

Robust Learning of Fixed-Structure Bayesian Network in Nearly-Linear Time

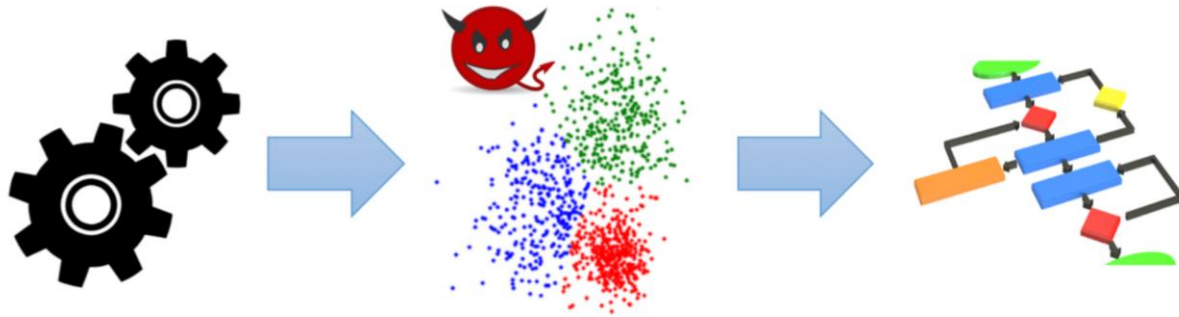
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Robust Parameter Estimation



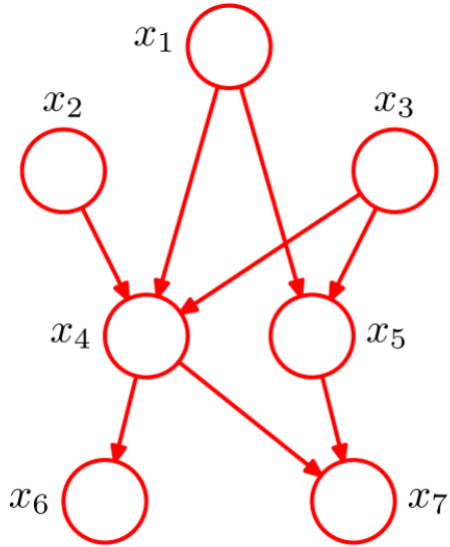
(Unknown) Parameters

Corrupted samples

Algorithms

Q: Can we design provably robust and efficient learning algorithms when a small fraction of the data is corrupted?

Bayesian Network



A Bayesian Network is a d -dimensional distribution supported on $\{0, 1\}^d$, where $\Pr[x_i = 1 \mid x_1, \dots, x_{i-1}]$ depends only on the values x_j where j is a parent of i .

Input: N samples $\{X_1, \dots, X_N\}$ drawn from a Bayesian Network P on \mathbb{R}^d .

Goal: Learn a Bayesian Network Q such that $d_{TV}(P, Q)$ is small.

Corruption Model

- N samples are drawn from an unknown distribution P .
- Adversary replaces ϵN samples with arbitrary points (after inspecting P , the samples, and the algorithm).



- Stronger than Huber's contamination model.
 - Adaptive, and allows both additive and subtractive errors

Corruption Model

- Consider the simplest case: P is a binary product distribution with all $p_i = \frac{1}{2}$.
- The binary product distribution is a Bayesian Network with an empty dependence graph.
- Under the ϵ -corruption model, the empirical estimator may output a Q such that $\|p - q\|_2 = \epsilon\sqrt{d}$, where the error is dependent with the dimension d .

Previous Result

	$d_{TV}(P, Q)(\delta)$	# of Samples (N)	Runtime
Filter[CDKS18]	$O(\epsilon\sqrt{\log(1/\epsilon)})$	$\tilde{O}(m/\delta^2)$	$\tilde{O}(Nd^2/\epsilon)$

- $m = \sum_i 2^{|\text{parent}(i)|}$ is the size of the conditional probability table.
- Under the assumption: P is c -balanced ($p_i \in [c, 1 - c]$), the minimum probability of parental configuration of $P \geq \alpha$, where c and α are constants.
- The error and sample complexity are optimal up to polylog factor.

Question: Can we design a robust algorithm for learning Bayesian networks in the fixed structure setting that runs in nearly-linear time?

Our Result

	$d_{\text{TV}}(P, Q)(\delta)$	# of Samples (N)	Runtime
Filter[CDKS18]	$O(\epsilon\sqrt{\log(1/\epsilon)})$	$\tilde{O}(m/\delta^2)$	$\tilde{O}(Nd^2/\epsilon)$
Our Result	$O(\epsilon\sqrt{\log(1/\epsilon)})$	$\tilde{O}(m/\delta^2)$	$\tilde{O}(Nd)$

- We give the first nearly-linear time algorithm for this problem with a dimension-independent error guarantee (Under the same assumption of α and c).
- We show that robust learning of Bayes nets can be essentially reduced to robust mean estimation, and as a result, this allows us to take advantage of the recent (and future) advances in robust mean estimation.

Overview of Our Approach

- We map each sample $X \in \mathbb{R}^d$ to some $f(X, q) \in \mathbb{R}^m$, where q is our current estimation of the conditional probability table.
- If we learn a good estimation u of the mean of $f(X, q)$ to good accuracy, we can use u to recover p .
- We show that the second moment of this distribution depends on its first moment in a way that allow us to use robust mean estimation algorithm on $f(X, q)$.

Overview of Our Approach

- In each iteration round, we run the robust mean estimation algorithm on $f(X, q)$, then use the output to recover a new estimation of q for the next round.
- We show in each round we can achieve a small error or reduce the error by a constant factor.

Overview of Our Approach

- We give a robust mean estimation algorithm that runs in time nearly linear in the total number of nonzero entries in the input, based on the algorithm in [DHL19].
- The reason we need it: if we naively run the robust mean estimation algorithm on $f(X, q)$. The runtime will be $\tilde{O}(Nm)$, where m can be $\exp(d)$. But notice that $f(X, q)$ is d -sparse.
- The main computation bottleneck of [DHL19] is the matrix multiplicative weights update using JL Lemma, which we show can be done in nearly input-sparsity time.

Open Question

1. Remove the assumption of the balance condition and minimum probability of parental configuration.
2. Robustly Learning Bayes Nets when the graph structure is unknown.