

PiCO: Contrastive Label Disambiguation for Partial Label Learning

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Motivation

Label Ambiguity in Annotation



A dog image x_i with
 $Y_i = \{\text{Husky}, \text{Malamute}, \text{Samoyed}\}$

Q: What the dog it is?

A: Siberian Husky?

Emm... Malamute?

Annotation difficulty:

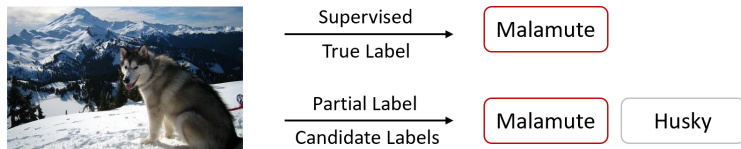
data annotation in the real-world can naturally be subject to inherent label ambiguity and noise.

Solution:

- **Aggressive:**
random selection, but introduce label noise
- **Passive:**
leave it being unlabeled, but ignore the fact that some labels are more likely to be true

Motivation

Partial Label Learning



- **Partial Label Learning (PLL)** [CST11]

- Each training example is equipped with a set of candidate labels instead of the exact ground-truth label.

- **A Non-trivial Dilemma of PLL**

- **Representation Learning:** The inherent label uncertainty can undesirably manifest in the representation learning process
- **Classifier Training:** The quality of representation prevents effective label disambiguation

PiCO

An Overview of Main Contributions

- **Methodology:** A synergistic PLL framework that leverages contrastive learning for enhanced representation and improved label disambiguation
- **Experiments:** Establishes the *SOTA* performance on PLL
- **Theory:** We interpret PiCO from the EM-algorithm perspective

- **Input:** training dataset $\mathcal{D} = \{(\mathbf{x}_i, Y_i)\}_{i=1}^n$
 - an image $\mathbf{x}_i \in \mathcal{X}$
 - a *candidate label set* $Y_i \subset \mathcal{Y} = \{1, 2, \dots, C\}$
 - (**assumption**) Y_i contains the true label y_i , i.e., $y_i \in Y_i$
- **Training:** learning with label disambiguation
 - each image \mathbf{x}_i is assigned a pseudo target $\mathbf{s}_i \in [0, 1]^C$
 - per-sample loss:

$$\mathcal{L}_{\text{cls}}(f; \mathbf{x}_i, Y_i) = \sum_{j=1}^C -s_{i,j} \log(f^j(\mathbf{x}_i))$$

s.t. $\sum_{j \in Y_i} s_{i,j} = 1$ and $s_{i,j} = 0, \forall j \notin Y_i,$

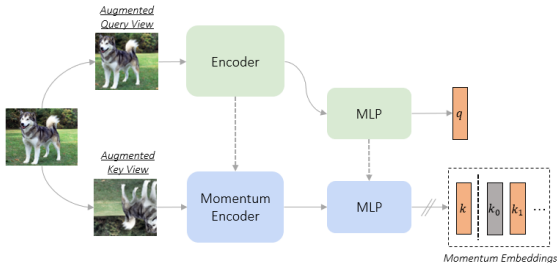
- **Output:** a predictor $f : \mathcal{X} \rightarrow [0, 1]^C$

- **MoCo-style [HFW⁺20] Backbone**

- Given each sample (\mathbf{x}, Y) , a query view and a key view are generated by randomized data augmentation $\text{Aug}(\mathbf{x})$.

- **Embedding Pool Generation**

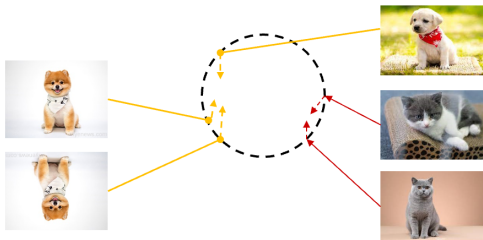
- Get a pair of normalized embeddings $\mathbf{q} = g(\text{Aug}_q(\mathbf{x}))$ and $\mathbf{k} = g'(\text{Aug}_k(\mathbf{x}))$.
- Generate an embedding pool: $A = B_q \cup B_k \cup \text{queue}$



- **Contrastive learning helps representation learning**
 - Pulls examples from the same class close together
 - Push away examples from different classes
- **Per-Sample Contrastive Loss**

$$\mathcal{L}_{\text{cont}}(g; \mathbf{x}, \tau, A) = -\frac{1}{|P(\mathbf{x})|} \sum_{\mathbf{k}_+ \in P(\mathbf{x})} \log \frac{\exp(\mathbf{q}^\top \mathbf{k}_+ / \tau)}{\sum_{\mathbf{k}' \in A(\mathbf{x})} \exp(\mathbf{q}^\top \mathbf{k}' / \tau)},$$

- **Challenge:** how to construct the positive set $P(\mathbf{x})$.



- **Positive Set Selection**

- Use the predicted label $\tilde{y} = \arg \max_{j \in Y} f^j(\text{Aug}_q(\mathbf{x}))$ from the classifier

$$P(\mathbf{x}) = \{\mathbf{k}' | \mathbf{k}' \in A(\mathbf{x}), \tilde{y}' = \tilde{y}\}$$

- Simple but effective; can be theoretically justified (Section 5)

- **The Overall Loss**

- Jointly train the classifier as well as the contrastive network

$$\mathcal{L} = \mathcal{L}_{\text{cls}} + \lambda \mathcal{L}_{\text{cont}}.$$

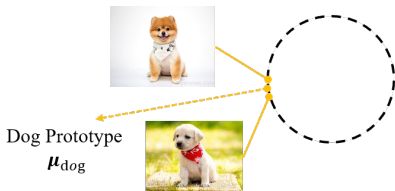
- The label ambiguity remains unsolved

- **Prototype-based Disambiguation**

- Keep a *prototype* embedding vector μ_c corresponding to each class $c \in \{1, 2, \dots, C\}$ as representative embedding vectors
- If an example is close to the j -th prototype, it also tends to have the j -th label as the ground-truth

- **Pseudo Target Updating by Moving-Average**

$$\mathbf{s} = \phi \mathbf{s} + (1 - \phi) \mathbf{z}, \quad z_c = \begin{cases} 1 & \text{if } c = \arg \max_{j \in Y} \mathbf{q}^\top \mu_j, \\ 0 & \text{else} \end{cases}$$



Candidate	dog	cat
Pseudo	0.65	0.35
Prototype	1	0
Updating	↑	↓

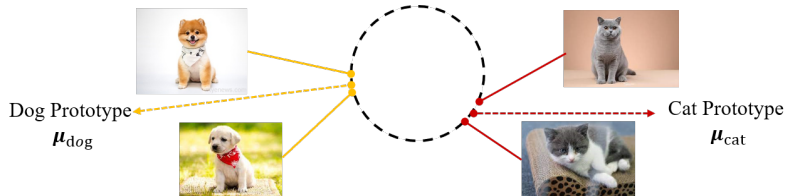


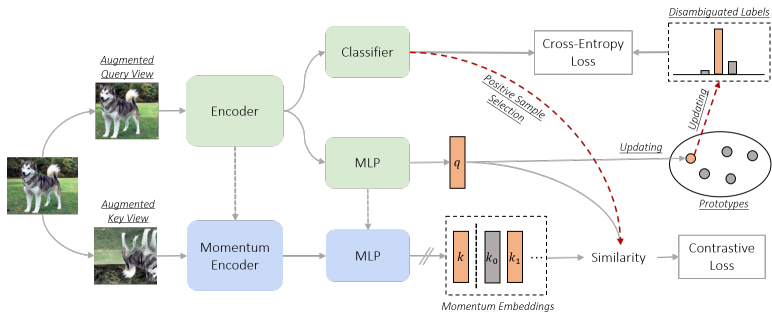
- Efficient Prototype Updating

- Momentum-updating the class prototype vectors

$$\mu_c = \text{Normalize}(\gamma \mu_c + (1 - \gamma) \mathbf{q}),$$

if $c = \arg \max_{j \in Y} f^j(\text{Aug}_q(\mathbf{x}))$,





- Synergy between Contrastive Learning and Label Disambiguation
 - The clustering effect of CL benefits label disambiguation
 - Better label disambiguation reciprocates the CL part by accurate positive set construction

Experiments

Main Results

- PiCO achieves comparable results to the fully supervised learning with less label ambiguity

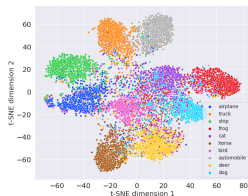
Table 1: Accuracy comparisons on benchmark datasets. Bold indicates superior results. Notably, PiCO achieves comparable results to the fully supervised learning (less than 1% in accuracy with ≈ 1 false candidate).

Dataset	Method	$q = 0.1$	$q = 0.3$	$q = 0.5$
CIFAR-10	PiCO (ours)	94.39 \pm 0.18%	94.18 \pm 0.12%	93.58 \pm 0.06%
	LWS	90.30 \pm 0.60%	88.99 \pm 1.43%	86.16 \pm 0.85%
	PRODEN	90.24 \pm 0.32%	89.38 \pm 0.31%	87.78 \pm 0.07%
	CC	82.30 \pm 0.21%	79.08 \pm 0.07%	74.05 \pm 0.35%
	MSE	79.97 \pm 0.45%	75.64 \pm 0.28%	67.09 \pm 0.66%
	EXP	79.23 \pm 0.10%	75.79 \pm 0.21%	70.34 \pm 1.32%
	Fully Supervised		94.91 \pm 0.07%	
Dataset	Method	$q = 0.01$	$q = 0.05$	$q = 0.1$
CIFAR-100	PiCO (ours)	73.09 \pm 0.34%	72.74 \pm 0.30%	69.91 \pm 0.24%
	LWS	65.78 \pm 0.02%	59.56 \pm 0.33%	53.53 \pm 0.08%
	PRODEN	62.60 \pm 0.02%	60.73 \pm 0.03%	56.80 \pm 0.29%
	CC	49.76 \pm 0.45%	47.62 \pm 0.08%	35.72 \pm 0.47%
	MSE	49.17 \pm 0.05%	46.02 \pm 1.82%	43.81 \pm 0.49%
	EXP	44.45 \pm 1.50%	41.05 \pm 1.40%	29.27 \pm 2.81%
	Fully Supervised		73.56 \pm 0.10%	

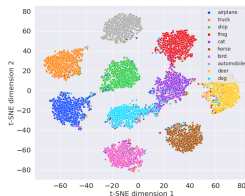
Experiments

Representation Visualization

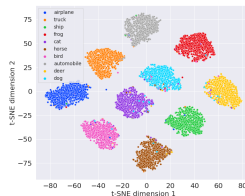
- PiCO learns more distinguishable representations



(a) Uniform features



(b) PRODEN features



(c) PiCO features (ours)

Experiments

Ablation Results

- Each component plays a vital role in PiCO

Table 2: Ablation study on CIFAR-10 with $q = 0.5$ and CIFAR-100 with $q = 0.05$.

Ablation	$\mathcal{L}_{\text{cont}}$	Label Disambiguation	CIFAR-10 ($q = 0.5$)	CIFAR-100 ($q = 0.05$)
PiCO	✓	Ours	93.58	72.74
PiCO w/o Disambiguation	✓	Uniform Pseudo Target	84.50	64.11
PiCO w/o $\mathcal{L}_{\text{cont}}$	✗	Uniform Pseudo Target	76.46	56.87
PiCO with $\phi = 0$	✓	Soft Prototype Probs	91.60	71.07
PiCO with $\phi = 0$	✓	One-hot Prototype	91.41	70.10
PiCO	✓	MA Soft Prototype Probs	81.67	63.75

Theoretical Analysis

Why PiCO improves partial label learning?

- **The Clustering Effect of Contrastive Learning**

- CL Loss decomposing: (a) alignment; (b) uniformity [W120]

$$\tilde{\mathcal{L}}_{\text{cont}}(g; \tau, \mathcal{D}) = \underbrace{\frac{1}{n} \sum_{\mathbf{x} \in \mathcal{D}} \left\{ -\frac{1}{|P(\mathbf{x})|} \sum_{\mathbf{k}_+ \in P(\mathbf{x})} (\mathbf{q}^\top \mathbf{k}_+ / \tau) \right\}}_{(a)} + \underbrace{\frac{1}{n} \sum_{\mathbf{x} \in \mathcal{D}} \left\{ \log \sum_{\mathbf{k}' \in A(\mathbf{x})} \exp(\mathbf{q}^\top \mathbf{k}' / \tau) \right\}}_{(b)}.$$

- Split the dataset to C subsets $S_j \in \mathcal{D}_C$ having the same prediction

$$(a) \approx \frac{1}{\tau n} \sum_{S_j \in \mathcal{D}_C} \sum_{\mathbf{x} \in S_j} \|g(\mathbf{x}) - \boldsymbol{\mu}_j\|^2 + K,$$

- K is a constant and $\boldsymbol{\mu}_j$ is the mean center of S_j

Theoretical Analysis

Why PiCO improves partial label learning?

Assumption 1

All labels y_i in the candidate label set have the same probability of generating Y_i , but no label outside of Y_i can generate Y_i , i.e. $P(Y_i|y_i) = \tilde{h}(Y_i)$ if $y_i \in Y_i$ else 0. Here $\tilde{h}(\cdot)$ is some function making it a valid probability distribution.

• Likelihood Maximization

- Establish the relationship between the candidate and the ground-truth label by the above assumption

$$\operatorname{argmax}_{\theta} \sum_{i=1}^n \log P(Y_i, \mathbf{x}_i | \theta) = \operatorname{argmax}_{\theta} \sum_{i=1}^n \log \sum_{y_i \in Y_i} P(\mathbf{x}_i, y_i | \theta) + \sum_{i=1}^n \log(\tilde{h}(Y_i))$$

Theoretical Analysis

Why PiCO improves partial label learning?

- **An Expectation-Maximization Perspective (E-Step)**

- Define some auxiliary distributions $\pi_i^j \geq 0$ ($1 \leq i \leq n, 1 \leq j \leq C$) such that $\pi_i^j = 0$ if $j \notin Y_i$ and $\sum_{j \in Y_i} \pi_i^j = 1$

$$\operatorname{argmax}_{\theta} \sum_{i=1}^n \log P(Y_i, \mathbf{x}_i | \theta) \geq \operatorname{argmax}_{\theta} \sum_{i=1}^n \sum_{y_i \in Y_i} \pi_i^{y_i} \log \frac{P(\mathbf{x}_i, y_i | \theta)}{\pi_i^{y_i}}.$$

- The condition that inequality holds with equality is,

$$\pi_i^{y_i} = \frac{P(\mathbf{x}_i, y_i | \theta)}{\sum_{y_i \in Y_i} P(\mathbf{x}_i, y_i | \theta)} = \frac{P(\mathbf{x}_i, y_i | \theta)}{P(\mathbf{x}_i | \theta)} = P(y_i | \mathbf{x}_i, \theta), \quad (1)$$

- $\pi_i^{y_i}$ is the posterior class probability

- **The Corresponding Component in PiCO**

- Positive set selection by using classifier's output

Theoretical Analysis

Why PiCO improves partial label learning?

Theorem 1

Assume data from the same class in the contrastive output space follow a d -variate von Mises-Fisher (vMF) distribution whose probabilistic density is given by $f(\mathbf{x}|\bar{\boldsymbol{\mu}}_i, \kappa) = c_d(\kappa)e^{\kappa\bar{\boldsymbol{\mu}}_i^\top \mathbf{g}(\mathbf{x})}$, where $\bar{\boldsymbol{\mu}}_i = \boldsymbol{\mu}_i/\|\boldsymbol{\mu}_i\|$ is the mean direction, κ is the concentration parameter, and $c_d(\kappa)$ is the normalization factor. We further assume a uniform class prior $P(y_i = j) = 1/C$. Let $n_j = |S_j|$. Then, optimizing Eq. (9) and Eq. (10) equal to maximize R_1 and R_2 below, respectively.

$$R_1 = \sum_{S_j \in \mathcal{D}_C} \frac{n_j}{n} \|\boldsymbol{\mu}_j\|^2 \leq \sum_{S_j \in \mathcal{D}_C} \frac{n_j}{n} \|\boldsymbol{\mu}_j\| = R_2. \quad (2)$$

• An Expectation-Maximization Perspective (M-Step)

- Minimizing contrastive loss (alignment term) also maximizes a lower bound of likelihood (Theorem 1)

Summary

Why PiCO improves partial label learning?

- We propose PiCO, a coherent and synergistic framework that pioneers the exploration of contrastive learning for partial label learning.
- PiCO achieves SOTA performance on common PLL benchmarks as well as new fine-grained classification tasks.
- Theoretical analysis shows that PiCO can be interpreted from an EM-algorithm perspective. In particular, we show contrastive learning manifests a clustering effect in the embedding space, and is beneficial for weakly-supervised learning.

References I

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- [WI20] Tongzhou Wang and Phillip Isola, *Understanding contrastive representation learning through alignment and uniformity on the hypersphere*, ICML, Proceedings of Machine Learning Research, vol. 119, PMLR, 2020, pp. 9929–9939.