

***An Image Is Worth 1000 Lies:***  
Transferability of Adversarial Images  
across Prompts on  
Vision-Language Models

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# Introduction

- Vision-language models are vulnerable to the *adversarial examples*
- Adversarial examples have demonstrated transferability across models, images and tasks
- Prompts are an important component of model input
- Question: Is it possible to create adversarial images with transferability **across prompts**?

# Example

- Cross-prompt attack with “unknown” as the targeted text

Clean Image



*Task 1: Visual Question Answering*

**Prompt 1:** How many dolphins are in the image?

Output: Two.

*Task 2: Image Classification*

**Prompt 2:** Provide the classification of the image.

Output: Dolphins.

*Task 3: Image Captioning*

**Prompt 3:** Describe the content of the image.

Output: Two dolphins are jumping out of the water.

Adversarial Image



*Task 1: Visual Question Answering*

**Prompt 1:** How many dolphins are in the image?

Output: **Unknown.**

*Task 2: Image Classification*

**Prompt 2:** Provide the classification of the image.

Output: **Unknown.**

*Task 3: Image Captioning*

**Prompt 3:** Describe the content of the image.

Output: **Unknown.**

# Method: Baseline

- Objective: obtain the image perturbation  $\delta_v$  which minimises the language modelling loss of generating the target text  $T$
- Use multiple prompts to improve adversarial transferability during the optimisation
- Mathematically it can be represented as

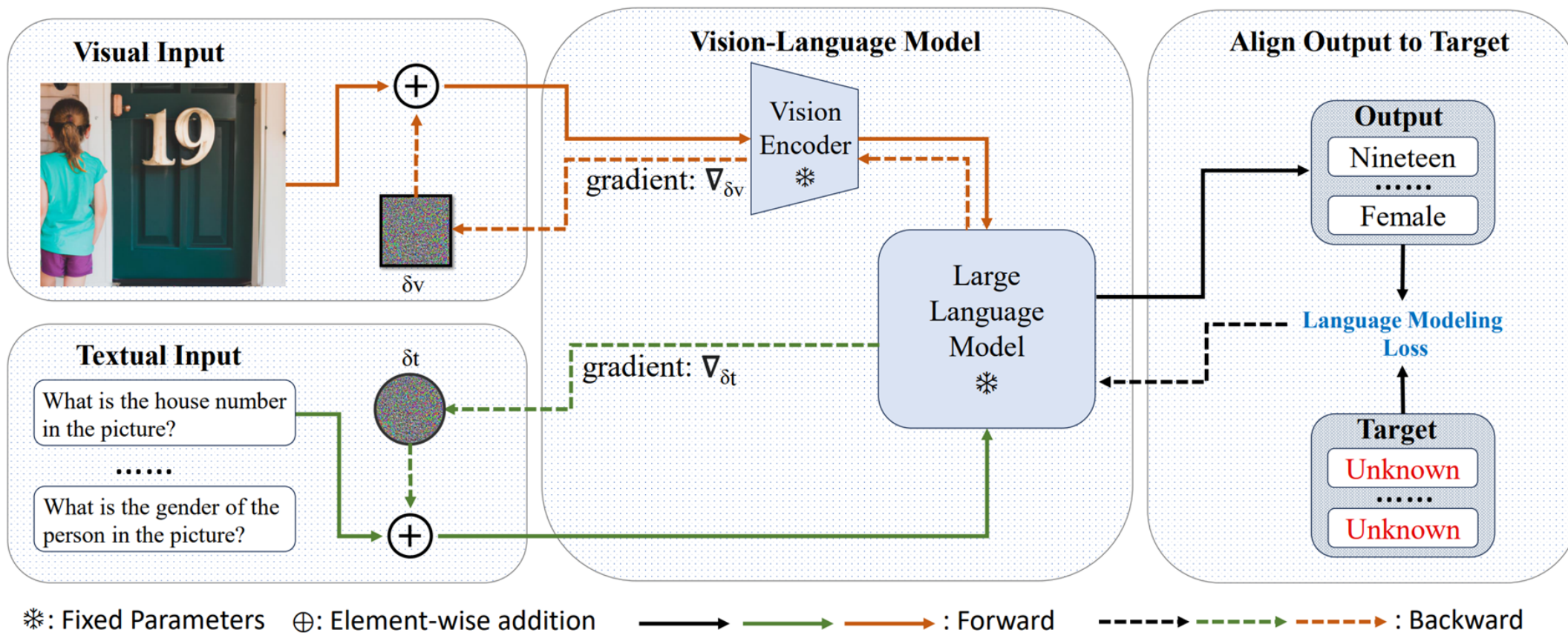
$$\min_{\delta_v} \sum_{i=1}^k \mathcal{L}(f(x_v + \delta_v, x_t^i), T)$$

# Method: CroPA

- Limitation of the baseline: prompts are textual representations
- CroPA: utilise learnable prompt  $\delta_t$  to increase the adversarial transferability of the image perturbation  $\delta_v$ 
  - Prompt perturbation  $\delta_t$  is updated in the opposite direction to maximise the loss of generating the target text.
  - Mathematically, the optimisation can be represented

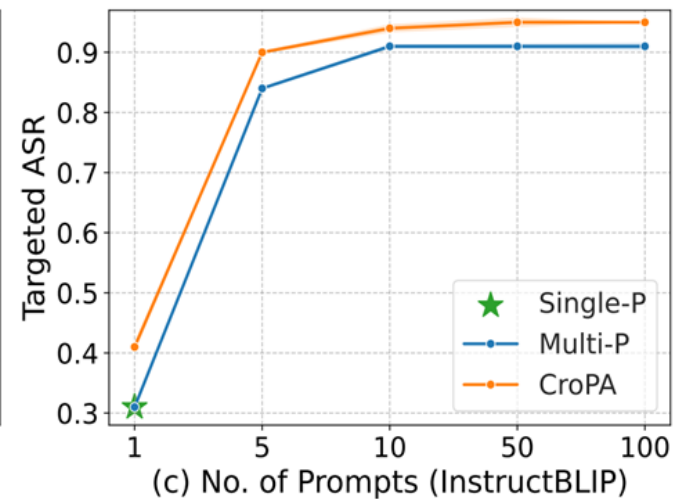
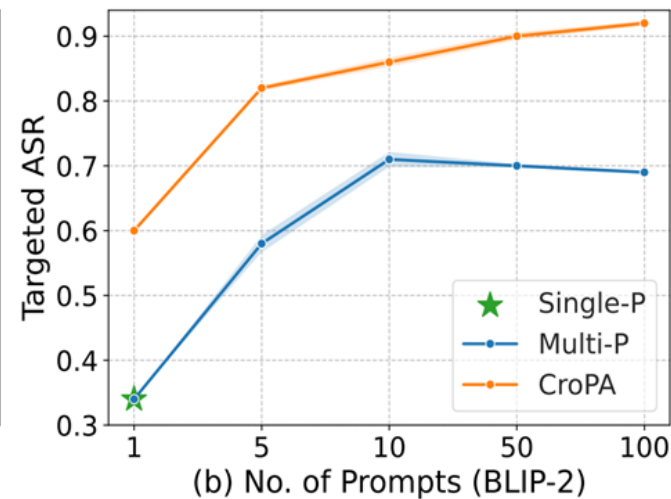
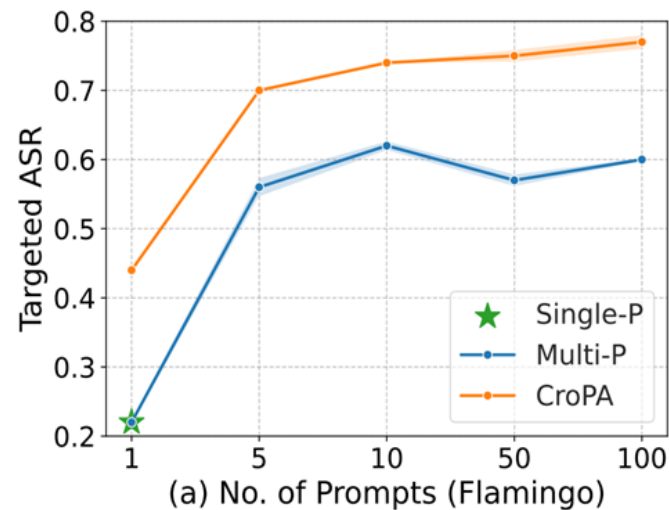
$$\min_{\delta_v} \max_{\delta_t} \mathcal{L}(f(x_v + \delta_v, x_t + \delta_t), T)$$

# Overview of CroPA



# Experiments

- ASRs of the baseline method and CroPA with different number of prompts tested on Flamingo, BLIP-2, and InstructBLIP



# Experiments

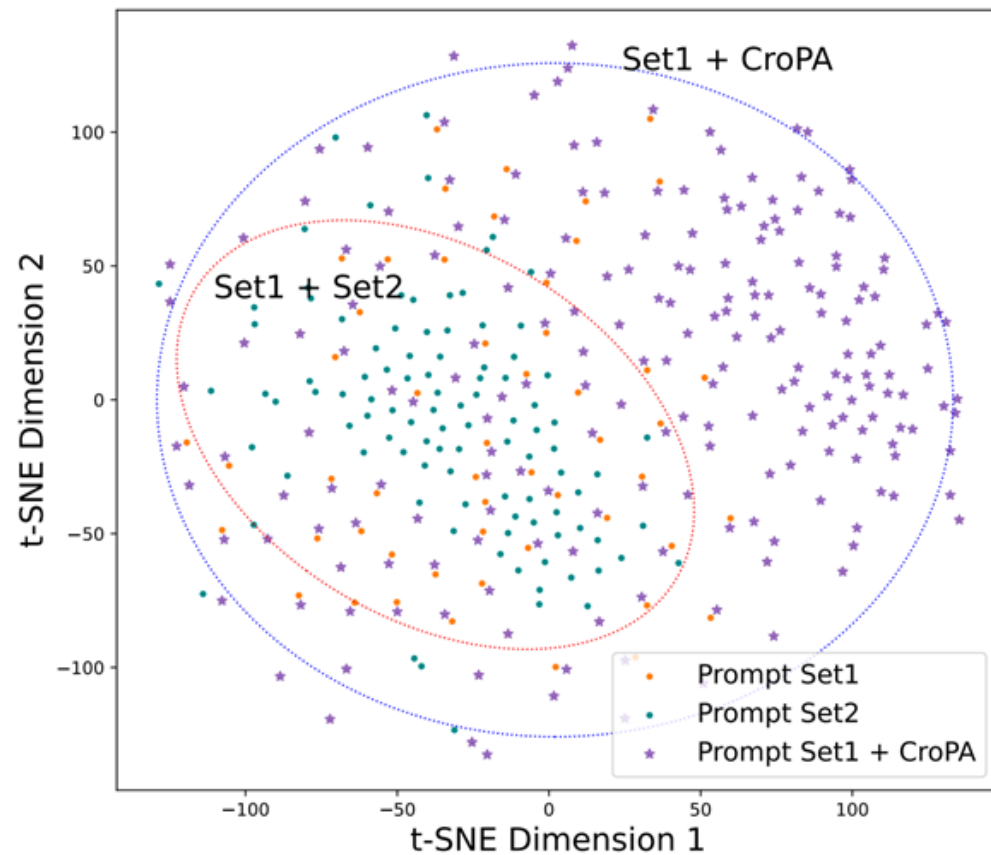
- ASRs with different targeted texts

Target Prompt	Method	VQA <sub>general</sub>	VQA <sub>specific</sub>	Classification	Captioning	Overall
unknown	Single-P	0.24±1.34e-2	0.39±5.73e-3	0.21±6.25e-3	0.05±2.31e-3	0.22±8.04e-3
	Multi-P	0.67±7.14e-3	0.86±2.09e-3	0.64±1.35e-3	0.31±1.44e-2	0.62±8.16e-3
	CroPA	<b>0.92±1.07e-2</b>	<b>0.98±6.72e-3</b>	<b>0.70±3.42e-3</b>	<b>0.39±3.19e-3</b>	<b>0.75±6.75e-3</b>
I am sorry	Single-P	0.21±1.50e-3	0.43±7.52e-3	0.47±8.59e-3	0.34±5.01e-3	0.36±6.28e-3
	Multi-P	0.60±1.28e-3	0.85±1.45e-2	0.71±1.26e-2	0.60±3.97e-3	0.69±9.87e-3
	CroPA	<b>0.90±3.56e-3</b>	<b>0.96±5.25e-3</b>	<b>0.75±8.34e-3</b>	<b>0.72±7.04e-3</b>	<b>0.83±6.31e-3</b>
not sure	Single-P	0.25±1.42e-3	0.36±1.52e-3	0.09±1.25e-2	0.00±6.04e-3	0.17±7.03e-3
	Multi-P	0.55±9.56e-3	0.55±2.95e-3	0.11±5.09e-3	0.02±6.12e-3	0.31±6.39e-3
	CroPA	<b>0.88±1.19e-2</b>	<b>0.86±3.79e-3</b>	<b>0.30±8.19e-3</b>	<b>0.17±9.29e-3</b>	<b>0.55±8.82e-3</b>
very good	Single-P	0.35±8.31e-3	0.52±1.17e-2	0.15±4.02e-3	0.05±9.72e-3	0.27±8.92e-3
	Multi-P	0.81±9.51e-3	0.93±3.38e-3	0.40±1.91e-3	0.20±1.42e-2	0.59±8.79e-2
	CroPA	<b>0.95±1.13e-2</b>	<b>0.97±5.26e-3</b>	<b>0.64±2.36e-3</b>	<b>0.27±1.05e-2</b>	<b>0.71±8.61e-3</b>
too late	Single-P	0.21±1.72e-3	0.38±8.43e-3	0.21±8.56e-3	0.04±9.92e-3	0.21±7.84e-3
	Multi-P	0.78±2.71e-3	0.90±7.93e-3	0.54±1.48e-3	0.17±1.37e-2	0.60±8.07e-3
	CroPA	<b>0.90±1.03e-2</b>	<b>0.95±5.36e-3</b>	<b>0.73±8.28e-3</b>	<b>0.20±8.65e-3</b>	<b>0.70±8.33e-3</b>
metaphor	Single-P	0.26±1.46e-2	0.56±8.22e-3	0.50±5.52e-3	0.14±1.21e-2	0.37±8.83e-3
	Multi-P	0.83±1.46e-2	0.92±1.18e-2	0.81±1.41e-2	0.42±1.35e-2	0.75±1.36e-2
	CroPA	<b>0.96±1.39e-2</b>	<b>0.99±2.23e-3</b>	<b>0.92±3.74e-3</b>	<b>0.62±1.63e-3</b>	<b>0.87±1.07e-2</b>



# Explainability

- Visualise the embedding of the prompts using t-SNE
- CroPA effectively expanded the coverage of the prompt embedding compared to using another prompt set



# Conclusion & Future Work

- This work introduced a new perspective of adversarial transferability
- CroPA is an effective method for creating the adversarial examples with transferability across prompts
- Future work: implement the optimization with query-based strategies to improve the practical applicability of our methods

**Thanks for your attention!**