### ICLR 2024

# On-Policy Distillation of Language Models: Learning from Self-Generated Mistakes

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### Google DeepMind



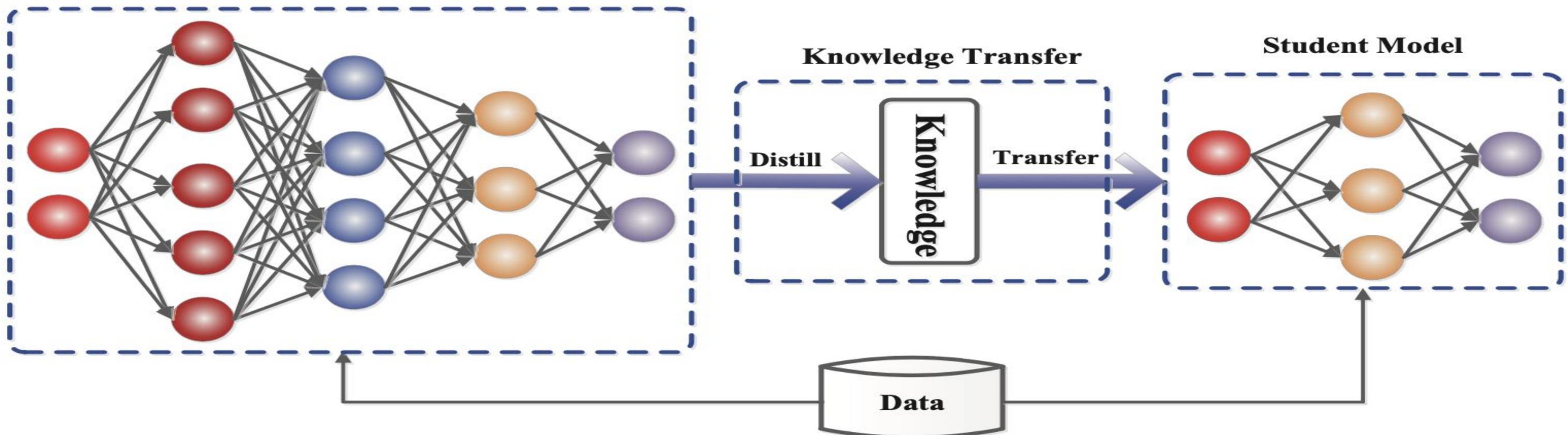
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# **Knowledge Distillation (KD)**

Goal: Transfer knowledge from a teacher model into a smaller student model.

# or memory footprint.

**Teacher Model** 



The generic framework of teacher-student knowledge distillation training. (Image source: <u>Gou et al. 2020</u>)

Why: Deployment of "large" models often limited by their inference cost

## **KD for LLMs: Distribution Mismatch (Exposure Bias)**

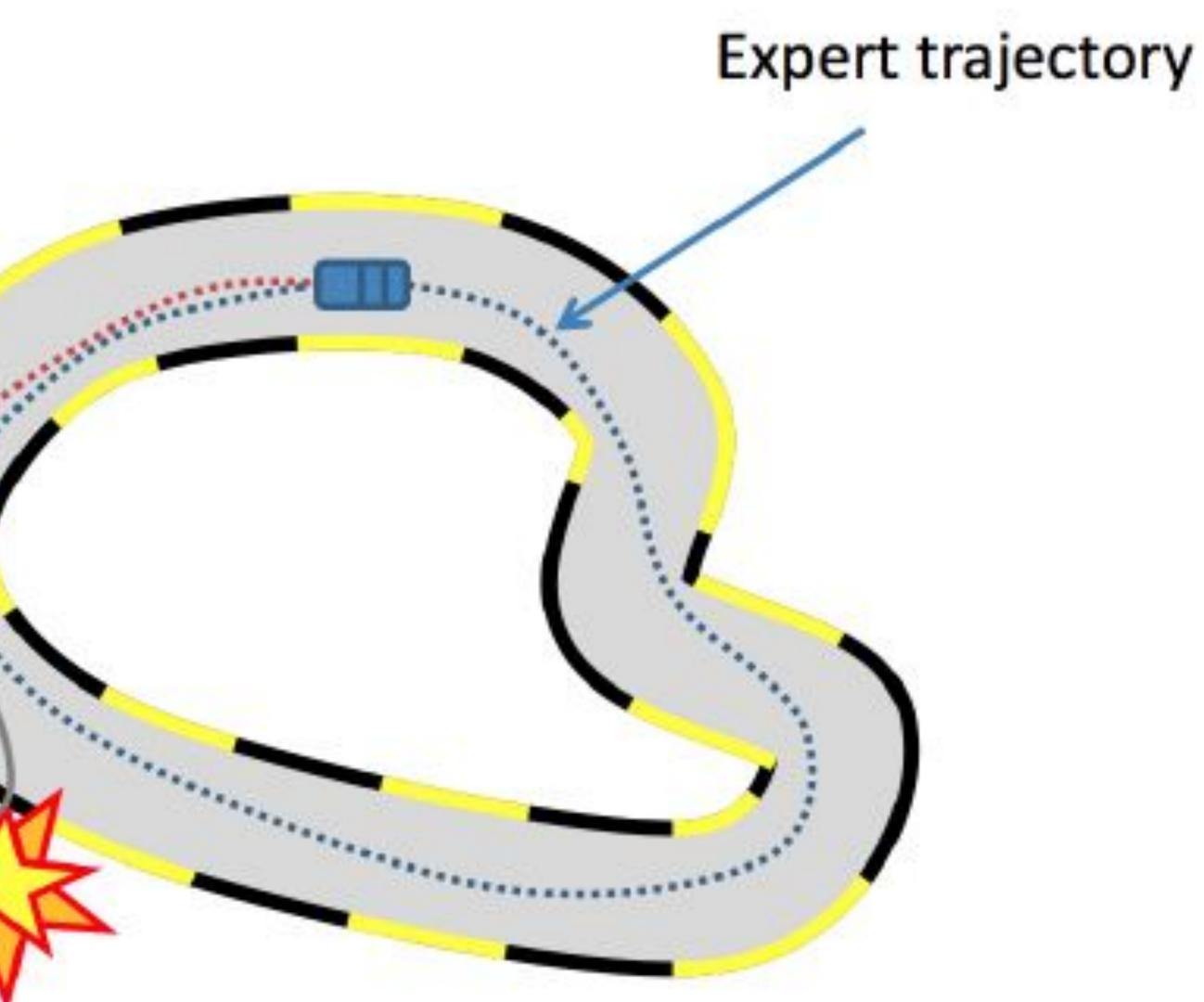
Existing KD methods typically train on a fixed dataset of output sequences.

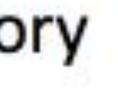
This results in a train-inference mismatch.

See DaggER. A Reduction of Imitation Learning and Structured Prediction to No-Regret Online Learning.

### Learned Policy

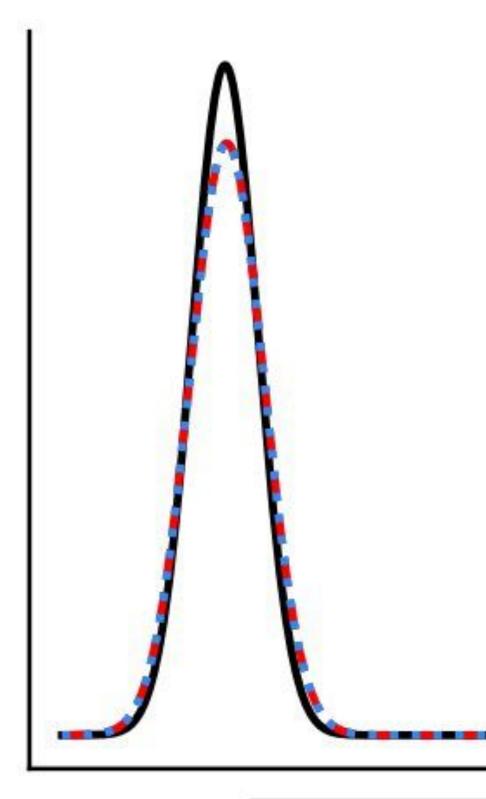
No data on how to recover



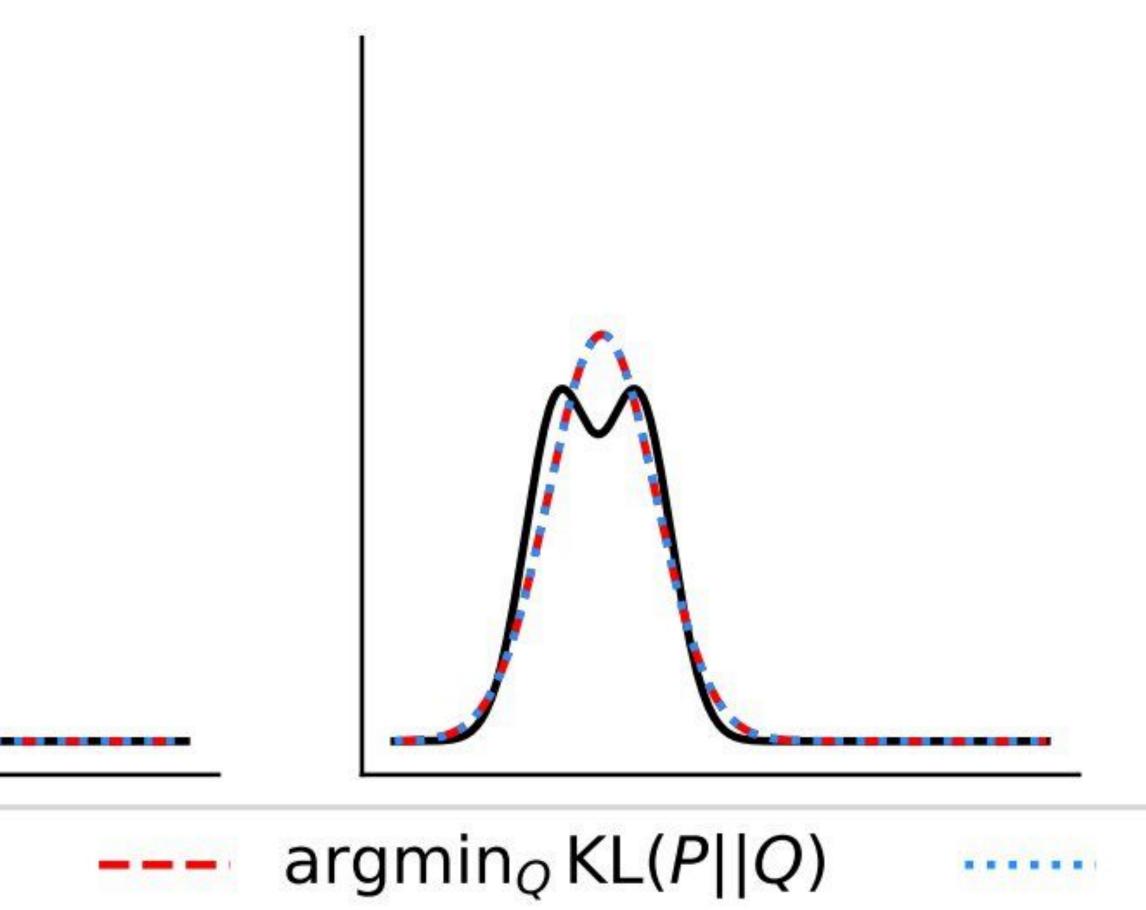


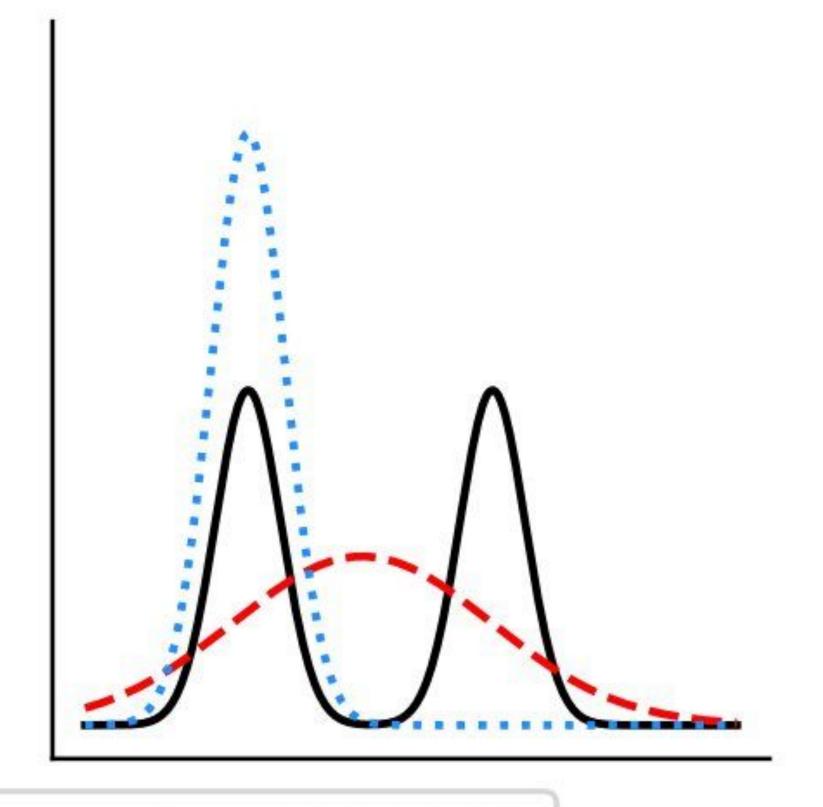
## **KD for LLMs: Model Capacity Mismatch**

If student is often not expressive enough to fit the teacher's distribution, standard KD objective can lead to *unnatural* student-generated samples. Supervised KD = KL(Teacher || Student), which is mode-covering.









 $\operatorname{argmin}_O \operatorname{KL}(Q||P)$ 

1) On-policy Data: Sample self-generated output sequences from the student model.

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3) Supervised Training: Minimize mismatch (e.g., KL-divergence) between student and teacher token-level logits.

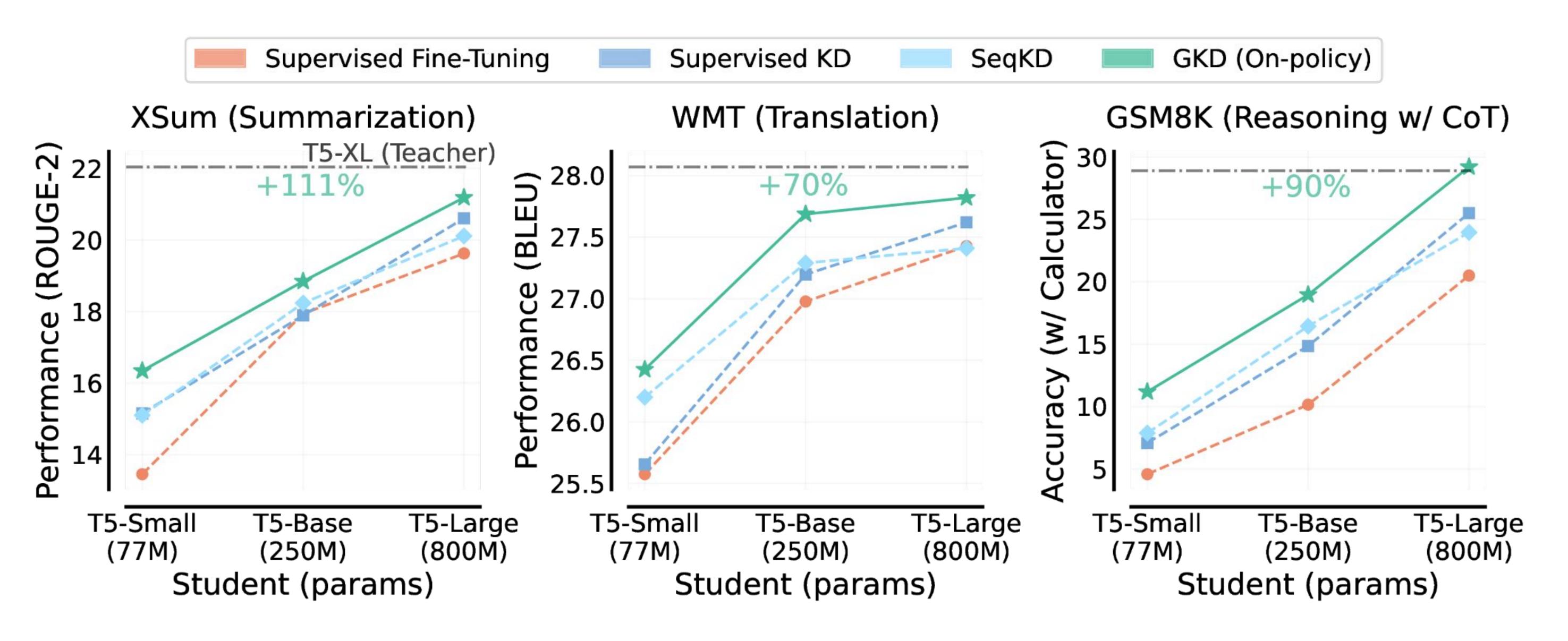
### SFT Results with GKD

Setup:

### One SFT task (eg summarization, translation) • Teacher = big LM fine tuned on the task • Student = small LM fine tuned on the task • Goal = close the performance gap between the two

### SFT Results with GKD

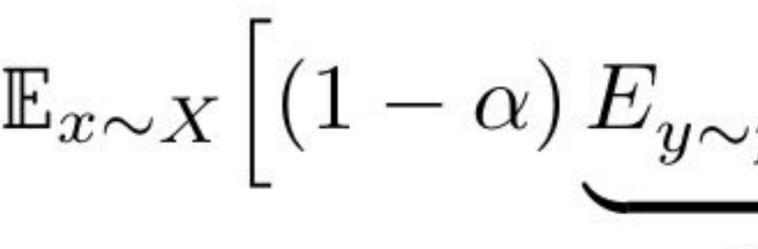
### On-Policy GKD consistently improves over common distillation approaches (SFT, SeqKD, Supervised KD) on different tasks.



On-Policy Distillation of Language Models: Learning from Self-Generated Mistakes. Agarwal\*, Veillard\* et al. ICLR 2024.

### **GKD + RLHF: A Natural Combination**

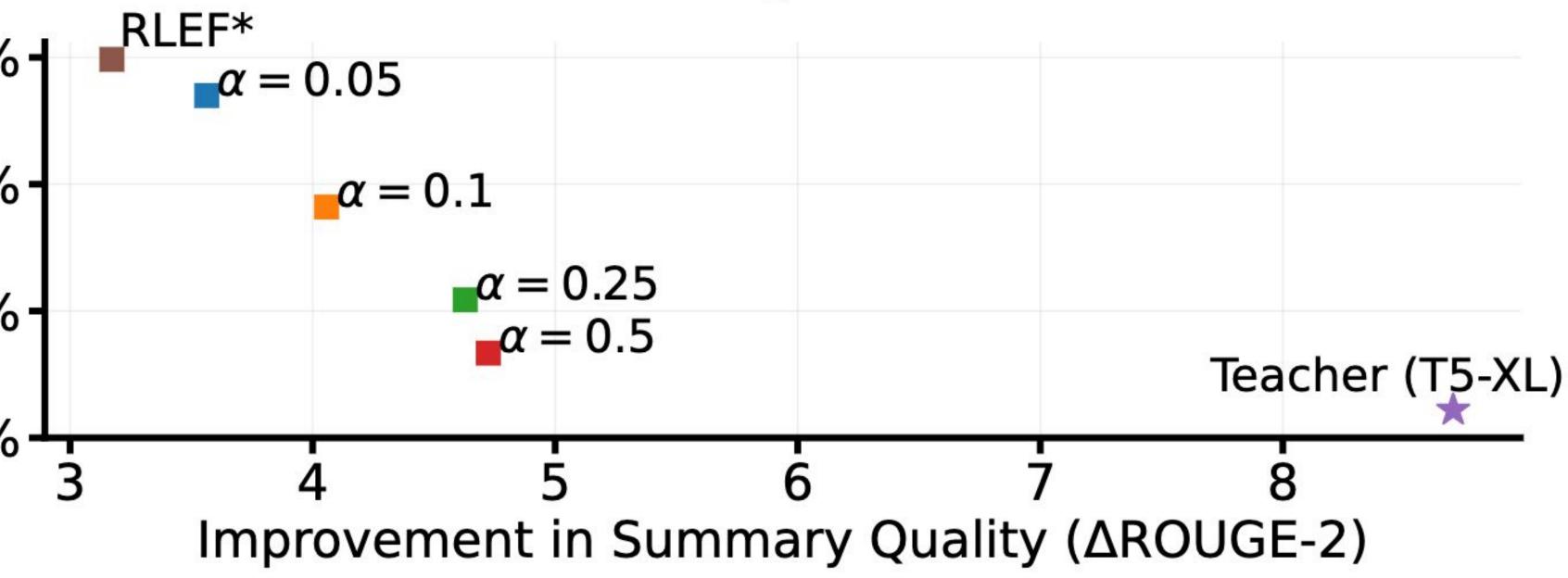
# **GKD + RLHF: A Natural Combination** RL for LLMs is regularized towards the initial policy. Instead, regularize towards the teacher: combine the two objectives !



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 $\mathbb{E}_{x \sim X} \left[ (1 - \alpha) \underbrace{E_{y \sim p_{\mathsf{S}}^{\theta}(\cdot|x)} \left[ r(y) \right]}_{y \sim p_{\mathsf{S}}(\cdot|x)} \left[ \mathcal{D}_{KL} \left( p_{\mathsf{S}}^{\theta}(y|x) \| p_{\mathsf{T}}(y|x) \right) \right] \right]_{\mathsf{T}}$ Generalized On-Policy KD RL objective

RL Fine-Tuning + Distillation



### **Conclusion and thanks!**

• Takeaway message:

• Come visit us at the poster ! Friday, 4:30 pm, Halle B



# • If you distill LLMs for an SFT task, do it on the student distribution