## CAMBranch: Contrastive Learning with Augmented MILPs for Branching

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Our Solution: Augmented MILPs

| $\min _{x} \boldsymbol{c}^{\mathrm{T}} \boldsymbol{x}$ |  | $\min _{\hat{x}} c^{\mathrm{T}} \hat{\boldsymbol{x}}-c^{\mathrm{T}} s$ |  | $\min _{\hat{x}} \boldsymbol{c}^{\mathrm{T}} \hat{\boldsymbol{x}}-\boldsymbol{c}^{\mathrm{T}} \boldsymbol{s}$ |
| :---: | :---: | :---: | :---: | :---: |
| s.t. $\boldsymbol{A} \boldsymbol{x} \leqslant \boldsymbol{b}$ | $\hat{x}=x+s$ | s.t. $\boldsymbol{A} \hat{\boldsymbol{x}} \leqslant \boldsymbol{A s}+\boldsymbol{b}$ | $\hat{b}=\boldsymbol{A} s+\boldsymbol{b}, ~ \hat{l}=l+s$ | s.t. $\boldsymbol{A} \hat{\boldsymbol{x}} \leqslant \hat{\boldsymbol{b}}$ |
| $l \leqslant x \leqslant u$ | $s_{i} \in \mathbb{Z}$ if $x_{i} \in \mathbb{Z}$ | $l+s \leqslant \hat{x} \leqslant u+s$ | $\hat{u}=u+s$ | $\hat{\imath} \leqslant \hat{x} \leqslant \hat{u}$ |
| $x_{j} \in \mathbb{Z}, \forall j \in \mathcal{I}$ | else $s_{i} \in \mathbb{R}$ | $\hat{x}_{j} \in \mathbb{Z}, \forall j \in \mathcal{I}$ |  | $\hat{x}_{j} \in \mathbb{Z}, \forall j \in \mathcal{I}$ |

## Characteristics of Augmented MILPs (AMILPs)

$>$ Each MILP can generate multiple AMILPs
> Generated AMILPs share identical Variable Selection Decisions to its original MILPs

Generate labeled expert data without solving AMILPs $\approx$

Next, by lemmas and theorems, obtain AMIILP's Bipartite Graph features which will be fed into the GCNN for feature extraction.

Leveraging Contrastive Learning between MILPs and AMILPs


Original Bipartite Graph $\quad\left(\mathcal{C}_{\text {ori }}, \mathbf{C}_{\text {ori }}, \mathbf{E}_{\text {ori }}, \mathbf{V}_{\text {ori }}\right)$ Augmented Bipartite Graph $\left(\mathcal{G}_{\text {aug }}, \mathbf{C}_{\text {aug }}, \mathbf{E}_{\text {aug }}, \mathbf{V}_{\text {aug }}\right)$

[^0]$g_{\text {ori }}=\operatorname{MLP}\left(\right.$ Concat $\left.\left(C_{\text {ori }}^{c}, v_{\text {ori }}^{c}\right)\right)$
$g_{\text {aug }}=\operatorname{MLP}\left(\right.$ Concat $\left.\left(C_{\text {aug }}^{c}, v_{\text {augs }}^{c}\right)\right)$
Variable and Constraint Node

Loss function

| 1. Imitation Learning | $\mathcal{L}_{\text {sup }}=-\frac{1}{N} \sum_{\left(\mathbf{s}_{\left.\mathbf{i}, \mathbf{a}_{i}^{*}\right) \in D} \log \pi_{\theta}\left(\mathbf{a}_{i}^{*} \mid \mathbf{s}_{i}\right)\right.}$ |
| :---: | :---: |
| 2. Contrastive Learning |  |
| 3. Consistency Loss | $\mathcal{L}^{(\mathrm{Aux})}=\sum_{i=1}^{n_{\text {bacth }}}\left(\boldsymbol{P}_{\text {ori }}(i)-\boldsymbol{P}_{\text {aug }}(i)\right)^{2}$ |

The final loss function is $\mathcal{L}=\mathcal{L}^{(\text {sup })}+\lambda_{1} \mathcal{L}^{(\text {infoNCE })}+\lambda_{2} \mathcal{L}^{\text {(Aux) }}$

Experimental Results

| Model | Time | Easy Wins | Nodes | Time | $\underset{\substack{\text { Medium } \\ \text { Wins }}}{ }$ | Nodes | Time | $\begin{aligned} & \begin{array}{l} \text { Hard } \\ \text { Wins } \end{array} \end{aligned}$ | Nodes |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FSB | 4.71 | 0/100 | 10 | 97.6 | 0/100 | 90 | 1396.62 | 0/64 | 381 |
| RPb | 2.61 | 1/100 | 21 | 19.68 | 2/100 | 713 | 142.52 | 29/100 | 8971 |
| GCNN | 1.96 | 43/100 | 87 | 11.30 | 74/100 | 695 | 158.81 | $19 / 94$ | 12089 |
| GCNN (10\%) | 1.99 | 44/100 | 102 | 12.38 | 16/100 | 787 | 144.40 | 10/100 | 10031 |
| CAMBranch (10\%) | 2.03 | 12/100 | 91 | 12.68 | 8/100 | 758 | 131.79 | 42/100 | 9074 |
| Combinatorial Auction |  |  |  |  |  |  |  |  |  |
| FSB | 34.94 | 0/100 | 54 | 242.51 | 0/100 | 114 | 995.40 | 0/82 | 84 |
| RPb | 30.63 | 9/100 | 79 | 177.25 | 2/100 | 196 | 830.90 | $2 / 93$ | 178 |
| GCNN | 24.72 | 25/100 | 169 | 145.17 | 13/100 | 405 | 680.78 | 5/95 | 449 |
| GCNN (10\%) | 26.30 | 15/100 | 180 | 124.49 | 48/100 | 406 | 672.88 | 11195 | 423 |
| CAMBranch (10\%) | 24.91 | 50/100 | 183 | 124.36 | 37/100 | 390 | 470.83 | 77795 | 428 |
| Capacitated Facility Location |  |  |  |  |  |  |  |  |  |
| FSB | 28.85 | 10/100 | 19 | 1219.15 | 0/62 | 81 | 3600.00 |  |  |
| RPb | 10.73 | 11/100 | 78 | 133.30 | 5/100 | 2917 | 965.67 | 10/40 | 17019 |
| GCNN | 7.17 | 11/100 | 90 | 164.51 | $4 / 99$ | 5041 | 1020.58 | 0/17 | 21925 |
| GCNN (10\%) | 7.18 | 26/100 | 103 | 122.65 | 8/89 | 3711 | 695.96 | 2/20 | 17034 |
| CAMBranch (10\%) | 6.92 | 42/100 | 90 | 61.51 | 83/100 | 1479 | 496.86 | 33/40 | 10828 |

Our CAMBranch, trained with only $10 \%$ of the full dataset outperforms GCNN trained with full data.

Table 3: The results of evaluating the instance-solving performance for the Combinatorial Auction problem by utilizing the complete training dataset. Bold numbers denote the best resulis. A. $\begin{array}{lll}\text { Easy } & \text { Medium } & \text { Hard }\end{array}$

| Model |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Time | Wins | Nodes | Time | Wins | Nodes | Time | Wins | Nodes |
| GCNN (10\%) | 1.99 | 2/100 | 102 | 12.38 | 3/100 | 787 | 144.40 | 2/10 | 10031 |
| GCNN (100\%) | 1.96 | 4/100 | 87 | 11.30 | 7/100 | 695 | 158.81 | 4/9 | 12089 |
| CAMBranch (10\%) | 2.03 | 1/100 | 91 | 12.68 | 2/100 | 758 | 131.79 | 11/100 | 9074 |
| CAMBranch (100\%) | 1.73 | 93/100 | 88 | 10.04 | 88/100 | 690 | 109.96 | 83/100 | 8260 |

CAMBranch is not limited to data-limited scenarios, which also serves a valuable tool for data argumentation with full dataset.


[^0]:    $c_{\text {ori }}^{c}=\operatorname{MLP}\left(\right.$ Concat (MaxPool( $\mathbf{C o r}_{\text {or }}^{\prime}$ ) , MeanPool( $\left(\right.$ orir $\left.\left._{\prime}^{\prime}\right)\right)$ ) $v_{\text {ori }}^{c}=\operatorname{MLP}\left(\right.$ Concat(MaxPool $\left(V_{\text {ori }}^{\prime}\right)$ MeanPool $\left.\left.\left(V_{\text {ori }}^{\prime}\right)\right)\right)$ $c_{\text {aug }}^{c}=\operatorname{MLP}\left(\right.$ Concat (MaxPool( $\left(\right.$ Caug $\left._{\text {ang }}^{\prime}\right)$, MeanPool $\left(\right.$ Caug $\left.\left._{\text {aug }}^{\prime}\right)\right)$ $v_{\text {aug }}^{c}=\operatorname{MLP}\left(\right.$ Concat(MaxPool $\left(\right.$ Vaug $\left._{\text {aug }}^{\prime}\right)$ MeanPool ( augg $\left.\left._{\prime}^{\prime}\right)\right)$ Variable and Constraint Node Pooling

