

# A representation-learning game for classes of prediction tasks

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## Introduction

- The goal is to develop a method for learning data representations that utilizes prior knowledge about the following statistical inference.
- We introduce a game-based formulation for learning dimensionality-reducing representations.

## Game-Theoretic Formulation

$$\text{regret}(R, f | P_x) := \min_{Q \in \mathcal{Q}_{\mathbb{R}^r}} \mathbb{E}[\text{loss}(\mathbf{y}, Q(R(\mathbf{x})))] - \min_{Q \in \mathcal{Q}_X} \mathbb{E}[\text{loss}(\mathbf{y}, Q(\mathbf{x}))]$$

$$\text{regret}_{\text{pure}}(\mathcal{R}, \mathcal{F} | P_x) := \min_{R \in \mathcal{R}} \max_{f \in \mathcal{F}} \mathbb{E}[\text{regret}(R, f | P_x)]$$

$$\text{regret}_{\text{mix}}(\mathcal{R}, \mathcal{F} | P_x) := \min_{L(R) \in \mathcal{P}(\mathcal{R})} \max_{f \in \mathcal{F}} \mathbb{E}[\text{regret}(R, f | P_x)]$$

$$= \max_{L(f) \in \mathcal{P}(\mathcal{F})} \min_{R \in \mathcal{R}} \mathbb{E}[\text{regret}(R, f | P_x)]$$

## Theoretical Solution for Linear MSE Setting

- $\mathcal{X} = \mathbb{R}^d, \mathcal{Y} = \mathbb{R}$
- $R \in \mathbb{R}^{d \times r}, z = R(x) = R^T x$
- $f \in \mathbb{R}^d: \|f\|_2^2 \leq 1, S \in \mathbb{S}_{++}^d$
- $Q \in \mathcal{Q} \subset \mathbb{R}^r, Q(z) = q^T z = R^T q^T x \in \mathbb{R}$
- $\mathbf{y} = f^T \mathbf{x} + \mathbf{n} \in \mathbb{R}$
- $\text{loss}(y_1, y_2) = \|y_1 - y_2\|^2$

### Theorem I

$$\text{regret}_{\text{pure}}(\mathcal{F}_S | \Sigma_x) = \lambda_{r+1} \left( \Sigma_x^{1/2} S \Sigma_x^{1/2} \right)$$

$$R^* := \Sigma_x^{-1/2} \cdot V_{1:r} \left( \Sigma_x^{1/2} S \Sigma_x^{1/2} \right)$$

$$f^* := S^{1/2} \cdot v_{r+1} \left( \Sigma_x^{1/2} S \Sigma_x^{1/2} \right)$$

### Theorem II

$$\text{regret}_{\text{mix}}(\mathcal{F}_S | \Sigma_x) = \frac{\ell^* - r}{\sum_{i=1}^{\ell^*} \lambda_i^{-1}}$$

$$R^* = \Sigma_x^{-1/2} V_{\mathcal{F}} w.p. p_j$$

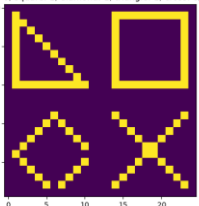
$$\Sigma_f^* := \frac{V^T \Lambda_f^{-1} V}{\sum_{i=1}^{\ell^*} \lambda_i^{-1}}$$

$$\lambda_i \equiv \lambda_i(S^{1/2} \Sigma_x S^{1/2}), V \equiv V(S^{1/2} \Sigma_x S^{1/2})$$

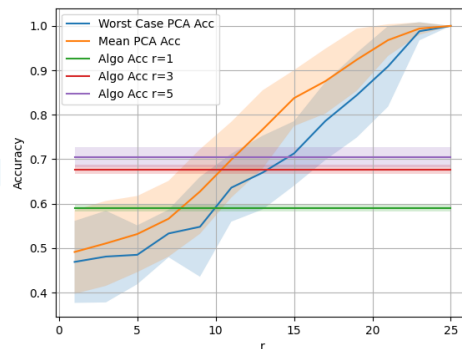
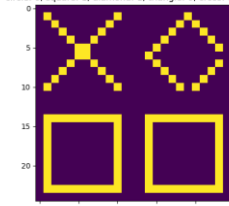
## Multi Label Setting

- $\mathcal{X} = \mathbb{R}^{\sqrt{d} \times \sqrt{d}}$ , that  $\mathcal{Y} = \{\pm 1\}$
- $R \in \mathcal{R} := \mathbb{R}^{d \times r}$  where  $d > r$
- $\mathcal{Q} := \{Q(z) = 1/[1 + \exp(-q^T z)], q \in \mathbb{R}^r\}$
- $\mathcal{F} = \{f_1, \dots, f_n\}$
- $\text{loss}(y_i, q) := -\frac{1}{2}(1 + y_i) \log q - \frac{1}{2}(1 - y_i) \log(1 - q), i \in [n]$

circle: 0, square: 1, diamond: 1, triangle: 1, cross: 0, x: 1.



circle: 0, square: 1, diamond: 1, triangle: 0, cross: 0, x: 1.



## Algorithm

- Alternating optimization algorithm using gradient descent ascent.
- Finding best representation and worst function at each iteration.
- Resemble the best response algorithm from the field of game theory.

### Algorithm 1 Algorithm 1

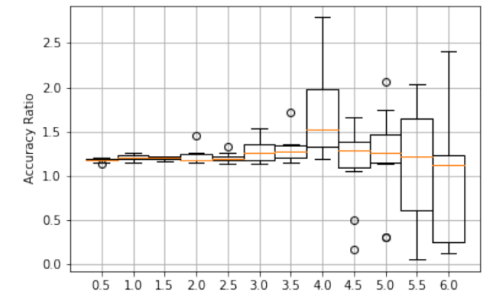
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input  $P_x, \mathcal{R}, \mathcal{F}, \mathcal{Q}, d, r, m, m_0$            ▷ Feature distribution, classes, dimensions and parameters
input  $R^{(1)}, \{f^{(j)}\}_{j \in [m_0]}$            ▷ Initial representation and initial function (set)
for  $k=1$  to  $m$  do
    phase 1:  $f^{(m_0+k)}$  is set by a solver of [eq: phase 1 iterative alg] and
     $\text{reg}_k \leftarrow \text{regret}_{\text{mix}}(\{R^{(j)}, p^{(j)}\}_{j \in [k]}, \mathcal{F} | P_x)$ 
    ▷ Solved using Algorithm [alg: phase 1 sol]
    phase 2:  $R^{(k+1)}, \{p_k^{(j)}\}_{j \in [k+1]}$  is set by a solver of [eq: phase 2 iterative alg]   ▷ Solved using
    Algorithm [alg: phase 2 sol]; step can be removed if  $k=m$ 
end
set  $m^* = \arg \min_{k \in [m]} \text{reg}_k$ 
return  $\{R^{(j)}\}_{j \in [m^*]}$  and  $p_{m^*} = \{p_k^{(j)}\}_{j \in [m^*]}$ 
  
```

## Results

### MSE-Linear

- Comparison between the theoretical results and the results achieved by the algorithm



### Cross Entropy

- Algorithm results for classification
- Regret decrease with m
- Regret increase with d

