Efficient local linearity regularization to overcome catastrophic overfitting

Elias Abad Rocamora¹, Fanghui Liu², Grigorios G. Chrysos³, Pablo M. Olmos⁴, Volkan Cevher¹



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Background: Adversarial Training (AT)

Considering a classifier f_{θ} parametrized by θ and a distribution \mathcal{D} on inputs x and labels y.

• We are interested in fast Adversarial Training (AT) (Madry et al., 2018) :

$$\min_{\boldsymbol{\theta}} \mathbb{E}_{(\boldsymbol{x}, y) \sim \mathcal{D}} \left[\max_{||\boldsymbol{\delta}||_{\infty} \leq \epsilon} \mathcal{L}(\boldsymbol{f}_{\boldsymbol{\theta}}(\boldsymbol{x} + \boldsymbol{\delta}), y) \right]$$



Madry et al., Towards Deep Learning Models Resistant to Adversarial Attacks ICLR, 2018.



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• Solving the inner max slows down training:

$$\boldsymbol{\delta}_{t+1} = \underset{||\boldsymbol{\delta}||_{\infty} \leq \epsilon}{\operatorname{proj}} \left[\boldsymbol{\delta}_{t+1} + \gamma \cdot \operatorname{sign} \left(\nabla_{\boldsymbol{x}} \mathcal{L}(\boldsymbol{f}_{\boldsymbol{\theta}}(\boldsymbol{x} + \boldsymbol{\delta}_{t}), \boldsymbol{y}) \right) \right]$$

10 PGD steps are tipically employed $\Rightarrow \times 10$ overhead! 🥮



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Background: Catastrophic Overfitting (CO)

• As a cheap alternative, 1 PGD step (FGSM) can be used:

 $\boldsymbol{\delta}_{\mathsf{FGSM}} = \boldsymbol{\epsilon} \cdot \mathsf{sign}\left(\nabla_{\boldsymbol{x}} \mathcal{L}(\boldsymbol{f}_{\boldsymbol{\theta}}(\boldsymbol{x}), \boldsymbol{y})\right)$



Wong et al., Fast is better than free: Revisiting adversarial training *ICLR*, 2020. Andriuschenko and Flammarion, Understanding and Improving Fast Adversarial Training *NeurIPS*, 2020.



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Background: Catastrophic Overfitting (CO)

• As a cheap alternative, 1 PGD step (FGSM) can be used:

$$\delta_{\mathsf{FGSM}} = \epsilon \cdot \mathsf{sign}\left(\nabla_{\pmb{x}} \mathcal{L}(\pmb{f}_{\pmb{\theta}}(\pmb{x}), \pmb{y}) \right)$$

• Sadly, Catastrophic Overfitting (CO) appears:



• Local linearity regularization can overcome CO. Let $\eta \sim \text{Unif}(-\epsilon, \epsilon)$:



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- Local linearity regularization can overcome CO. Let $\eta \sim \text{Unif}(-\epsilon, \epsilon)$:
- GradAlign:
 - 1 cos-sim $[\nabla_{\mathbf{x}} \mathcal{L}(\mathbf{f}_{\boldsymbol{\theta}}(\mathbf{x}), \mathbf{y}), \nabla_{\mathbf{x}} \mathcal{L}(\mathbf{f}_{\boldsymbol{\theta}}(\mathbf{x}+\boldsymbol{\eta}), \mathbf{y})]$



Moosavi-Dezfooli et al., Robustness via Curvature Regularization, and Vice Versa CVPR, 2019.

LLR:

$$\mathcal{L}(f_{\theta}(\mathbf{x}+\boldsymbol{\eta}), y) - \mathcal{L}(f_{\theta}(\mathbf{x}), y) + \boldsymbol{\eta}^{\top} \nabla_{\mathbf{x}} \mathcal{L}(f_{\theta}(\mathbf{x}), y)$$

Qin et al., Adversarial Robustness through Local Linearization NeurIPS, 2019.

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- Local linearity regularization can overcome CO. Let $\eta \sim \text{Unif}(-\epsilon, \epsilon)$:
- GradAlign:

LLR:

 $1 - \cos - \sin \left[\nabla_{\mathbf{x}} \mathcal{L}(\mathbf{f}_{\boldsymbol{\theta}}(\mathbf{x}), \mathbf{y}), \nabla_{\mathbf{x}} \mathcal{L}(\mathbf{f}_{\boldsymbol{\theta}}(\mathbf{x} + \boldsymbol{\eta}), \mathbf{y}) \right]$



 $\left| \mathcal{L}(\mathbf{f}_{\boldsymbol{\theta}}(\mathbf{x} + \boldsymbol{\eta}), y) - \mathcal{L}(\mathbf{f}_{\boldsymbol{\theta}}(\mathbf{x}), y) + \boldsymbol{\eta}^{\top} \nabla_{\mathbf{x}} \mathcal{L}(\mathbf{f}_{\boldsymbol{\theta}}(\mathbf{x}), y) \right|$

Qin et al., Adversarial Robustness through Local Linearization NeurIPS, 2019.

• The problem: Differentiating gradients $(\nabla_{\theta} \nabla_{x})$ is costly.

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- Local linearity regularization can overcome CO. Let $\eta \sim \text{Unif}(-\epsilon, \epsilon)$:
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LLR:

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 $\left| \mathcal{L}(\mathbf{f}_{\boldsymbol{\theta}}(\mathbf{x} + \boldsymbol{\eta}), \mathbf{y}) - \mathcal{L}(\mathbf{f}_{\boldsymbol{\theta}}(\mathbf{x}), \mathbf{y}) + \boldsymbol{\eta}^{\top} \nabla_{\mathbf{x}} \mathcal{L}(\mathbf{f}_{\boldsymbol{\theta}}(\mathbf{x}), \mathbf{y}) \right|$

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- The problem: Differentiating gradients $(\nabla_{\theta} \nabla_{x})$ is costly.
- The challenge: Can we efficiently regularize local linearity?



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Our Method: ELLE

• If a function h is locally linear in a convex set \mathcal{X} , it must safisfy:

 $h((1-\alpha)\cdot\mathbf{x}_{a}+\alpha\cdot\mathbf{x}_{b}) = (1-\alpha)\cdot h(\mathbf{x}_{a}) + \alpha\cdot h(\mathbf{x}_{b}), \quad \forall \alpha \in [0,1], \forall \mathbf{x}_{a}, \mathbf{x}_{b} \in \mathcal{X}$



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• ELLE: Let $\mathbf{x}_{a}, \mathbf{x}_{b} \sim \text{Unif}(\mathbf{x} + \boldsymbol{\delta} : ||\boldsymbol{\delta}||_{\infty} \leq \epsilon), \ \alpha \sim \text{Unif}([0, 1]) \text{ and } \mathbf{x}_{c} = (1 - \alpha) \cdot \mathbf{x}_{a} + \alpha \cdot \mathbf{x}_{b}:$ $[(1 - \alpha) \cdot \mathcal{L}(\mathbf{f}_{\boldsymbol{\theta}}(\mathbf{x}_{a}), y) + \alpha \cdot \mathcal{L}(\mathbf{f}_{\boldsymbol{\theta}}(\mathbf{x}_{b}), y) - \mathcal{L}(\mathbf{f}_{\boldsymbol{\theta}}(\mathbf{x}_{c}), y)]^{2}$

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- ELLE: Let $\mathbf{x}_{a}, \mathbf{x}_{b} \sim \text{Unif}(\mathbf{x} + \boldsymbol{\delta} : ||\boldsymbol{\delta}||_{\infty} \leq \epsilon), \ \alpha \sim \text{Unif}([0, 1]) \text{ and } \mathbf{x}_{c} = (1 \alpha) \cdot \mathbf{x}_{a} + \alpha \cdot \mathbf{x}_{b}:$ $[(1 - \alpha) \cdot \mathcal{L}(\mathbf{f}_{\boldsymbol{\theta}}(\mathbf{x}_{a}), y) + \alpha \cdot \mathcal{L}(\mathbf{f}_{\boldsymbol{\theta}}(\mathbf{x}_{b}), y) - \mathcal{L}(\mathbf{f}_{\boldsymbol{\theta}}(\mathbf{x}_{c}), y)]^{2}$
- Our regularization term does not involve differentiating gradients 🤩.

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Method

Our Method: ELLE



Figure: PreActResNet in CIFAR10 at $\epsilon = 8/255$

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ICLR

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Abad Rocamora (EPFL)

Method

Our Method: ELLE



Figure: PreActResNet in CIFAR10 at $\epsilon = 8/255$

Our local linearity metric follows the one of GradAlign at a reduced cost.



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Method

Our Method: ELLE



Figure: PreActResNet in CIFAR10 at $\epsilon = 8/255$

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- Our local linearity metric follows the one of GradAlign at a reduced cost.
- When regularized (• and •), CO is overcome.

Comparison with other regularization terms



ε	8	3	16		
Method	AA	Clean	AA	Clean	
LLR CURE GradAlign	$\begin{array}{l} 42.18 \pm (0.20) \\ 43.60 \pm (0.17) \\ \textbf{44.66} \pm (0.21) \end{array}$	$\begin{array}{l} 75.02 \pm (0.09) \\ 77.74 \pm (0.11) \\ \textbf{80.50} \pm (0.07) \end{array}$	$\begin{array}{c} 16.92 \pm (0.20) \\ \underline{18.25} \pm (0.45) \\ 17.46 \pm (1.71) \end{array}$	$\begin{array}{c} 42.81 \pm (9.62) \\ 52.49 \pm (0.04) \\ 44.35 \pm (15.32) \end{array}$	
ELLE ELLE-A	$\begin{array}{c} 42.78 \pm (0.95) \\ \underline{44.32} \pm (0.04) \end{array}$	$\frac{80.13}{79.81} \pm (0.32) \\ \pm (0.10)$	$\begin{array}{c} {\bf 18.28} \pm (0.17) \\ {\bf 18.03} \pm (0.15) \end{array}$	$59.73 \pm (0.16) \\ \underline{59.21} \pm (1.23)$	
AT PGD-10	$46.95 \pm (0.11)$	$79.11\pm(0.08)$	$24.77 \pm (0.26)$	$59.64 \pm (0.46)$	

Runtime comparison

PreActResNet18 in CIFAR10

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Comparison with other regularization terms



ε	8	}	16		
Method	AA	Clean	AA	Clean	
LLR CURE GradAlign	$42.18 \pm (0.20) 43.60 \pm (0.17) 44.66 \pm (0.21)$	$75.02 \pm (0.09) 77.74 \pm (0.11) 80.50 \pm (0.07)$	$\begin{array}{c} 16.92 \pm (0.20) \\ \underline{18.25} \pm (0.45) \\ 17.46 \pm (1.71) \end{array}$	$\begin{array}{c} 42.81 \pm (9.62) \\ 52.49 \pm (0.04) \\ 44.35 \pm (15.32) \end{array}$	
ELLE ELLE-A	$\begin{array}{c} 42.78 \pm (0.95) \\ \underline{44.32} \pm (0.04) \end{array}$	$\frac{80.13}{79.81} \pm (0.32)$ 79.81 $\pm (0.10)$	$\begin{vmatrix} 18.28 \pm (0.17) \\ 18.03 \pm (0.15) \end{vmatrix}$	$\frac{59.73 \pm (0.16)}{\underline{59.21} \pm (1.23)}$	
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Runtime comparison

PreActResNet18 in CIFAR10

• ELLE attains comparable performance with negligible overhead.

ICLR

Combination with other methods

ϵ		16		26	
Method	Model	AA	Clean	AA	Clean
GAT GAT+ELLE-A N-FGSM N-FGSM+ELLE-A	No.	$\begin{array}{c} 0.54 \pm (0.53) \\ 13.83 \pm (4.63) \\ \textbf{20.59} \pm (0.21) \\ \underline{20.48} \pm (0.57) \end{array}$	$\begin{array}{c} 78.52 \pm (0.25) \\ 65.71 \pm (2.48) \\ 61.24 \pm (0.26) \\ 61.21 \pm (0.14) \end{array}$	$\begin{array}{c} 0.01 \pm (0.00) \\ 6.56 \pm (2.79) \\ \underline{10.96} \pm (0.26) \\ 12.03 \pm (1.02) \end{array}$	$\begin{array}{c} 84.35 \pm (0.34) \\ 58.37 \pm (2.39) \\ 37.73 \pm (0.32) \\ 26.77 \pm (3.25) \end{array}$
AT PGD-10		$24.77 \pm (0.26)$	$59.64 \pm (0.46)$	$14.42\pm(0.00)$	$34.90 \pm (0.61)$
GAT GAT+ELLE-A N-FGSM N-FGSM+ELLE-A	NR RA	$\begin{array}{c} 0.95 \pm (0.09) \\ 17.30 \pm (1.20) \\ \underline{20.54} \pm (0.18) \\ 21.28 \pm (0.07) \end{array}$	$\begin{array}{l} 84.09 \pm (0.10) \\ 64.27 \pm (3.56) \\ 63.83 \pm (1.24) \\ 64.25 \pm (0.20) \end{array}$	$\begin{array}{c} 0.00 \pm (0.00) \\ 6.74 \pm (2.08) \\ 3.31 \pm (2.58) \\ \textbf{12.22} \pm (0.25) \end{array}$	$\begin{array}{c} 89.04 \pm (0.28) \\ 42.04 \pm (10.52) \\ 27.96 \pm (9.36) \\ 33.50 \pm (0.14) \end{array}$
AT PGD-10		$26.77 \pm (0.28)$	$64.97 \pm (0.09)$	$14.61\pm(0.10)$	$36.30\pm(0.62)$



CIFAR10 Short schedule

WRN in CIFAR10 at $\epsilon=\frac{26}{255}$



Sriramanan et al., Guided adversarial attack for evaluating and enhancing adversarial defenses NeurIPS, 2020.

de Jorge et al., Make some noise: Reliable and efficient single-step adversarial training NeurIPS, 2022.



Combination with other methods

ε		16		26	
Method	Model	AA	Clean	AA	Clean
GAT GAT+ELLE-A N-FGSM N-FGSM+ELLE-A	of the second	$\begin{array}{c} \textbf{0.54} \pm (\textbf{0.53}) \\ \textbf{13.83} \pm (\textbf{4.63}) \\ \textbf{20.59} \pm (\textbf{0.21}) \\ \underline{\textbf{20.48}} \pm (\textbf{0.57}) \end{array}$	$\begin{array}{c} 78.52 \pm (0.25) \\ 65.71 \pm (2.48) \\ 61.24 \pm (0.26) \\ 61.21 \pm (0.14) \end{array}$	$\begin{array}{c} 0.01 \pm (0.00) \\ 6.56 \pm (2.79) \\ \underline{10.96} \pm (0.26) \\ 12.03 \pm (1.02) \end{array}$	$\begin{array}{c} 84.35 \pm (0.34) \\ 58.37 \pm (2.39) \\ 37.73 \pm (0.32) \\ 26.77 \pm (3.25) \end{array}$
AT PGD-10		$ 24.77 \pm (0.26) $	$59.64 \pm (0.46)$	$14.42\pm(0.00)$	$34.90 \pm (0.61)$
GAT GAT+ELLE-A N-FGSM N-FGSM+ELLE-A	NR NR	$\begin{array}{c} 0.95 \pm (0.09) \\ 17.30 \pm (1.20) \\ \underline{20.54} \pm (0.18) \\ \textbf{21.28} \pm (0.07) \end{array}$	$\begin{array}{l} 84.09 \pm (0.10) \\ 64.27 \pm (3.56) \\ 63.83 \pm (1.24) \\ 64.25 \pm (0.20) \end{array}$	$\begin{array}{c} 0.00 \pm (0.00) \\ 6.74 \pm (2.08) \\ 3.31 \pm (2.58) \\ \textbf{12.22} \pm (0.25) \end{array}$	$\begin{array}{c} 89.04 \pm (0.28) \\ 42.04 \pm (10.52) \\ 27.96 \pm (9.36) \\ 33.50 \pm (0.14) \end{array}$
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CIFAR10 Short schedule

WRN in CIFAR10 at $\epsilon = \frac{26}{255}$

 Plugging our regularization term stabilizes and improves the performance of popular single-step AT methods.

Sriramanan et al., Guided adversarial attack for evaluating and enhancing adversarial defenses NeurIPS, 2020.

de Jorge et al., Make some noise: Reliable and efficient single-step adversarial training NeurIPS, 2022.



Thanks

Thanks for your attention!

contact: elias.abadrocamora@epfl.ch

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