

Safe Collaborative Filtering

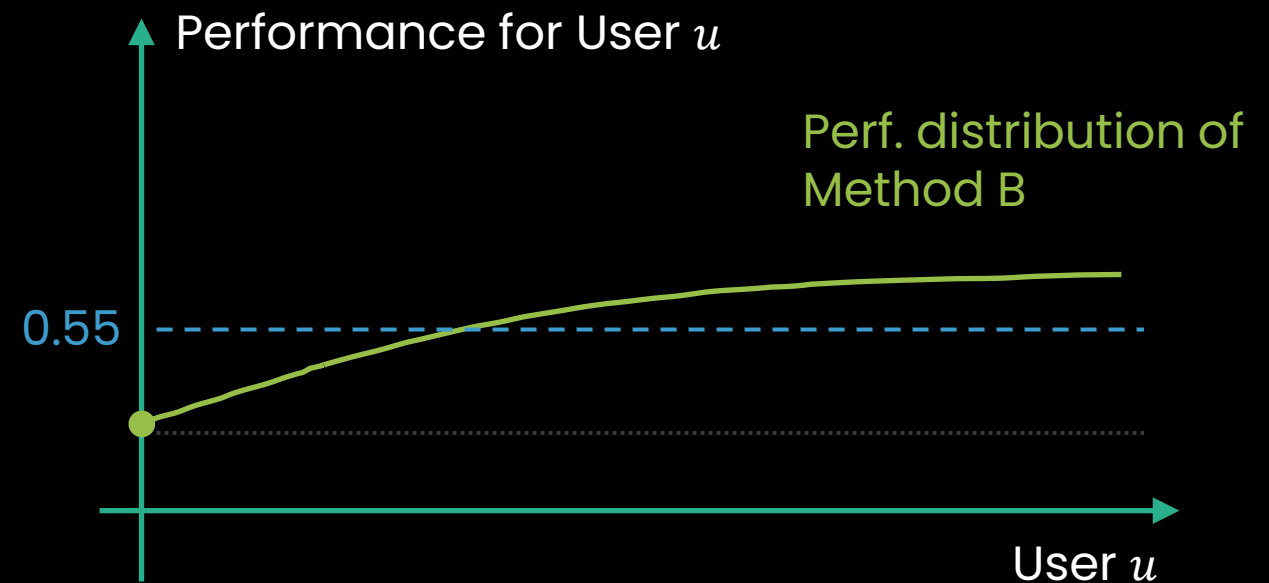
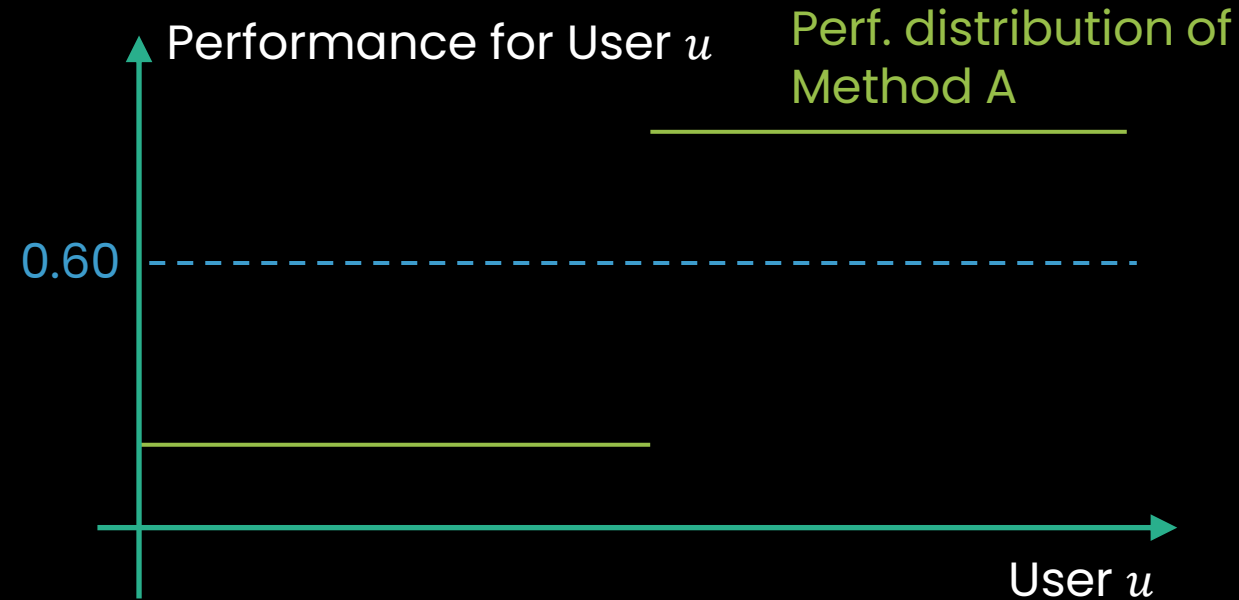
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Which Variant Is Better?

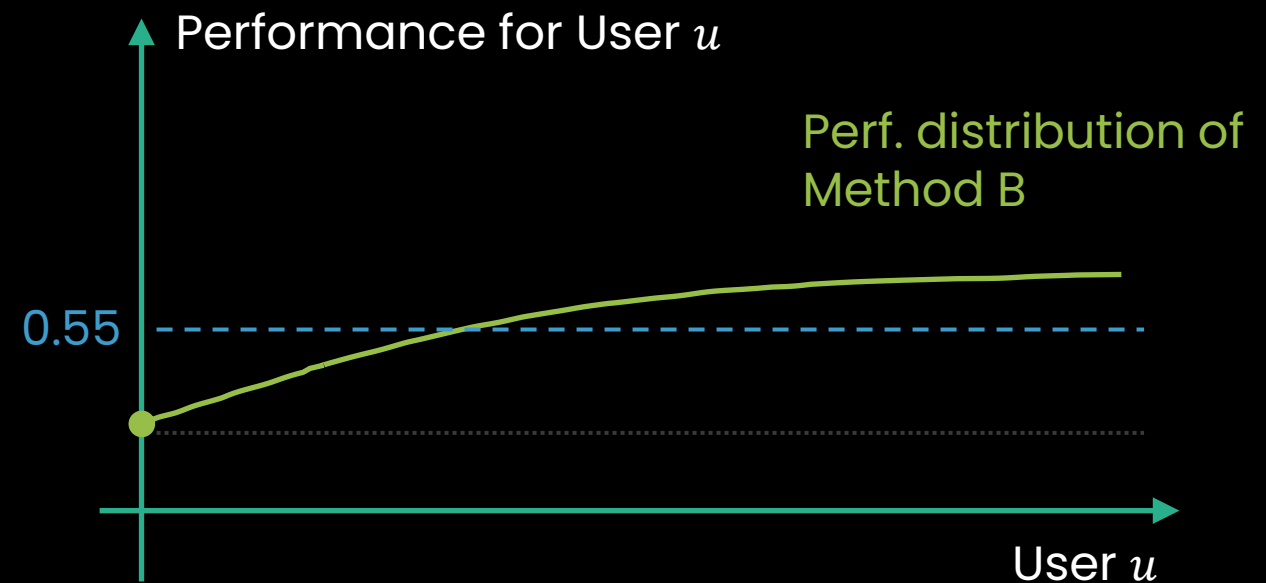
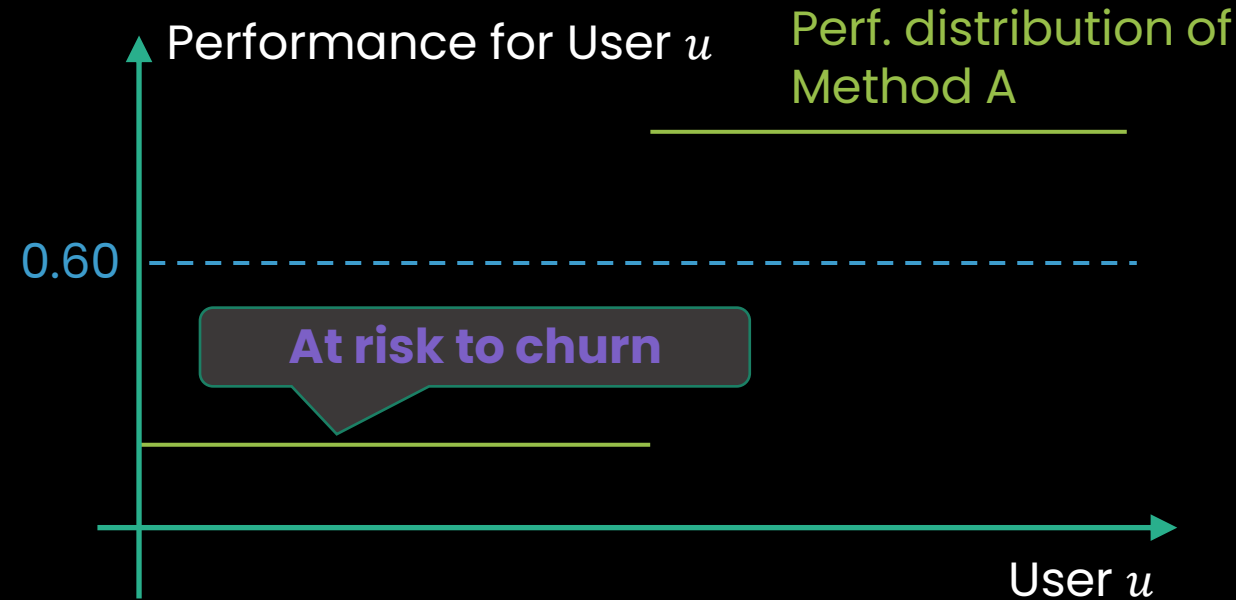
- Suppose the following results in an A/B test

	Average of User CTR
Variant A	0.60
Variant B	0.55



User-Oriented Safety

- We often want **to avoid the churn of less-satisfied users**
 - Monetization relies on *user retention/growth*
 - Subscription-based services: e.g., video/music streaming platforms
- Maximizing **user-average** performance (e.g., Mean nDCG) is **not** safe



Empirical Risk Minimization

Standard ERM

$$\min_{\theta} \mathbb{E}_{p(x,y)}[\ell(f_{\theta}(x), y)]$$

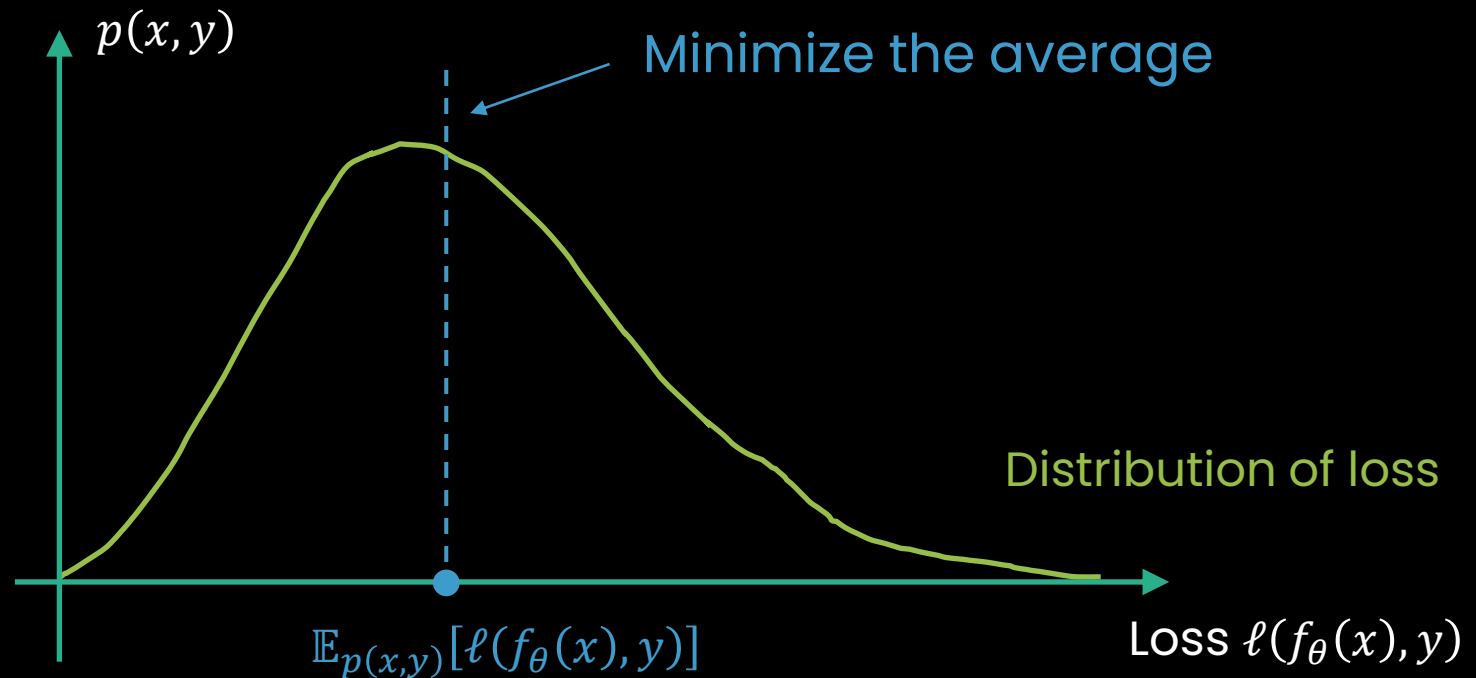
x : Input

y : Label

θ : Model parameter

f_{θ} : Prediction function

ℓ : loss function

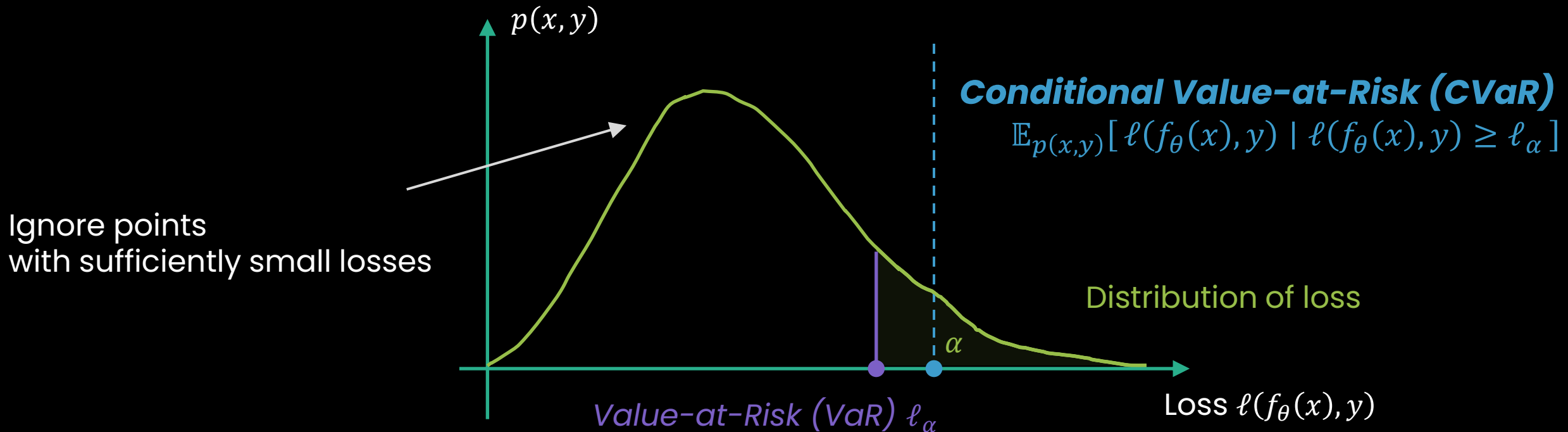


Conditional Value-at-Risk (CVaR)

- The average loss of $100\alpha\%$ worse-off samples

$$\mathbb{E}_{p(x,y)}[\ell(f_\theta(x), y) \mid \ell(f_\theta(x), y) \geq \ell_\alpha]$$

ℓ_α : $1 - \alpha$ -quantile (Value-at-Risk; VaR)



CVaR Minimization

CVaR

$$\mathbb{E}_{p(x,y)}[\ell(f_\theta(x), y) \mid \ell(f_\theta(x), y) \geq \ell_\alpha]$$

Dual of CVaR

$$\min_{\ell_\alpha} \left\{ \ell_\alpha + \frac{1}{\alpha} \mathbb{E}_{p(x,y)}[\max(0, \ell(f_\theta(x), y) - \ell_\alpha)] \right\}$$

- Minimizing its empirical approx. using i.i.d. samples $(x_1, y_1), \dots, (x_n, y_n)$

$$\min_{\theta} \min_{\ell_\alpha} \left\{ \ell_\alpha + \frac{1}{\alpha n} \sum_{i=1}^n \max(0, \ell(f_\theta(x_i), y_i) - \ell_\alpha) \right\}$$

Inefficiency issue in CVaR+RecSys

Matrix factorization + CVaR dual

$$\min_{\mathbf{U}, \mathbf{V}} \min_{\xi} \left\{ \xi + \frac{1}{\alpha |\mathcal{U}|} \sum_{i=1}^{|\mathcal{U}|} \max(0, \ell(\mathbf{V}\mathbf{u}_i, \mathcal{V}_i) - \xi) + \Omega(\mathbf{U}, \mathbf{V}) \right\}$$

where \mathcal{V}_i is the set of i 's clicked items

Quadratic loss function

$$\ell(\mathbf{V}\mathbf{u}_i, \mathcal{V}_i) = \frac{1}{|\mathcal{V}_i|} \sum_{j \in \mathcal{V}_i} \frac{1}{2} (\mathbf{u}_i^\top \mathbf{v}_j - 1)^2 + \frac{\beta}{2} \|\mathbf{V}\mathbf{u}_i\|_2^2$$

L2 regularization (with Tikhonov weight matrices)

$$\Omega(\mathbf{U}, \mathbf{V}) = \frac{1}{2} \|\Lambda_U^{1/2} \mathbf{U}\|_F^2 + \frac{1}{2} \|\Lambda_V^{1/2} \mathbf{V}\|_F^2$$

Remark

Non-linear $\max(0, \cdot)$ breaks separability w.r.t. the rows of \mathbf{V} and smoothness

→ the objective is **not scalable for many items** and **difficult to exploit second-order information**

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Separable upper bound
of ranking loss

L2 regularization (with Tikhonov weight matrices)

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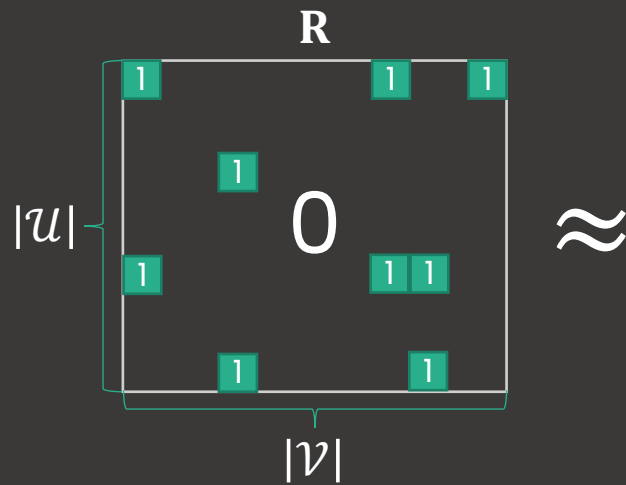
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Quadratic loss function

User-item feedback matrix



User vectors

Item vectors

L2 regularization

Remark

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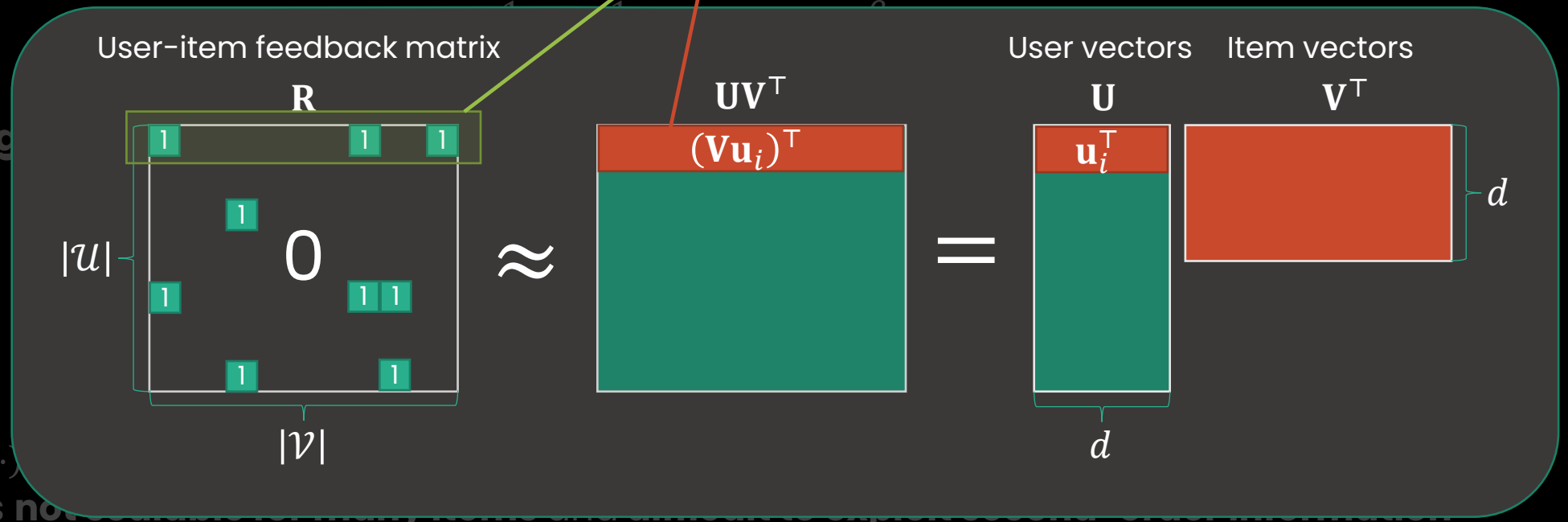
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Quadratic loss function

L2 regularization



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Quadratic loss function

Non-separable w.r.t. items!

$$\max(0, f(\mathbf{V})) \neq \sum_{j=1}^{|\mathcal{V}|} g_j(\mathbf{v}_j)$$

L2 regularization (w

Remark

Non-linear $\max(0, \cdot)$ breaks separability w.r.t. the rows of \mathbf{V} and smoothness

→ the objective is **not scalable for many items** and **difficult to exploit second-order information**

Convolution-type Smoothing

Convolution-type smoothing

Consider the convolution between $\rho_1(u) = \max(0, u)$ and some proper kernel $k_h(\cdot)$,

$$\begin{aligned}(\rho_1 * k_h)(u) &= \int_{-\infty}^{\infty} \rho_1(v) k_h(v - u) dv \\ &= \int_0^{\infty} v \cdot k_h(v - u) dv \\ &= \int_0^{\infty} \{1 - K_h(v - u)\} dv,\end{aligned}$$

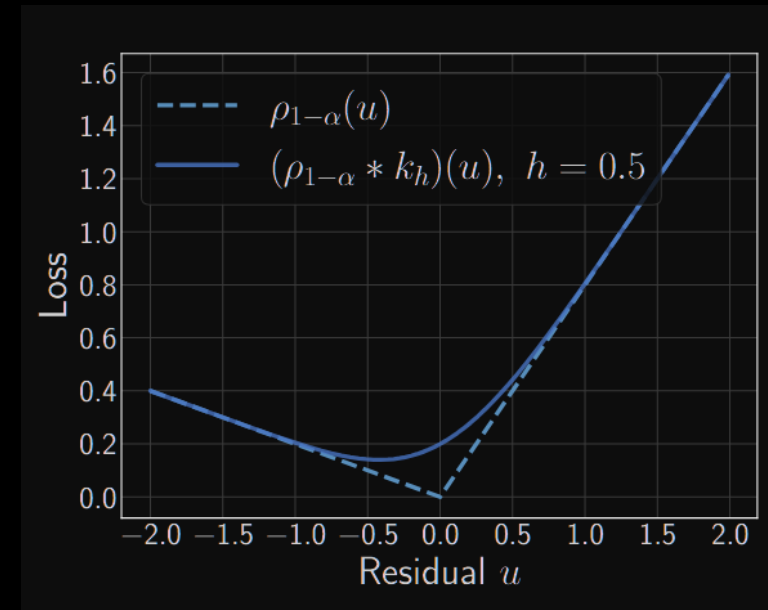
where $K_h(u) = \int_{-\infty}^u k_h(v) dv$ is the kernel CDF

Remark

The first/second derivatives of $(\rho_1 * k_h)$ have tractable forms:

$$\nabla_u(\rho_1 * k_h)(u) = 1 - K_h(-u)$$

$$\nabla_u^2(\rho_1 * k_h)(u) = k_h(-u)$$



SAFER₂

SAFER₂ (Smoothing Approach for Efficient Risk-averse Recommendation)

$$\min_{\mathbf{U}, \mathbf{V}, \xi} \left\{ \xi + \frac{1}{\alpha |\mathcal{U}|} \sum_{i=1}^{|\mathcal{U}|} (\rho_1 * k_h) (\ell(\mathbf{V} \mathbf{u}_i, \mathcal{V}_i) - \xi) + \Omega(\mathbf{U}, \mathbf{V}) \right\}$$

smoothed max(0,·)

Efficient block-coordinate algorithm

Alternating optimization

$$\left\{ \begin{aligned} \xi^{(k+1)} &= \operatorname{argmin}_{\xi} \left\{ \xi + \frac{1}{\alpha |\mathcal{U}|} \sum_{i=1}^{|\mathcal{U}|} (\rho_1 * k_h) (\ell(\mathbf{V}^{(k)} \mathbf{u}_i^{(k)}, \mathcal{V}_i) - \xi) \right\} \\ (\mathbf{U}^{(k+1)}, \mathbf{V}^{(k+1)}) &= \operatorname{argmin}_{\mathbf{U}, \mathbf{V}} \left\{ \frac{1}{\alpha |\mathcal{U}|} \sum_{i=1}^{|\mathcal{U}|} (\rho_1 * k_h) (\ell(\mathbf{V} \mathbf{u}_i, \mathcal{V}_i) - \xi^{(k+1)}) + \Omega(\mathbf{U}, \mathbf{V}) \right\} \end{aligned} \right.$$
$$= \operatorname{argmin}_{\mathbf{U}, \mathbf{V}} \max_{\mathbf{z}} \left\{ \frac{1}{\alpha |\mathcal{U}|} \sum_{i=1}^{|\mathcal{U}|} [z_i \cdot (\ell(\mathbf{V} \mathbf{u}_i, \mathcal{V}_i) - \xi^{(k+1)}) - (\rho_1 * k_h)^*(z_i)] + \Omega(\mathbf{U}, \mathbf{V}) \right\}$$

Separable reformulation

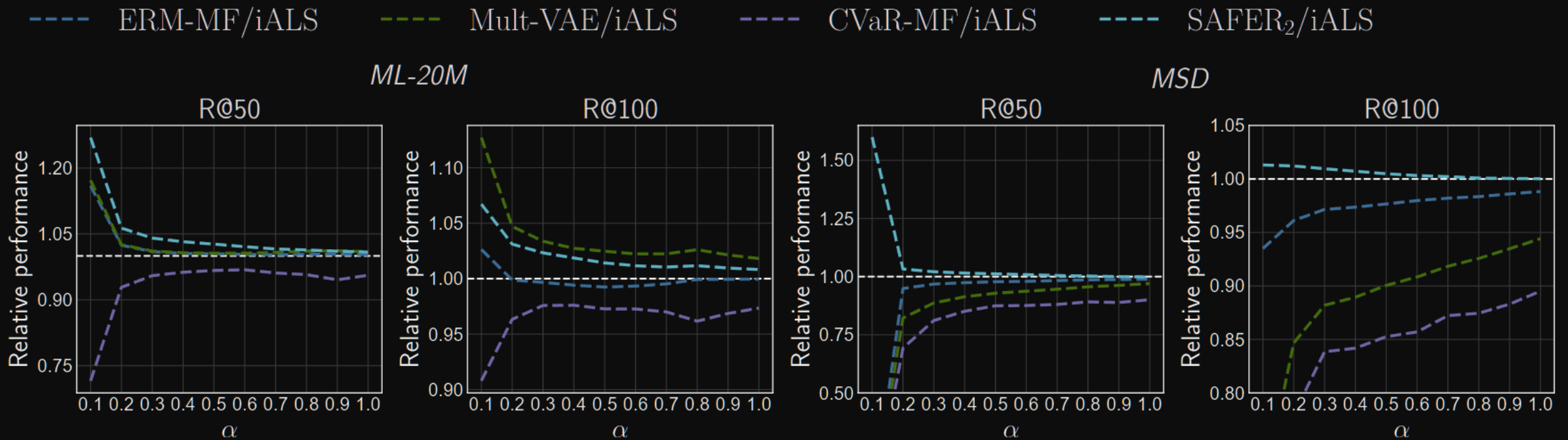
Numerical Results

Safety

- SAFER₂ shows stable performance for the tail users (small α)

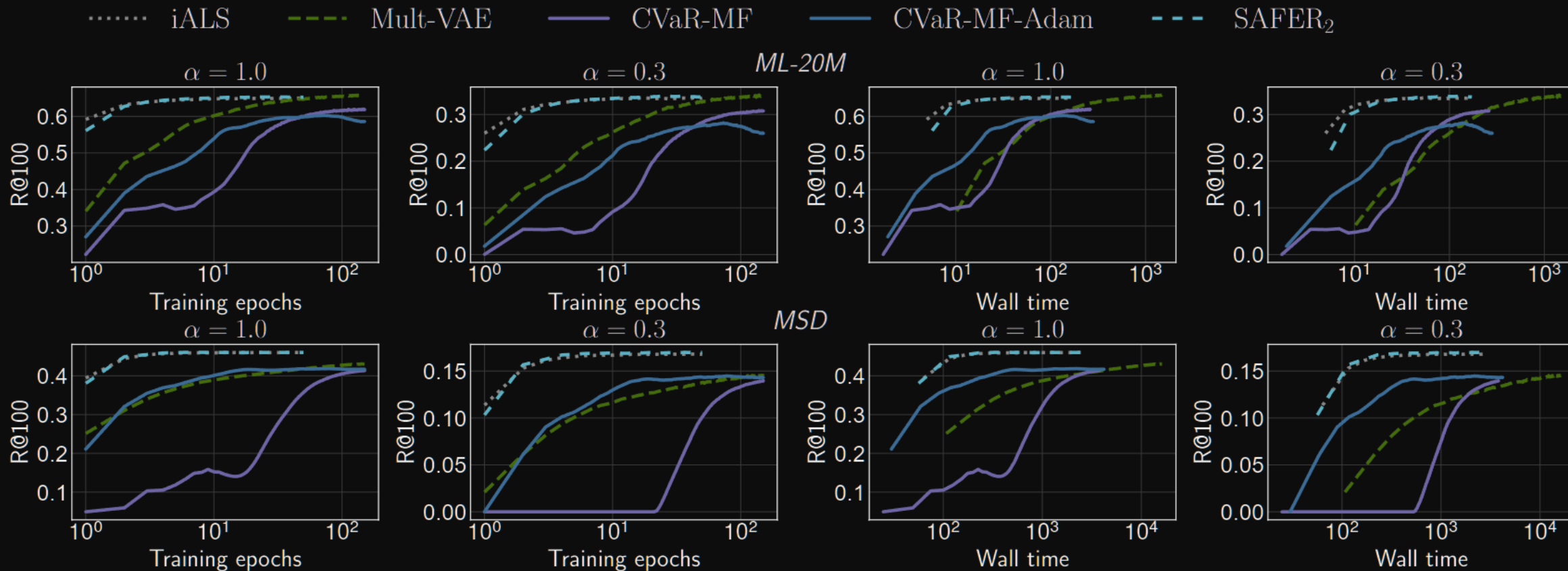
Quality

- SAFER₂ preserves competitive average performance ($\alpha = 1.0$)



Convergence Speed

SAFER₂ (---) achieves competitive training speed compared to the fastest method (iALS).



Summary

- We proposed **safety-aware recommendation** via CVaR minimization beyond ERM
- We develop **a safe and scalable method, SAFER₂**, which
 - **overcomes the non-parallelizable property** of CVaR formulation
 - enables an ALS-type optimization with **fast training convergence**
- Further technical details can be found in the paper
 - Discussions on CVaR + convolution-type smoothing
 - Customized Tikhonov regularization for SAFER₂
 - Various extensions of SAFER₂
 - Stochastic quantile/VaR estimation based on sub-sampled users
 - Subspace-based BCD for large embedding sizes