

Local Graph Clustering with Noisy Labels

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Local graph clustering

Setting: Given a graph $G = (V, E)$,
and a seed node $s \in V$

Goal: Find a good cluster that contains
 s , without necessarily exploring the
whole graph

Random walk [Spielman & Teng 2013]

PageRank [ACL 2006]

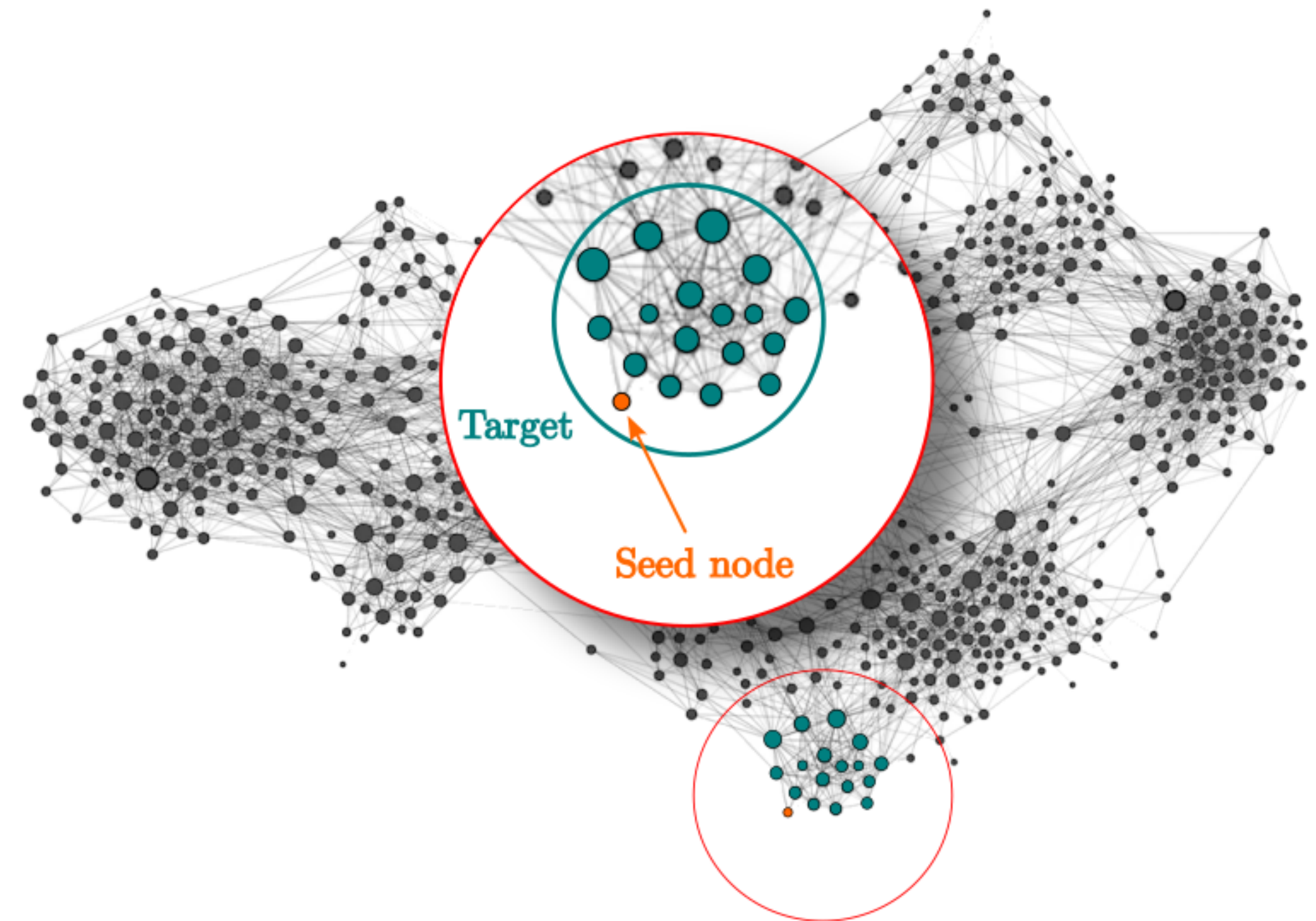
Heat kernel [Chung 2007]

Evolving sets [Andersen & Peres 2008]

Capacity releasing diffusion [Di *et al* 2017]

Flow diffusion [Fountoulakis *et al* 2020]

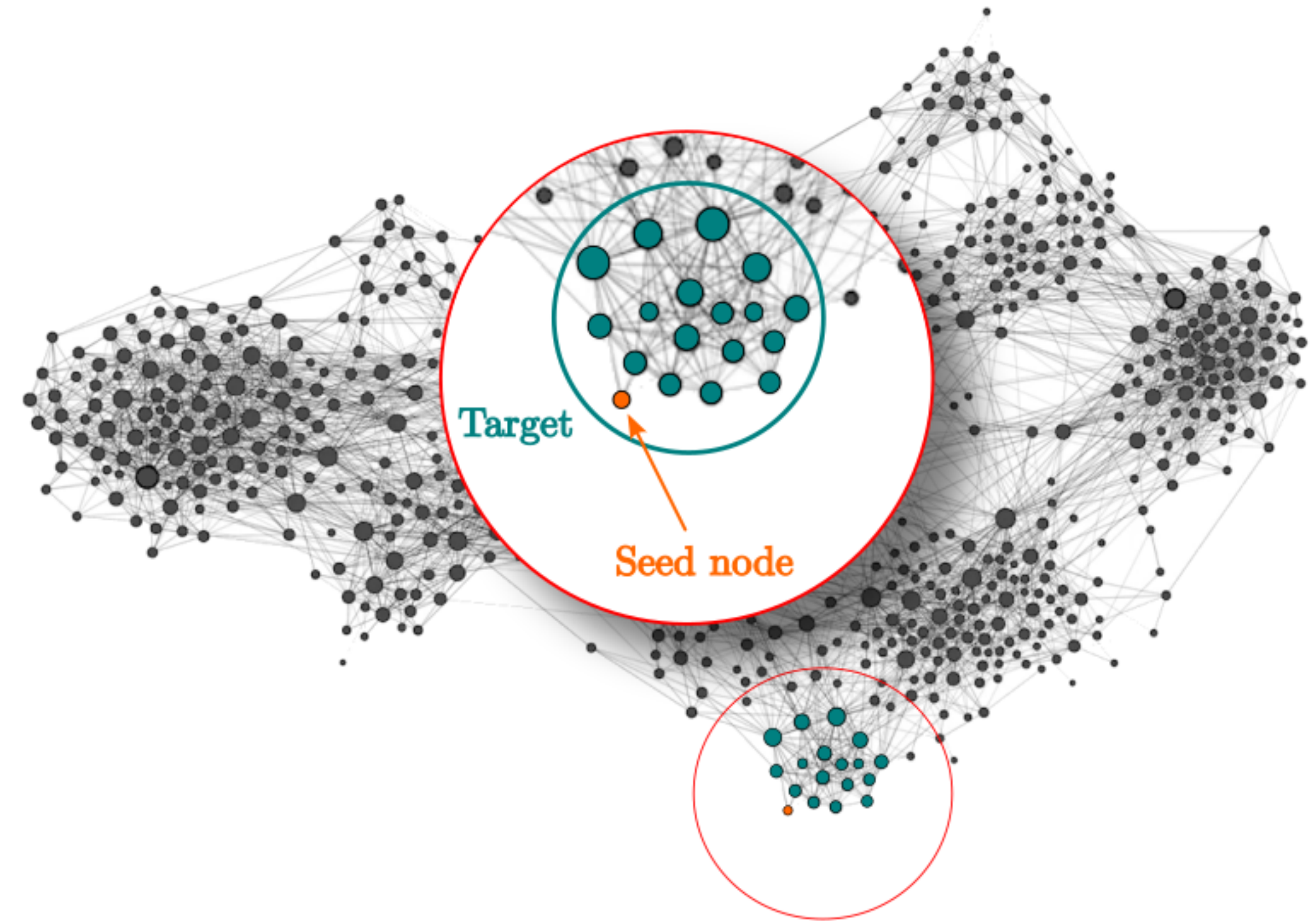
and many more...



Local graph clustering

Setting (this work): Given a graph $G = (V, E)$ with noisy node labels, and a seed node $s \in V$

Goal: Find a good cluster that contains s , without necessarily exploring the whole graph



Contributions

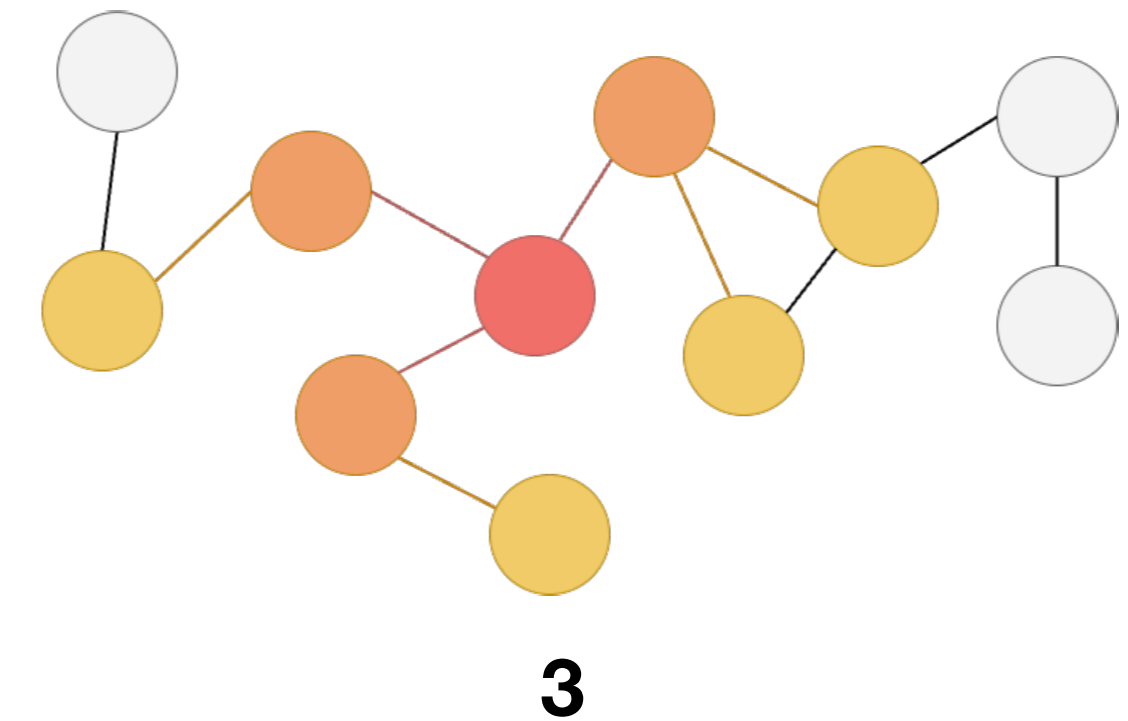
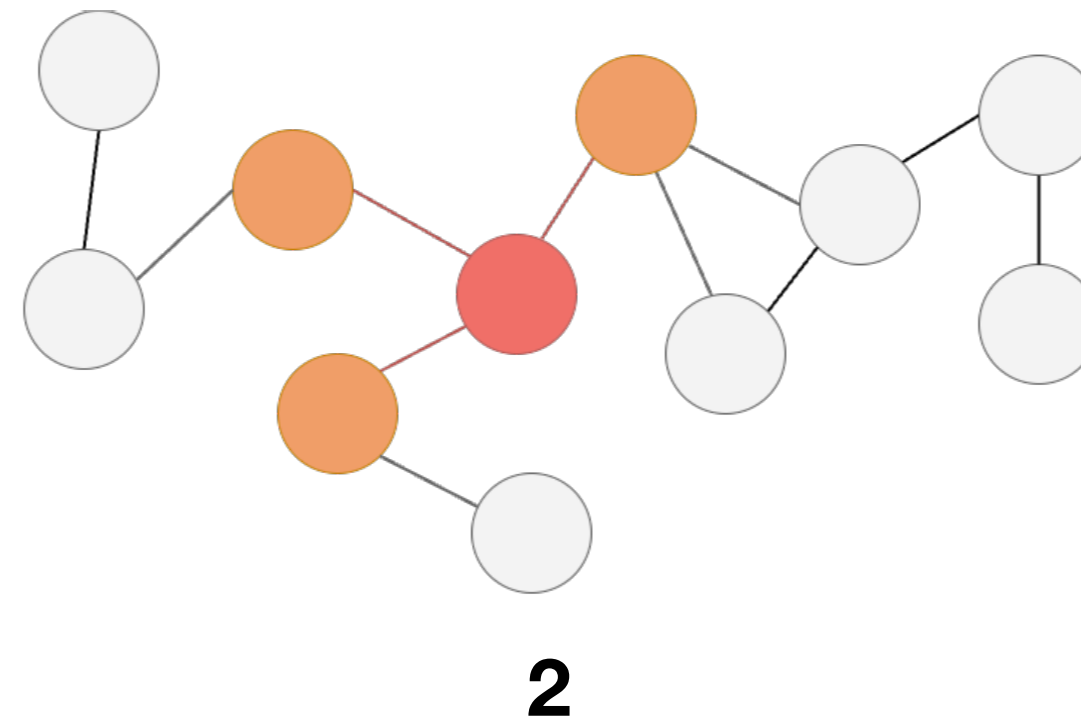
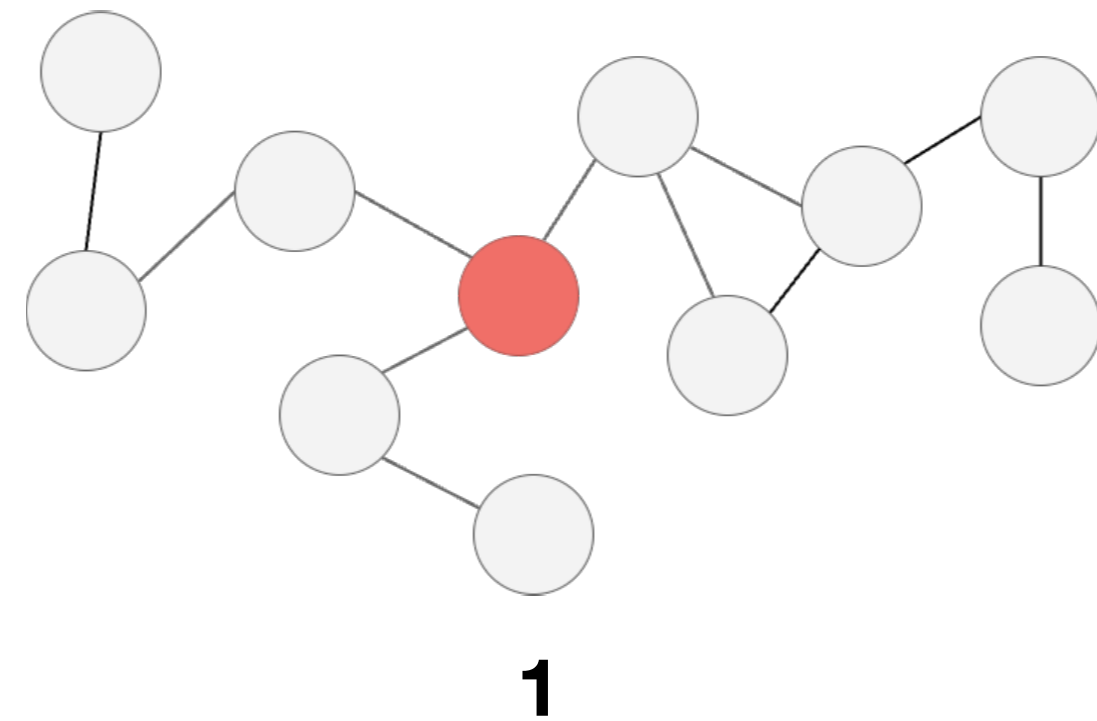
- A simple algorithm integrates [noisy node labels](#) into local graph clustering, demonstrating their usefulness, particularly when the graph structure is poor.
- We provide a [theoretical analysis](#) on the recovery of an unknown target cluster in a [local random graph model](#) with additional noisy node labels
- We empirically verify the results through extensive [experiments over both synthetic and real-world data](#)

Noisy node labels

- Each node receives a **binary label** indicating its membership: 1 if it belongs to the target cluster and 0 if it does not. A **fraction of the labels is then flipped** to introduce label noise
- From a practical point of view, **noisy labels can be the result of an imperfect classifier** that predicts cluster affiliation based on node attributes
 - This allows us work with text, image, audio, etc.
- By abstracting all sources of information as noisy labels, we can theoretically study the benefit of incorporating additional information without explicit assumptions on node attributes

Local graph diffusion

- Generic process to spread mass from a seed node to nearby nodes via edges in the graph
- Mass tends to spread within well-connected clusters



Local graph clustering

- **Input:** Graph $G = (V, E)$, seed node $s \in V$
- **Algorithm** (informal):
 - Run local graph diffusion in G starting from s
 - Check where and how the mass spread within G around s
 - Obtain an output cluster (by applying rounding/post-processing)

Local graph clustering with noisy labels

- **Input:** Graph $G = (V, E)$, seed node $s \in V$, noisy node labels $\tilde{y}_i \in \{0,1\}$, $\forall i$

- **Algorithm** (informal):

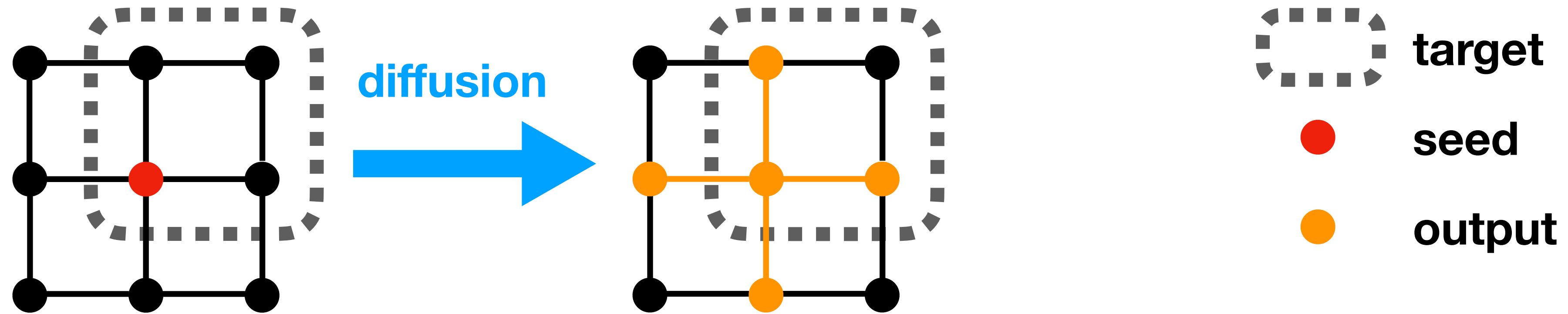
- Define weighted graph $G' = (V, E, w)$ with edge weight

$$w_{ij} = \begin{cases} 1 & \text{if } \tilde{y}_i = \tilde{y}_j, \\ \varepsilon & \text{if } \tilde{y}_i \neq \tilde{y}_j, \quad \varepsilon \in [0,1) \end{cases}$$

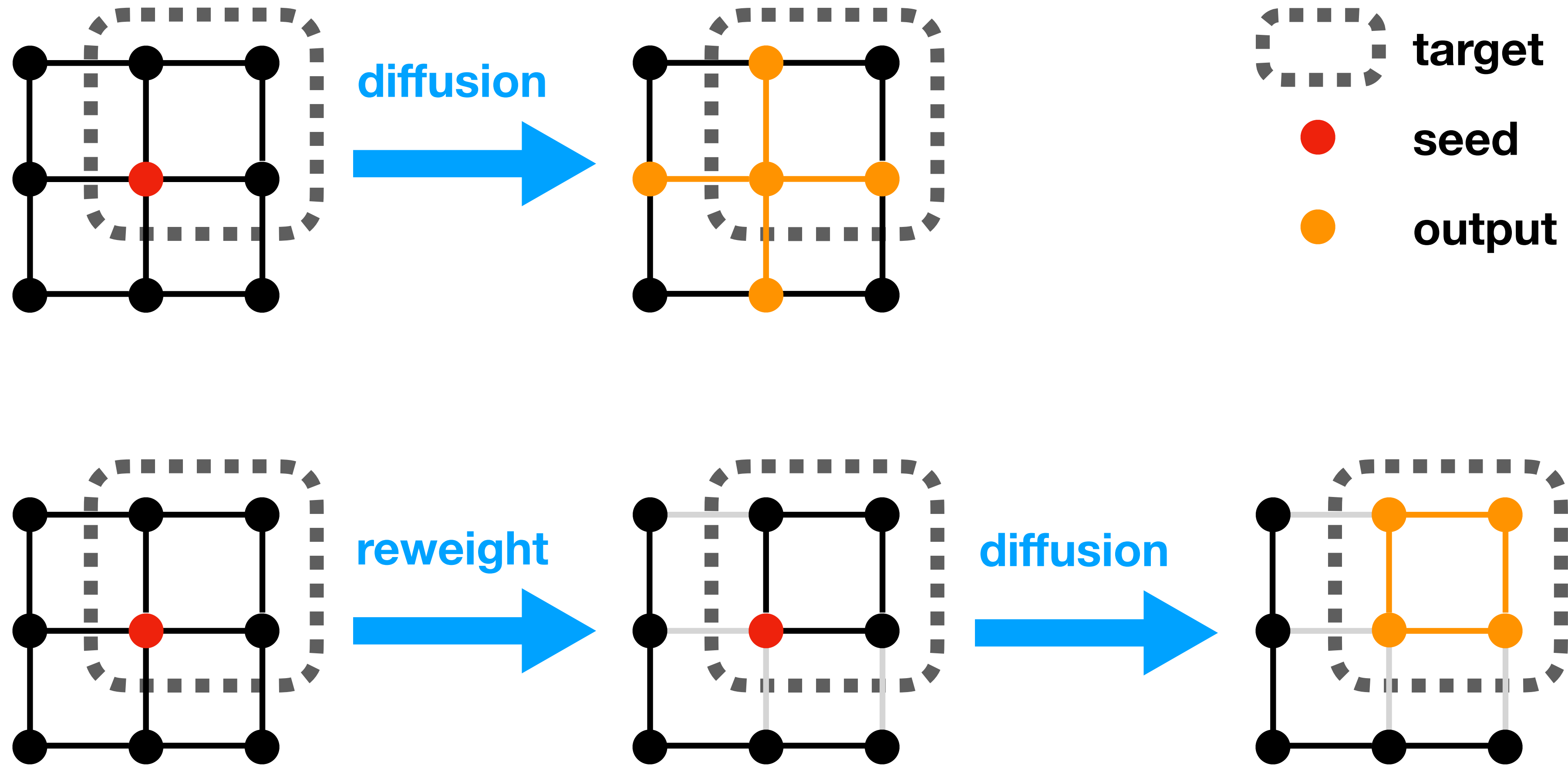
- Run **weighted** local graph diffusion in G' starting from s
- Check where and how the mass spread within G' around s
- Obtain an output cluster (by applying rounding/post-processing)

How does reweighing edges help exactly?

Example: how edge weights can help



Example: how edge weights can help



Local random model with noisy labels

Local random graph: Given a set of nodes V and a target cluster $K \subset V$

- Draw an edge (i, j) with probability p if $i \in K, j \in K$
- Draw an edge (i, j) with probability q if $i \in K, j \notin K$
- Edges (i, j) where $i, j \notin K$ can be arbitrary
- **Structural signal** $\gamma = (p(|K| - 1)) / (q(n - |K|))$

Noisy labels: Every node $i \in V$ is assigned a binary label $\tilde{y}_i \in \{0, 1\}$

- $\tilde{Y}_1 = \{i \in V : \tilde{y}_i = 1\}$ and $\tilde{Y}_0 = \{i \in V : \tilde{y}_i = 0\}$
- **Label accuracy** $a_1 = |\tilde{Y}_1 \cap K| / |K|$ and $a_0 = |\tilde{Y}_0 \cap K^C| / |K^C|$

Recovery guarantees

- Suppose that $p = \omega(\sqrt{\log |K|} / \sqrt{|K|})$
- Let S^* be the output of diffusion in the **weighted graph**, then

$$F1(S^*) \gtrsim \left[1 + \frac{(1 - a_1)}{2} + \frac{(1 - a_0)}{2\gamma} + \frac{(1 - a_0)^2}{2a_1\gamma^2} \right]^{-1}$$

- **For comparison:** Let S^\dagger be the output of diffusion in the **original graph**, then

$$F1(S^\dagger) \gtrsim \left[1 + \frac{1}{\gamma} + \frac{1}{2\gamma^2} \right]^{-1}$$

Comparison with SOTA on real data

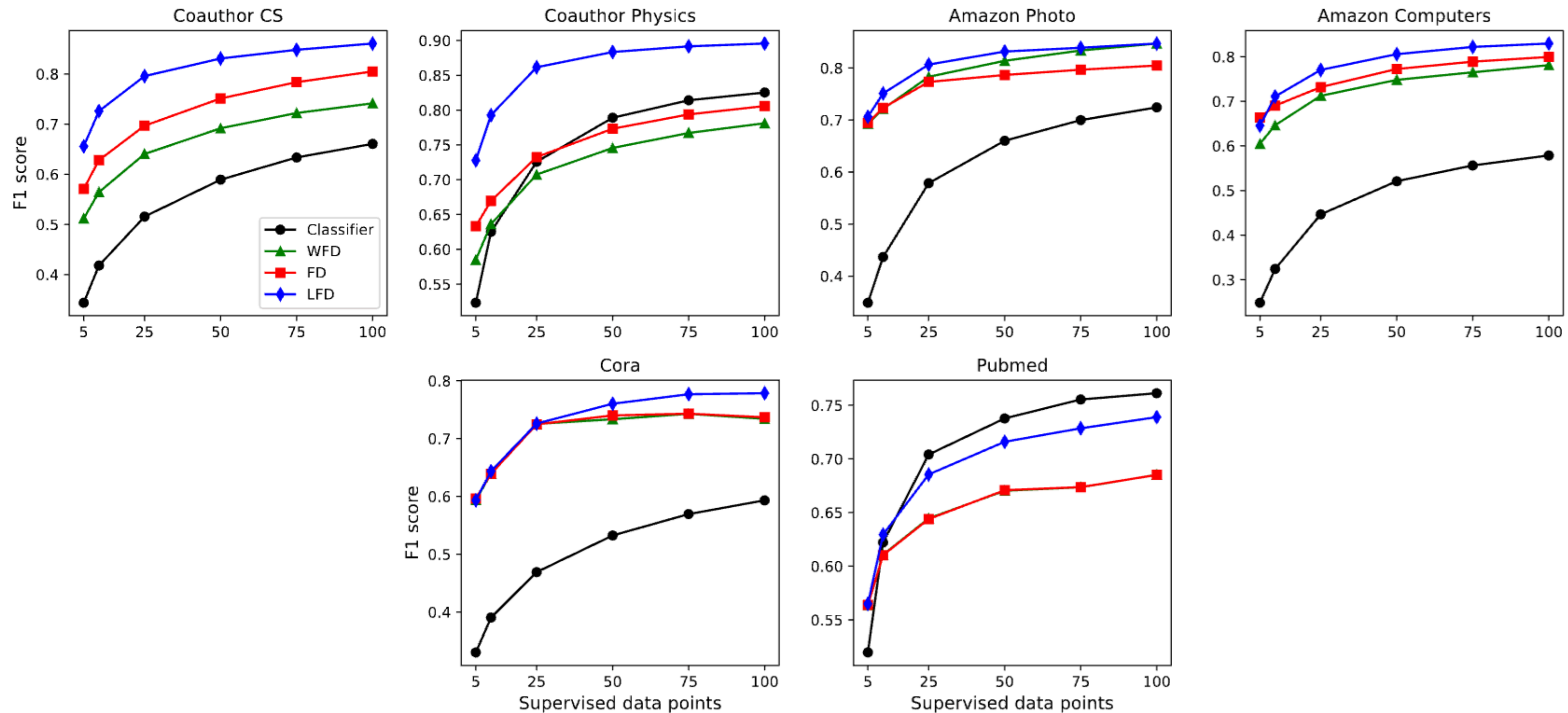


Figure 3: F1 scores for local clustering using Flow Diffusion (FD), Weighted Flow Diffusion (WFD), Label-based Flow Diffusion (LFD), and Logistic Regression (Classifier) with an increasing number of positive and negative ground-truth samples.

Improvement as high as 13% over any other method