

AutoFD: Automatic Functional Differentiation in JAX

Min Lin, Sea AI Lab



ICLR



TLDR

Given: $F[f] = \int \exp(f(x))dx$ Find: $\frac{\delta F[f]}{\delta f}$

```
from autofd import function
import autofd.operators as o

# define the functional
def F(f):
    return o.integrate(o.compose(jnp.exp, f))

# define a function
@function
def f(x: Float32[Array, ""]) -> Float32[Array, ""]:
    ...
# take the functional derivative
dFdf = jax.grad(F)(f)
# dFdf is invokable!
dFdf(1.)
```

Functions generalize vectors

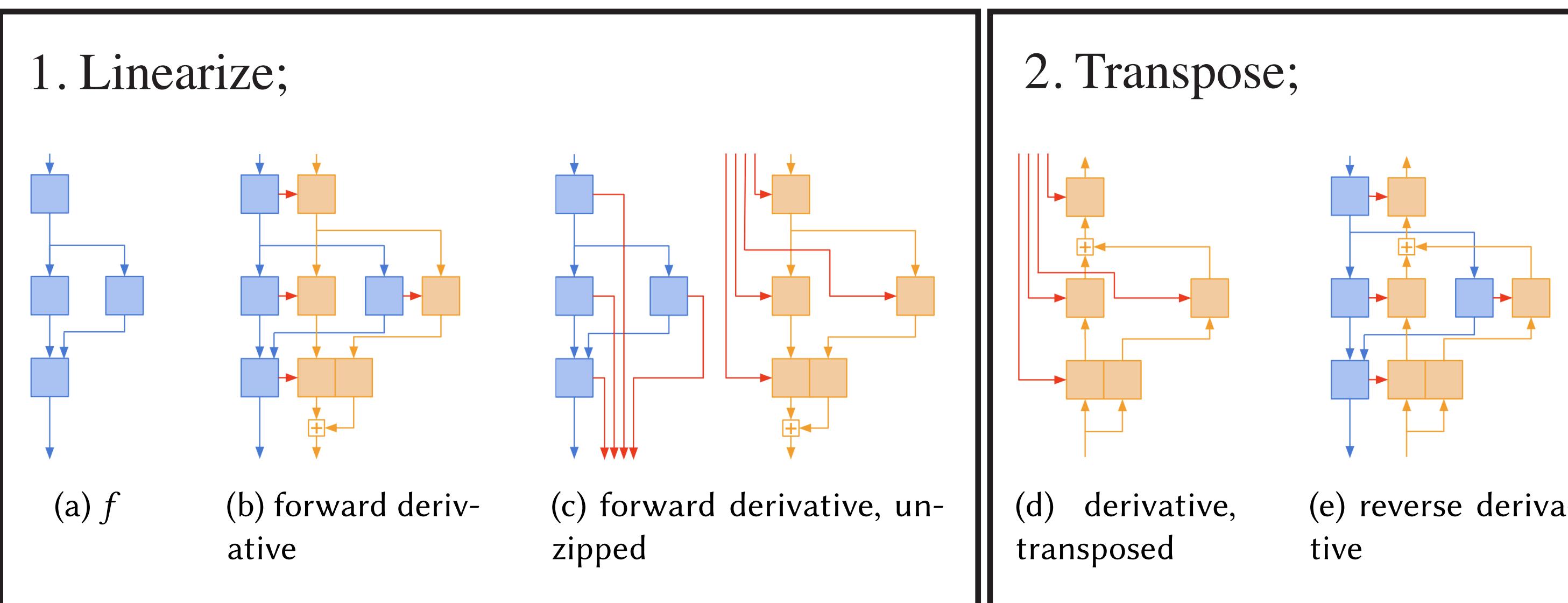
	Vector v	Function f
Visualize		
		Decrease the bin size Increase the number of bins
Indexing	v_i (discrete)	$f(x)$ (continuous)
Summation	$\sum_i v_i$	$\int f(x)dx$
Linear projection	$u = M^\top v$	$g(y) = \int K(y, x)f(x)dx$
Differentiation	$\frac{df(v)}{dv}$	$\frac{\delta F[f]}{\delta f}$

Types of Functionals & Operators

Local Operator	$\hat{\Phi}_L(f) : x \mapsto \phi_L(x, f(x)).$
Semilocal Operator	$\hat{\Phi}_S(f) : x \mapsto \phi_S(x, f(x), \nabla f(x), \dots, \nabla^{(n)} f(x)).$
Linear Nonlocal Operator	$\hat{\Phi}_I(f) : u \mapsto \int \phi_I(u, x)f(x)dx.$
Integral Functional	$F : f \mapsto \int \hat{\Phi}(f)(x)dx.$

Autodiff Mechanism of JAX

Radul et al. (2023)



Example jvp and transpose rules

```
def exp_jvp_rule(x, tangent):
    return exp(x) * tangent
```

```
def matvec_transpose(cotangent, m, v):
    if ad.is_undefined_primal(m):
        return [cotangent @ v.T, None]
    else:
        return [None, m.T @ cotangent]
```

Relating JAX API to math symbols

$\text{jax.jvp}(f, \underbrace{x}_{\text{primal tangent}}, \underbrace{\delta x}_{\text{Fréchet notation}}) = J_f(x)\delta x = \underbrace{D(f)(x)(\delta x)}_{\text{Fréchet notation}}$

$\text{jax.linear_transpose}(f, \underbrace{x}_{\text{primal}})(\underbrace{y}_{\text{cotangent}}) = f^\top(y) = T(f)(x)(y)$

AD for Functionals & Operators

JVP → Gateaux derivative

Example:

Compose operator

$\hat{C}(f, g) : x \mapsto f(g(x))$

Python:

```
def compose_impl(f, g):
    return lambda *args: f(g(*args))
```

$$\begin{aligned} \partial_g(\hat{C})(f, g)(\delta g)(x) \\ = \lim_{\tau \rightarrow 0} \frac{f(g(x) + \tau \delta g(x)) - f(g(x))}{\tau} \\ = \frac{d}{d\tau} f(g(x) + \tau \delta g(x)) |_{\tau=0} \end{aligned}$$

Math:

$$\begin{aligned} \partial_f(\hat{C})(f, g)(\delta f)(x) \\ = \lim_{\tau \rightarrow 0} \frac{f(g(x) + \tau \delta f(g(x))) - f(g(x))}{\tau} \\ = \delta f(g(x)) \\ = \hat{C}(\delta f, g)(x) \end{aligned}$$

```
def compose_jvp_rule(primals, tangents):
```

```
    f, g = primals
    df, dg = tangents
    primal_out = compose(f, g)
    tangent_out = sum(
        compose(linearize(f), g, dg),
        compose(df, g),
    )
    return primal_out, tangent_out
```

Transpose → Conjugate operator

Nabla operator

$\nabla(f) : x \mapsto f'(x)$

```
def nabla_impl(f):
    return jax.grad(f)
```

Conjugate operator $\langle \hat{O}f, g \rangle = \langle f, \hat{O}^*g \rangle$

$$\begin{aligned} \langle \nabla f, g \rangle &= \int dy g(y) \int dx \delta'(x-y) f(x) \\ &= \int dx f(x) \int dy \delta'(x-y) g(y) \\ &= \langle f, -\nabla g \rangle \end{aligned}$$

```
def nabla_transpose_rule(cotangent, primal):
```

```
    return -nabla(cotangent)
```

Primitive Operators

$\hat{C}(f, g) : x \mapsto f(g(x))$

$\nabla(f) : x \mapsto f'(x)$

$\hat{L}(f) : x, \delta x \mapsto f'(x)\delta x$

$\hat{T}(f) : x \mapsto f^\top(x)$

$\hat{I} : f \mapsto \int f(x)dx$

$\text{PermuteArgs}(f) : x, y \mapsto f(y, x)$

$\text{Zip}(f, g) : x, y \mapsto f(x), g(y)$

$\text{Partial}(f, x) : y \mapsto f(x, y)$

...

Neural Operator

```
def f(x: Float32[Array, ""]) -> Float32[Array, ""]:
    return jnp.sin(4 * x * jnp.pi)

def b(x: Float32[Array, ""]) -> Float32[Array, ""]:
    return jnp.sin(x * jnp.pi)

def y(x: Float32[Array, ""]) -> Float32[Array, ""]:
    return jnp.cos(x * jnp.pi)

def k(y: Float32[Array, ""], x: Float32[Array, ""]):
    return jnp.sin(y) + jnp.cos(x)

def layer(k, b, f, activate=True):
    # here k @ f is syntactic sugar for
    # o.integrate(k * broadcast(f), argnums=1)
    g = k @ f + b
    if activate:
        a = o.numpy.tanh(g)
        return a
    else:
        return g

def loss(params, f, t):
    # two layer mlp
    k1, b1, k2, b2 = params
    h1 = layer(k1, b1, f, activation=True)
    h2 = layer(k2, b2, h1, activation=False)
    return o.integrate((h2 - t)**2)
```

Density Functional Theory

Exchange Correlation Functionals

- Mostly semi-local
- Derivative of energy functional gives potential.
- Crucial for constructing Kohn-Sham Hamiltonian.
- Traditionally hand waved using Euler-Lagrange.

Calculating Band Structure for Solids

- Physicists write simple equations in function space.
- Implementation is in coefficient space.
- One of the difficulties in scientific computing is the math to implementation gap.

```
from autofd.operators import integrate
# a point in 3D
r = jnp.array([0.1, 0.2, 0.3])
# Exc, exchange-correlation energy functional
def exc(rho: Callable) -> float:
    epsilon_xc = gga_x_pbe(rho)
    return integrate(epsilon_xc * rho)
# Vxc is the functional derivative of Exc
vxc = jax.grad(exc)(rho)
# Vxc is itself a function callable with r as input
vxc(r)

def band_structure(crystal, fixed_rho):
    def potential_energy(rho):
        return (
            e.hartree(rho) +
            e.external(rho, crystal) +
            jax_xc.energy.lda_x(rho)
        )
    _, eff_energy = jax.linearize(potential_energy, (fixed_rho,))
    def energy_under_veff(param, k):
        psi = o.partial(wave_ansatz, args=(param,), argnums=(0,))
        return e.kinetic(psi) + eff_energy(psi_to_rho(psi))
    bands = {}
    for k in k_vectors:
        bands[k] = jnp.eigh(jax.hessian(energy_under_veff)(param, k))[0]
    return bands
```