

# Value Function Spaces

## Skill-Centric State Abstractions for Long-Horizon Reasoning

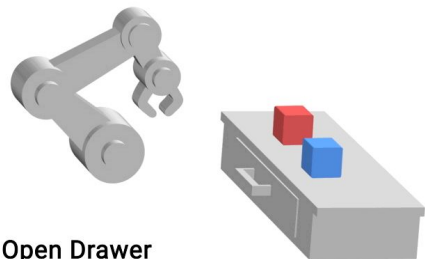
Dhruv Shah 🐻, Peng Xu, Yao Lu, Ted Xiao,  
Alexander Toshev, Sergey Levine 🐻, Brian Ichter

International Conference on Learning  
Representations (ICLR), 2022

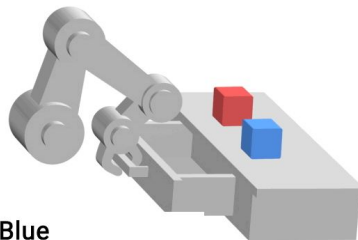
Google Research

🐻 also at UC Berkeley

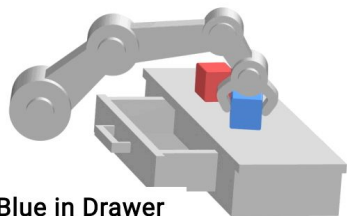
# Motivation



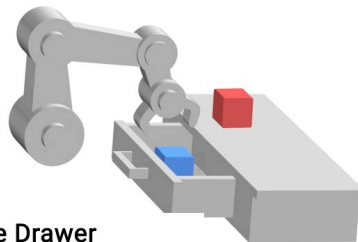
Open Drawer



Pick Blue



Place Blue in Drawer



Close Drawer

# Motivation

- Performing such tasks in real-world situations is challenging
  - Reasoning over long horizons
  - Parse high-dimensional observations
- How do we get state and action abstractions?
  - State abstraction should depend on the capabilities of the lower-level skills

# From Affordances to Skill Value Functions

- The notion of “values” in RL is closely related to affordances
  - Example, for sparse terminal reward:  $V(s) = E(\gamma^T r(s))$
  - In general, value denotes the probability of success
- For any policy (or skill), its value function captures:
  - *preconditions* or *affordances* of the scene, i.e. where the skill can be used
  - *outcome*, i.e. did the skill execute successfully
- Given a finite set of skills, define a representation  $Z(s_t)$  by stacking the corresponding skill value functions  $Z(s_t) = [V_1(s_t), V_2(s_t), \dots, V_k(s_t)]$

# A Toy Example

“Place Blue in Drawer”



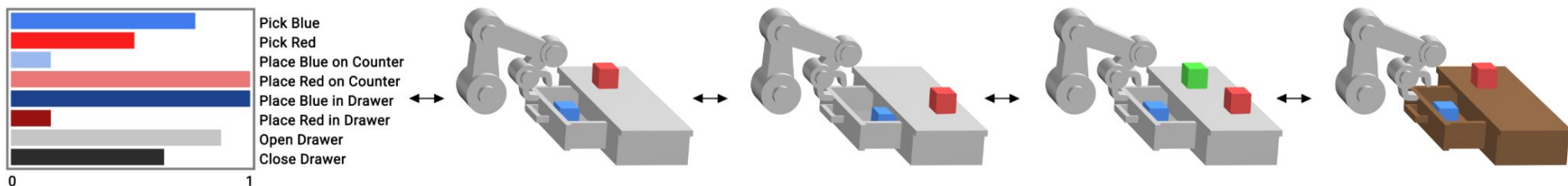
# A Toy Example

“Place Blue in Drawer”



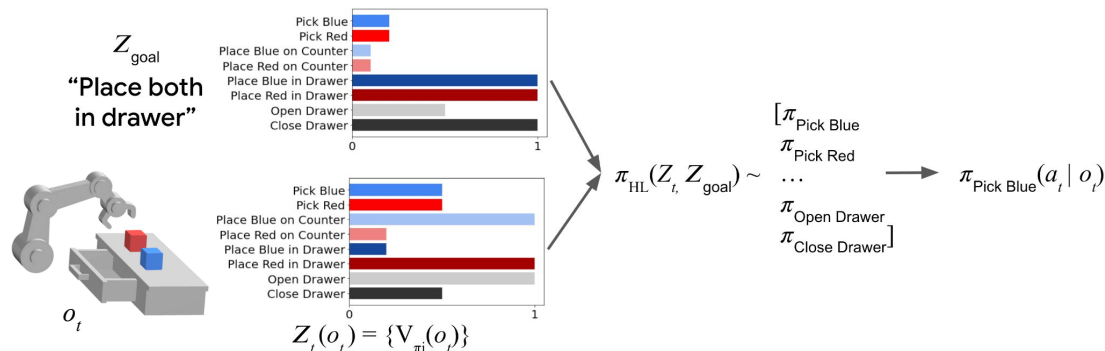
# A Toy Example

- The representation is robust to exogenous factors of variation
  - generalization for free, modulo the underlying skills.

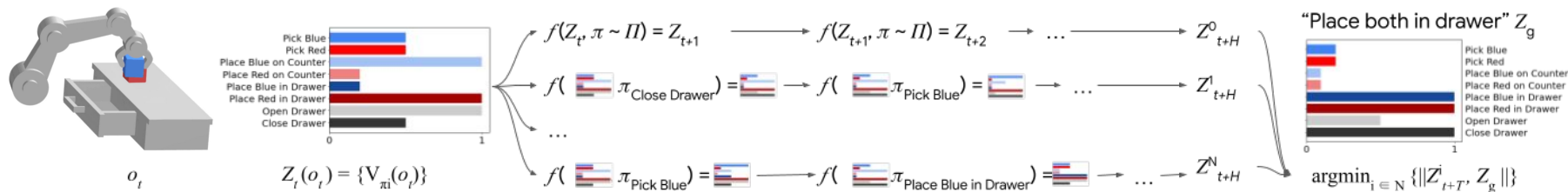


# Instantiating RL Pipelines with VFS

- Model-Free: HRL with high-level policy over skills using VFS as state



- Model-Based: Random shooting using predictive model on VFS states





# Instantiating RL Pipelines with VFS

## Primitives

GoToGreenDoor

GoToRedDoor

GoToYellowDoor

GoToPurpleDoor

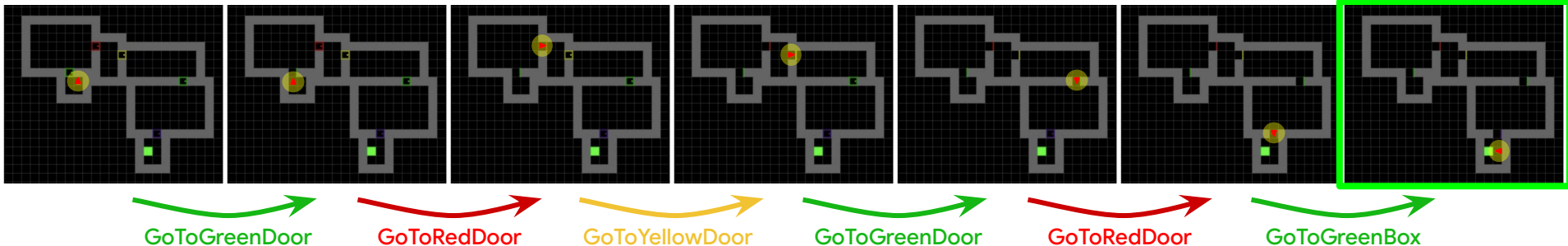
GoToGreenBox

GoToRedBox

GoToYellowBox

GoToPurpleBox

Goal: GreenBox



GoToGreenDoor

GoToRedDoor

GoToYellowDoor

GoToGreenDoor

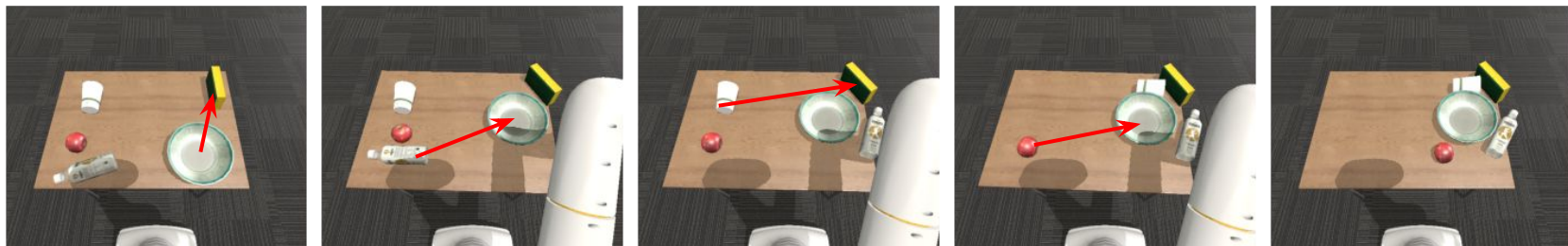
GoToRedDoor

GoToGreenBox

# Instantiating RL Pipelines with VFS

## Primitives

Move “A” Near “B”



Goal: “Move All to  
Top Right Corner”

Move Bowl  
Near Sponge

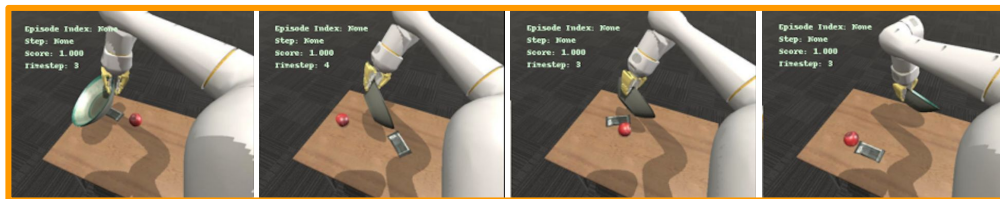
Move Bottle  
Near Bowl

Move Glass  
Near Sponge

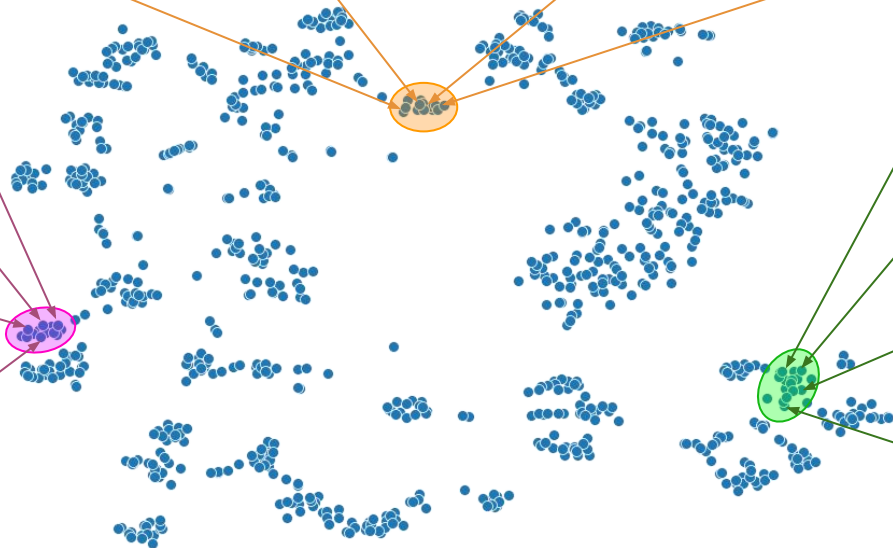
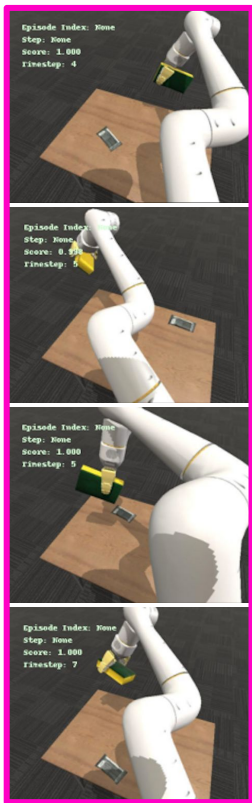
Move Apple Near Bowl

# Visualizing the Representations

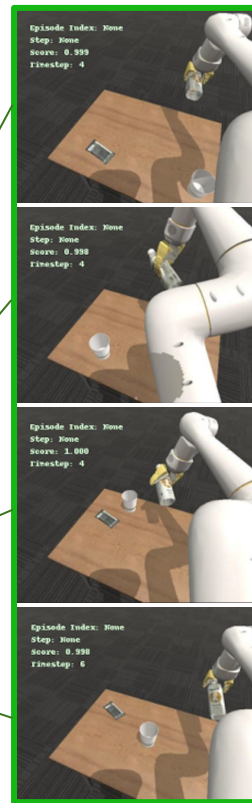
bowl in hand



sponge in hand





bottle in hand



# Value Function Spaces

## Skill-Centric State Abstractions for Long-Horizon Reasoning

Dhruv Shah 🐻, Peng Xu, Yao Lu, Ted Xiao,  
Alexander Toshev, Sergey Levine 🐻, Brian Ichter

 [cs.berkeley.edu/~shah/VFS](https://cs.berkeley.edu/~shah/VFS)  
 [shah@cs.berkeley.edu](mailto:shah@cs.berkeley.edu)

Google Research

 also at UC Berkeley