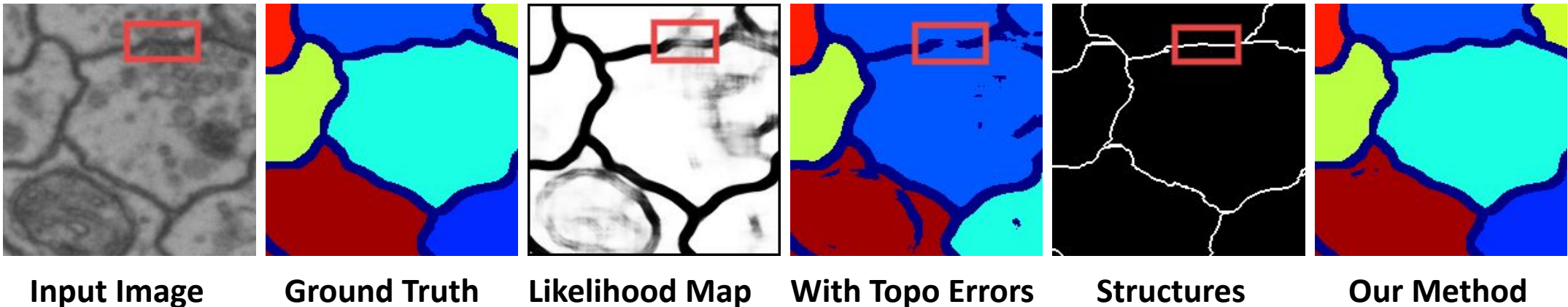
Topology-Aware Segmentation Using Discrete Morse Theory

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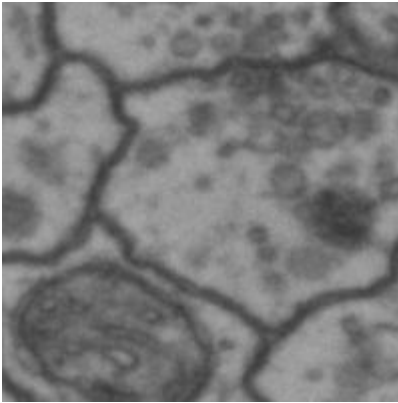
Importance of correct topology for image segmentation

- Existing methods optimize w.r.t. per-pixel accuracy
- Topological errors:
 - broken connection, missing components
- Structural errors damage downstream analysis

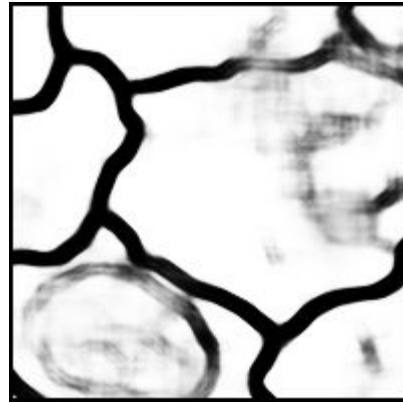


Why Discrete Morse Theory

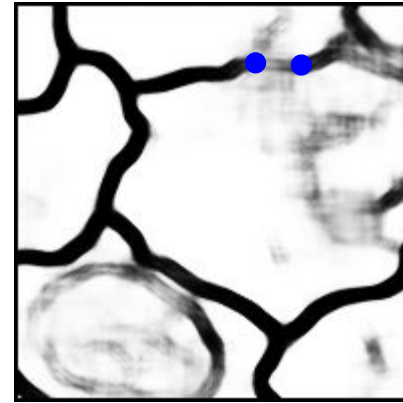
- Fix topological errors with persistent homology:
 - [Hu et al. NeurIPS'19] – Topological loss by matching persistence diagram



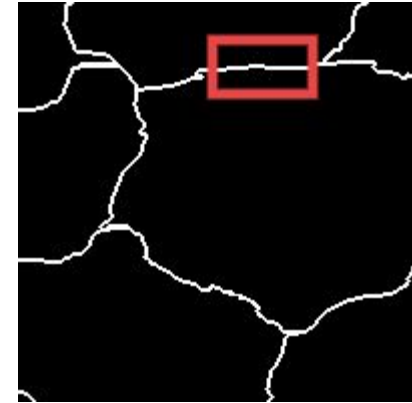
Input Image



Likelihood Map



Critical Points



DMT Structures

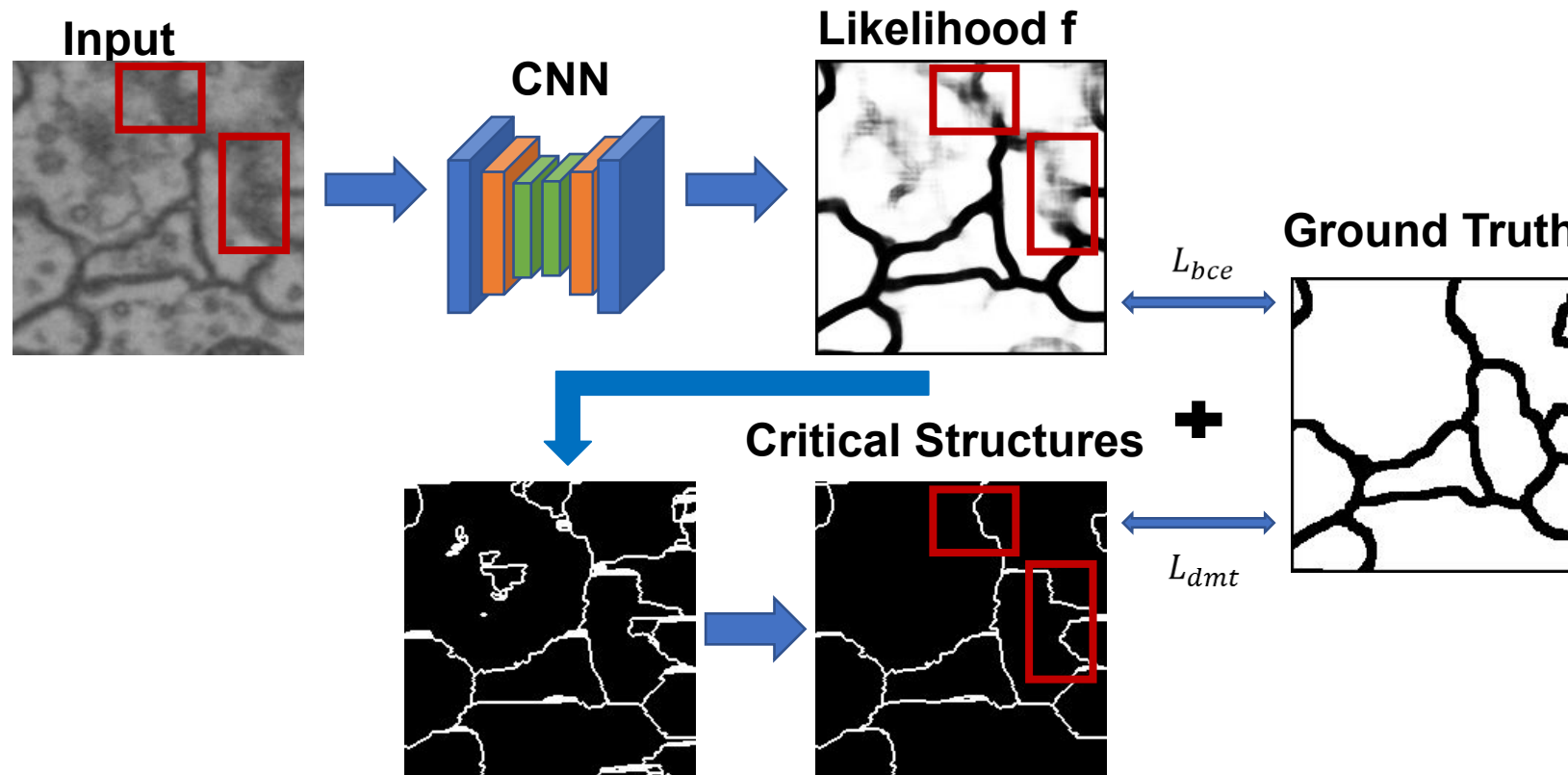
Not efficient enough!

Summary of Contributions

- Our contributions:
 - **DMT loss**: capturing the **critical structures** of the training data
 - DMT-based **loss function** for end-to-end training of neural networks
 - Efficiency: converging faster than topological loss

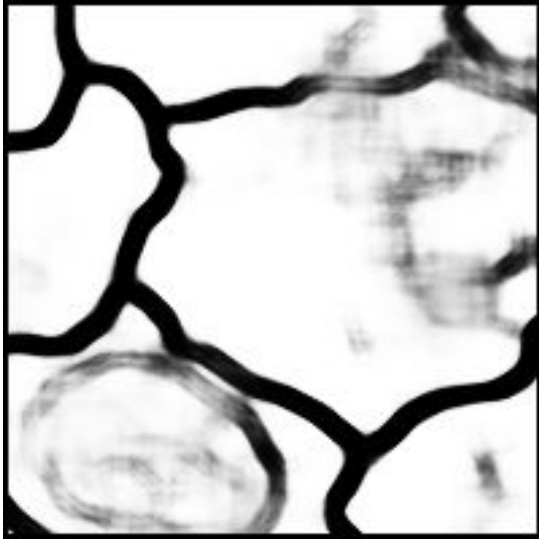
DMT Loss

- loss function – train the model to be topology-preserving
 - Identity the critical structures instead of critical points

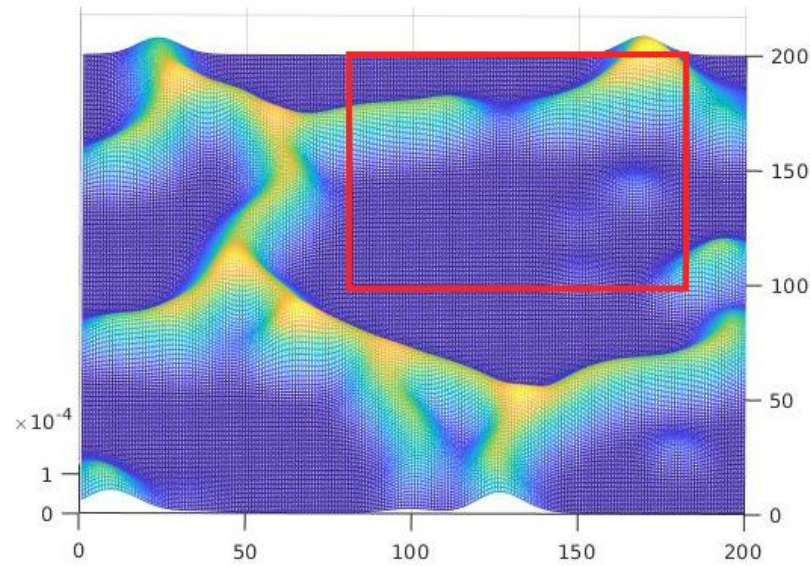


Overview of the proposed method

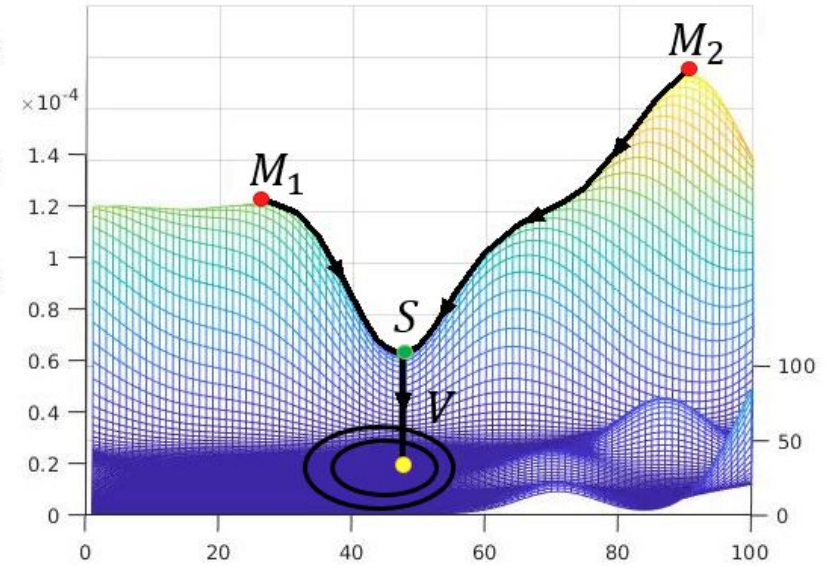
Morse theory



Likelihood Map



Density Map

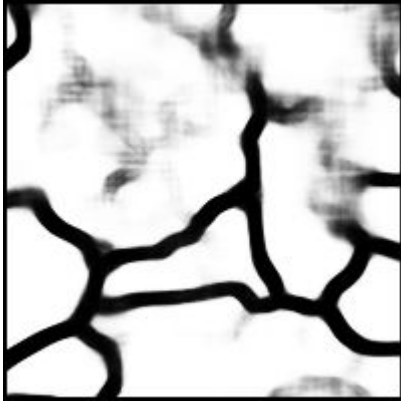


Density Map for highlighted region

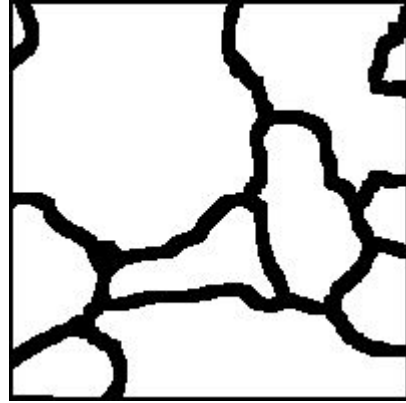
Gradient: $\nabla f(x) = \left[\frac{\partial f}{\partial x_1}, \frac{\partial f}{\partial x_2}, \dots, \frac{\partial f}{\partial x_d} \right]^T$

Critical Points (minimum, maximum, saddle): $\nabla f(x) = 0$

Persistence-based structure pruning



Likelihood Map



Ground Truth



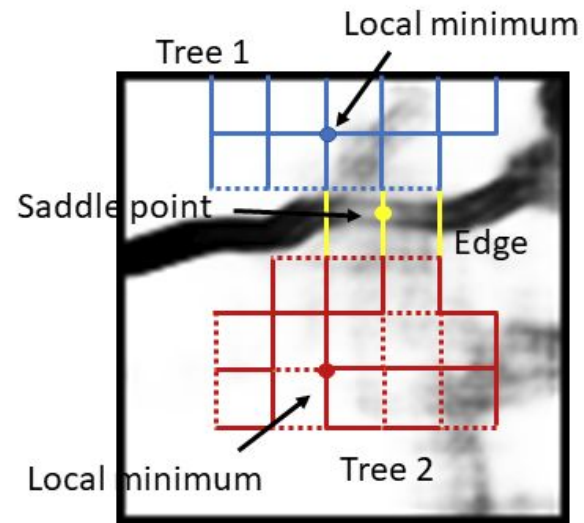
**Improperly pruned
structures**



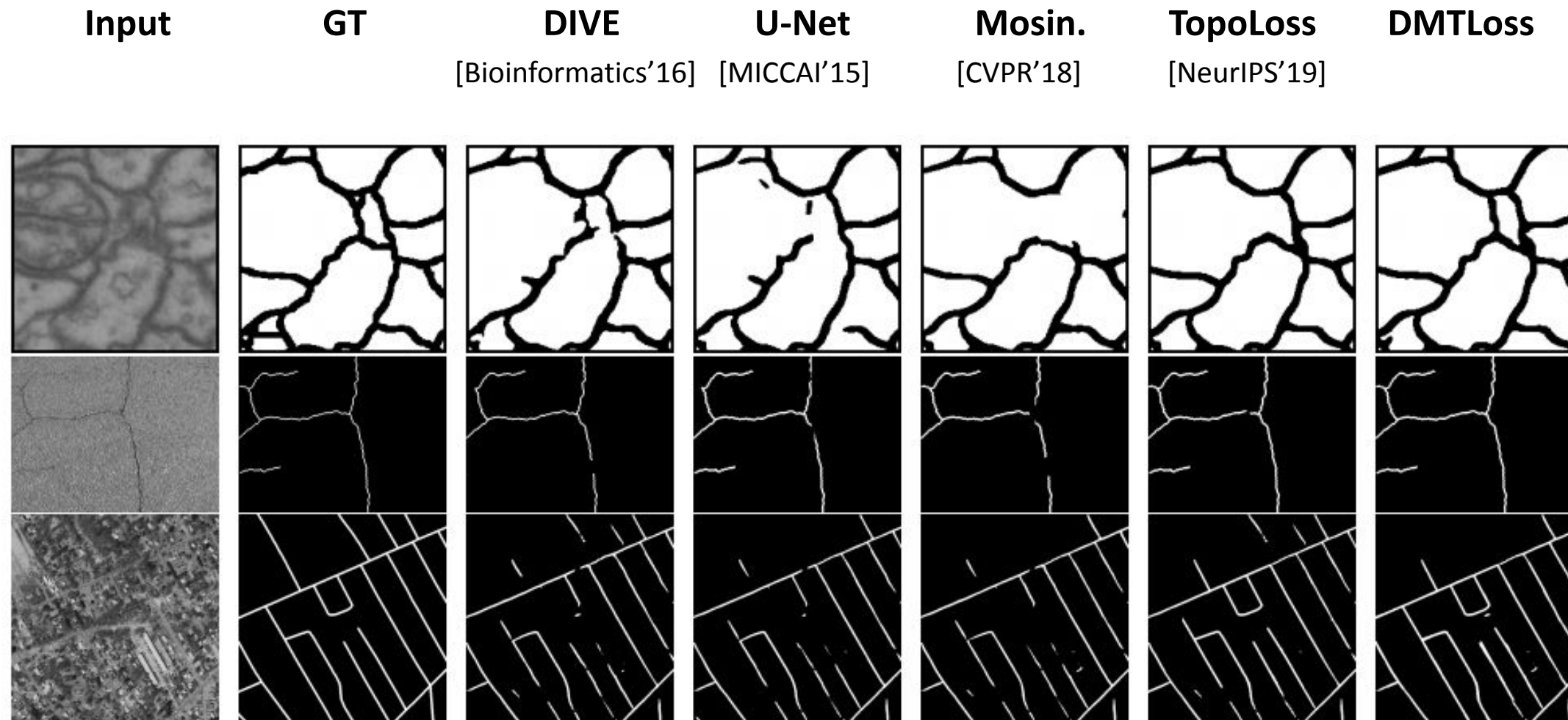
**Properly pruned
structures**

Approximation

Approximate $S_2(\epsilon)$ by $\widehat{S}_2(\epsilon)$ using spanning tree:



Qualitative Results



Quantitative Results for 2D datatest

- Per-pixel error, DICE score, Betti number error, Adjusted Rand Index, Variation of Information

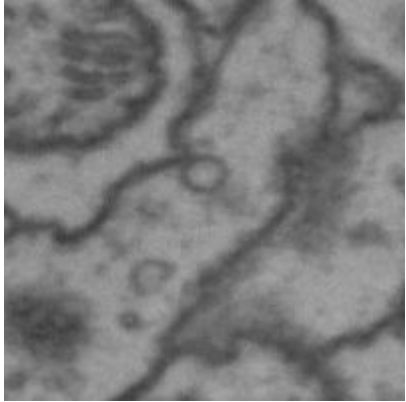
Method	Accuracy	DICE	ARI	VOI	Betti Error
ISBI13					
DIVE	0.9642 \pm 0.0018	0.9658 \pm 0.0020	0.6923 \pm 0.0134	2.790 \pm 0.025	3.875 \pm 0.326
U-Net	0.9631 \pm 0.0024	0.9649 \pm 0.0057	0.7031 \pm 0.0256	2.583 \pm 0.078	3.463 \pm 0.435
Mosin.	0.9578 \pm 0.0029	0.9623 \pm 0.0047	0.7483 \pm 0.0367	1.534 \pm 0.063	2.952 \pm 0.379
TopoLoss	0.9569 \pm 0.0031	0.9689 \pm 0.0026	0.8064 \pm 0.0112	1.436 \pm 0.008	1.253 \pm 0.172
DMT	0.9625 \pm 0.0027	0.9712 \pm 0.0047	0.8289 \pm 0.0189	1.176 \pm 0.052	1.102 \pm 0.203
CREMI					
DIVE	0.9498 \pm 0.0029	0.9542 \pm 0.0037	0.6532 \pm 0.0247	2.513 \pm 0.047	4.378 \pm 0.152
U-Net	0.9468 \pm 0.0048	0.9523 \pm 0.0049	0.6723 \pm 0.0312	2.346 \pm 0.105	3.016 \pm 0.253
Mosin.	0.9467 \pm 0.0058	0.9489 \pm 0.0053	0.7853 \pm 0.0281	1.623 \pm 0.083	1.973 \pm 0.310
TopoLoss	0.9456 \pm 0.0053	0.9596 \pm 0.0029	0.8083 \pm 0.0104	1.462 \pm 0.028	1.113 \pm 0.224
DMT	0.9475 \pm 0.0031	0.9653 \pm 0.0019	0.8203 \pm 0.0147	1.089 \pm 0.061	0.982 \pm 0.179
CrackTree					
DIVE	0.9854 \pm 0.0052	0.6530 \pm 0.0017	0.8634 \pm 0.0376	1.570 \pm 0.078	1.576 \pm 0.287
U-Net	0.9821 \pm 0.0097	0.6491 \pm 0.0029	0.8749 \pm 0.0421	1.625 \pm 0.104	1.785 \pm 0.303
Mosin.	0.9833 \pm 0.0067	0.6527 \pm 0.0010	0.8897 \pm 0.0201	1.113 \pm 0.057	1.045 \pm 0.214
TopoLoss	0.9826 \pm 0.0084	0.6732 \pm 0.0041	0.9291 \pm 0.0123	0.997 \pm 0.011	0.672 \pm 0.176
DMT	0.9842 \pm 0.0041	0.6811 \pm 0.0047	0.9307 \pm 0.0172	0.901 \pm 0.081	0.518 \pm 0.189
Road					
DIVE	0.9734 \pm 0.0077	0.6743 \pm 0.0051	0.8201 \pm 0.0128	2.368 \pm 0.203	3.598 \pm 0.783
U-Net	0.9786 \pm 0.0052	0.6612 \pm 0.0016	0.8189 \pm 0.0097	2.249 \pm 0.175	3.439 \pm 0.621
Mosin.	0.9754 \pm 0.0043	0.6673 \pm 0.0044	0.8456 \pm 0.0174	1.457 \pm 0.096	2.781 \pm 0.237
TopoLoss	0.9728 \pm 0.0063	0.6903 \pm 0.0038	0.8671 \pm 0.0068	1.234 \pm 0.037	1.275 \pm 0.192
DMT	0.9744 \pm 0.0049	0.7056 \pm 0.0022	0.8819 \pm 0.0104	1.092 \pm 0.129	0.995 \pm 0.301

Quantitative Results for 3D datatest

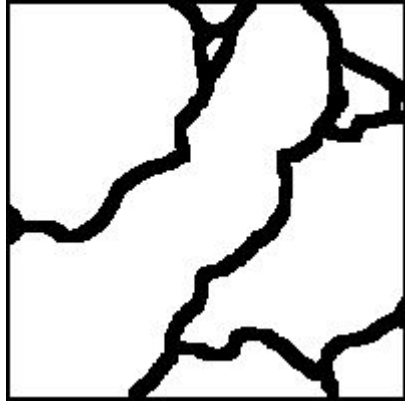
- Per-pixel error, DICE score, Betti number error, Adjusted Rand Index, Variation of Information

Method	Accuracy	DICE	ARI	VOI	Betti Error
ISBI13					
3D DIVE	0.9723 \pm 0.0021	0.9681 \pm 0.0043	0.8719 \pm 0.0189	1.208 \pm 0.149	2.375 \pm 0.419
3D U-Net	0.9746 \pm 0.0025	0.9701 \pm 0.0012	0.8956 \pm 0.0391	1.123 \pm 0.091	1.954 \pm 0.585
MALA	0.9701 \pm 0.0018	0.9699 \pm 0.0013	0.8945 \pm 0.0481	0.901 \pm 0.106	1.103 \pm 0.207
3D TopoLoss	0.9689 \pm 0.0031	0.9752 \pm 0.0045	0.9043 \pm 0.0283	0.792 \pm 0.086	0.972 \pm 0.245
DMT	0.9701 \pm 0.0026	0.9803 \pm 0.0019	0.9149 \pm 0.0217	0.634 \pm 0.086	0.812 \pm 0.134
CREMI					
3D DIVE	0.9503 \pm 0.0061	0.9641 \pm 0.0011	0.8514 \pm 0.0387	1.219 \pm 0.103	2.674 \pm 0.473
3D U-Net	0.9547 \pm 0.0038	0.9618 \pm 0.0026	0.8322 \pm 0.0315	1.416 \pm 0.097	2.313 \pm 0.501
MALA	0.9472 \pm 0.0027	0.9583 \pm 0.0023	0.8713 \pm 0.0286	1.109 \pm 0.093	1.114 \pm 0.309
3D TopoLoss	0.9523 \pm 0.0043	0.9672 \pm 0.0010	0.8726 \pm 0.0194	1.044 \pm 0.128	1.076 \pm 0.206
DMT	0.9529 \pm 0.0031	0.9731 \pm 0.0045	0.9013 \pm 0.0202	0.891 \pm 0.099	0.726 \pm 0.187
3Dircadb					
3D DIVE	0.9618 \pm 0.0054	0.6097 \pm 0.0034	/	/	4.571 \pm 0.505
3D U-Net	0.9632 \pm 0.0009	0.5898 \pm 0.0025	/	/	4.131 \pm 0.483
MALA	0.9546 \pm 0.0033	0.5719 \pm 0.0043	/	/	2.982 \pm 0.105
3D TopoLoss	0.9561 \pm 0.0019	0.6138 \pm 0.0029	/	/	2.245 \pm 0.255
DMT	0.9587 \pm 0.0023	0.6257 \pm 0.0021	/	/	1.415 \pm 0.305

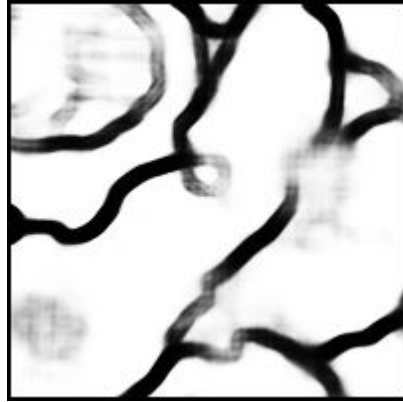
Comparison with reweighted cross entropy loss



Input Image



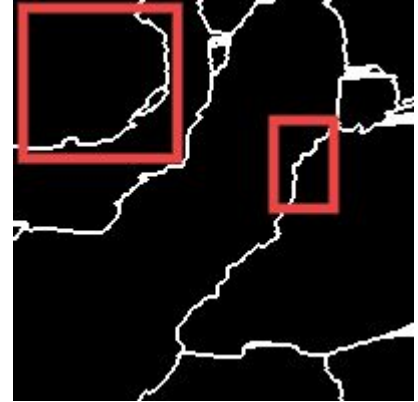
Ground Truth



Likelihood map



Pixels identified by
reweighted CE



Highlighted
Structures by DMT

Method	Accuracy	Betti Error
DMT	0.9475	0.982
Reweighted CE	0.9481	2.753

Conclusions

- DMT loss identifies critical structures that are relevant to image topology and fixes them once at a time.
- Could be incorporated into any segmentation backbones to train the model to be topology-preserving.
- Works for both 2D and 3D images with rich structures.

Thank you for your attention!

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