# Weaker MVI Condition Extragradient Methods with Multi-Step Exploration

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Yifeng Fan, Yongqiang Li, Bo Chen Weaker MVI Condition

# Min-max optimization

### Problem setting

 $\min_{\boldsymbol{x}} \max_{\boldsymbol{y}} f(\boldsymbol{x}, \boldsymbol{y})$ 

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• Saddle gradient operator

$$Fz = \begin{bmatrix} \nabla_x f(x, y) \\ -\nabla_y f(x, y) \end{bmatrix}$$
, where  $z = \begin{bmatrix} x \\ y \end{bmatrix}$ 

$$\min_{\boldsymbol{x}} \max_{\boldsymbol{y}} f(\boldsymbol{x}, \boldsymbol{y})$$

• Saddle gradient operator

$$F \boldsymbol{z} = \begin{bmatrix} \nabla_{\boldsymbol{x}} f(\boldsymbol{x}, \boldsymbol{y}) \\ -\nabla_{\boldsymbol{y}} f(\boldsymbol{x}, \boldsymbol{y}) \end{bmatrix}$$
, where  $\boldsymbol{z} = \begin{bmatrix} \boldsymbol{x} \\ \boldsymbol{y} \end{bmatrix}$ 

• Scenaries: GANs training, adversarial training, robust learning

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• Saddle gradient operator

$$F m{z} = egin{bmatrix} 
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, where  $m{z} = egin{bmatrix} m{x} \\ m{y} \end{bmatrix}$ 

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- Assumptions on F

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• *L*-Lipschitz 
$$||F\boldsymbol{u} - F\boldsymbol{v}|| \le L||\boldsymbol{u} - \boldsymbol{v}||$$

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  - *L*-Lipschitz  $||F\boldsymbol{u} F\boldsymbol{v}|| \le L||\boldsymbol{u} \boldsymbol{v}||$ • weak MVI condition  $\langle F\boldsymbol{z}, \boldsymbol{z} - \boldsymbol{z}^* \rangle \ge \rho ||F\boldsymbol{z}||^2$

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Scenaries: GANs training, adversarial training, robust learning

- F may not be monotone
- Assumptions on F
  - $\|F\mathbf{u} F\mathbf{v}\| \leq L \|\mathbf{u} \mathbf{v}\|$   $|F\mathbf{u} F\mathbf{v}\| \leq c \|\mathbf{u} \mathbf{v}\|$   $|F\mathbf{u} \mathbf{v}| \leq c \|\mathbf{u} \mathbf{v}\|$ • *L*-Lipschitz
  - weak MVI condition

on 
$$\langle F \boldsymbol{z}, \boldsymbol{z} - \boldsymbol{z}^* \rangle \geq \rho \| F$$

• If  $\rho = 0$ , MVI (star-monotonicity)

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- F may not be monotone
- Assumptions on F
  - L-Lipschitz  $\|F\boldsymbol{u} F\boldsymbol{v}\| \leq L \|\boldsymbol{u} \boldsymbol{v}\|$
  - weak MVI condition  $\langle Fz, z-z \rangle$

$$\langle Fz, z - z^* \rangle \ge \rho \|Fz\|^2$$

- If  $\rho = 0$ , MVI (star-monotonicity)
- Weak MVI allows  $\rho < 0$

# Weak MVI Condition

Weak MVI Condition (star-cohypomonotonicity)

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- Minty variational inequality  $\langle Fz, z z^* \rangle \ge 0$
- monotone

$$\langle F\boldsymbol{z} - F\boldsymbol{v}, \boldsymbol{z} - \boldsymbol{v} \rangle \geq 0$$



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- Minty variational inequality  $\langle F \boldsymbol{z}, \boldsymbol{z} \boldsymbol{z}^* \rangle \ge 0$
- monotone  $\langle F\boldsymbol{z} - F\boldsymbol{v}, \boldsymbol{z} - \boldsymbol{v} \rangle \geq 0$
- $\rho$ -comonotone  $\langle F \mathbf{z} - F \mathbf{v}, \mathbf{z} - \mathbf{v} \rangle \geq \rho \|F \mathbf{z} - F \mathbf{v}\|^2$



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- monotone  $\langle F \boldsymbol{z} F \boldsymbol{v}, \boldsymbol{z} \boldsymbol{v} \rangle \geq 0$
- $\rho$ -comonotone  $\langle F \boldsymbol{z} - F \boldsymbol{v}, \boldsymbol{z} - \boldsymbol{v} \rangle \geq \rho \|F \boldsymbol{z} - F \boldsymbol{v}\|^2$

• star: 
$$\mathbf{v} = \mathbf{z}^*$$
, hypo:  $\rho < 0$ 



• Weak MVI: negative gradient might point away from zero



weak MVI with different parameters

# Existing Works

• Extragradient (MVI)

• same stepsizes

$$\bar{\mathbf{z}}^{k} = \mathbf{z}^{k} - \alpha_{k} F \mathbf{z}^{k}$$
$$\mathbf{z}^{k+1} = \mathbf{z}^{k} - \alpha_{k} F \bar{\mathbf{z}}^{k}$$

• Extragradient (MVI)

• same stepsizes

$$\bar{\boldsymbol{z}}^{k} = \boldsymbol{z}^{k} - \alpha_{k} \boldsymbol{F} \boldsymbol{z}^{k}$$
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• EG+/AdaptiveEG+ (weak MVI,  $\rho > -1/2L$ )

• larger extrapolation stepsize  $\gamma_k$ 

$$\bar{z}^{k} = z^{k} - \gamma_{k}Fz^{k}$$
$$z^{k+1} = z^{k} - \alpha_{k}F\bar{z}^{k}$$

• First known first-order algorithm that converges for weak MVI problems with  $\rho < -1/2L$ . We provide convergence guarantee for  $\rho > -0.632/L$ . • First known first-order algorithm that converges for weak MVI problems with  $\rho < -1/2L$ . We provide convergence guarantee for  $\rho > -0.632/L$ .

• Adaptive method effectively resolves problems with limit cycles.

### 2-step Extragradient

$$\mathbf{z}_{1}^{k} = \mathbf{z}^{k} - \gamma_{k,1} F \mathbf{z}^{k}$$
$$\bar{\mathbf{z}}^{k} = \mathbf{z}_{1}^{k} - \gamma_{k,2} F \mathbf{z}_{1}^{k}$$
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#### 2-step Extragradient

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$$z^{k+1} = z^k - \alpha_k F \bar{z}^k$$

Take stepsizes  $\gamma_{k,1} = \delta_1/L$ ,  $\gamma_{k,2} = \delta_2/L$ 

$$\rho > \begin{cases} -\frac{1}{L} \left[ 1 - \frac{1}{(1+\delta_1)(1+\delta_2)} \right] & \text{if } \delta_1 + \delta_2 \le 1 \\ -\frac{1}{L} \left[ \frac{\delta_1(1-\delta_1^2 - \delta_2^2)}{2(1-\delta_1^2)(1-\delta_2^2)} + \frac{\delta_2}{1+\delta_2} \right] & \text{if } \delta_1 + \delta_2 > 1 \end{cases}$$

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Relation between the upper bound of  $-\rho L$  and  $\delta_1$ ,  $\delta_2$ 

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• 
$$\delta_1=\delta_2=1/2,\ \rho>-5/9L$$



Relation between the upper bound of  $-\rho L$  and  $\delta_1$ ,  $\delta_2$ 

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• 
$$\delta_1 = \delta_2 = 1/2, \ \rho > -5/9L$$

• 
$$\delta_1 \approx 0.52212, \ \delta_2 \approx 0.644793, \ \rho > -0.5834/L$$



Relation between the upper bound of  $-\rho L$  and  $\delta_1$ ,  $\delta_2$ 

#### *n*-step Extragradient

$$z_1^k = z^k - \gamma_{k,1}Fz^k$$

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$$\vdots$$

$$\bar{z}^k = z_{n-1}^k - \gamma_{k,n-1}Fz_{n-1}^k$$

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• Take 
$$\gamma_{k,i} = \delta_i / L, i \in [n]$$
. If  $\sum_{i=1}^n \delta_i \le 1$ ,  
 $\rho > -\frac{1}{L} \left( 1 - \prod_{i=1}^n \frac{1}{1 + \delta_i} \right)$ 

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• Take  $\gamma_{k,i} = \delta_i / L, i \in [n]$ . If  $\sum_{i=1}^n \delta_i \leq 1$ ,

$$\rho > -\frac{1}{L} \left( 1 - \prod_{i=1}^{n} \frac{1}{1+\delta_i} \right)$$

• Convergence guarantee for  $\rho > -(1-1/e)/L \approx -0.632/L$  with invariant stepsizes  $\gamma_{k,i} = 1/nL$ ,  $i \in [n]$  and large enough n

# Introducing Adaptive Exploration

#### • Perspective of projection



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• MDEG: Max Distance Extragradient

# Introducing Adaptive Exploration

#### Perspective of projection



- MDEG: Max Distance Extragradient
- Sub-iteration stops when projection distance decreases

### Examples

• *n*-step EG converges for  $\rho < -1/2L$ .



(b)

# Examples

- n-step EG converges for  $\rho < -{\rm 1/2L}.$
- MDEG converges break out of the limit cycle and converges to the stationary point.



(c)

# Examples

- n-step EG converges for  $\rho < -{\rm 1/2L}.$
- MDEG converges break out of the limit cycle and converges to the stationary point.
- MDEG bypasses the highly nonmonotonic regions with local  $\rho L \approx -3.04076$  and converges to the stationary point.



# Thank you!