

# Function-space Parameterization of Neural Networks for Sequential Learning

Aidan Scannell\*, Riccardo Mereu\*, Paul Edmund Chang, Ella Tamir, Joni Pajarinen, Arno Solin

*\*Equal contribution*



Scan

For project website+code

# **Motivation:** Combine Benefits of Neural Networks and Gaussian Processes

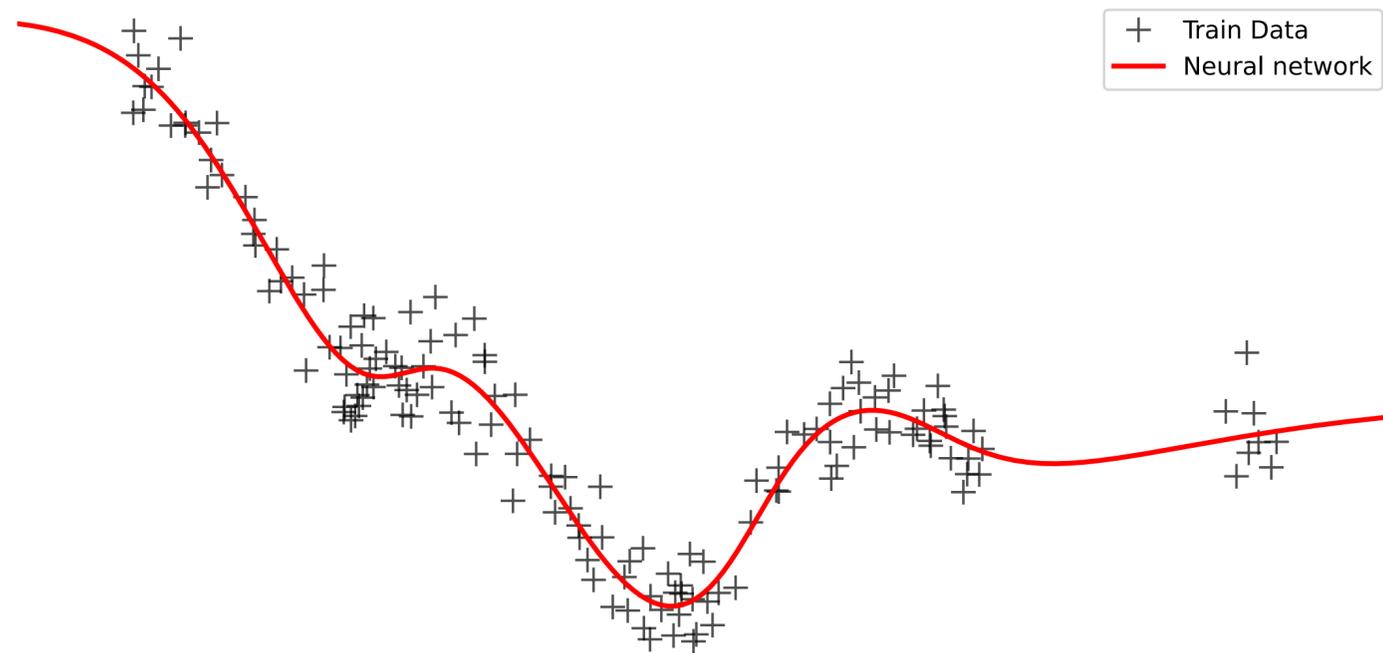
# Uncertainty Quantification

Neural networks lack uncertainty estimates

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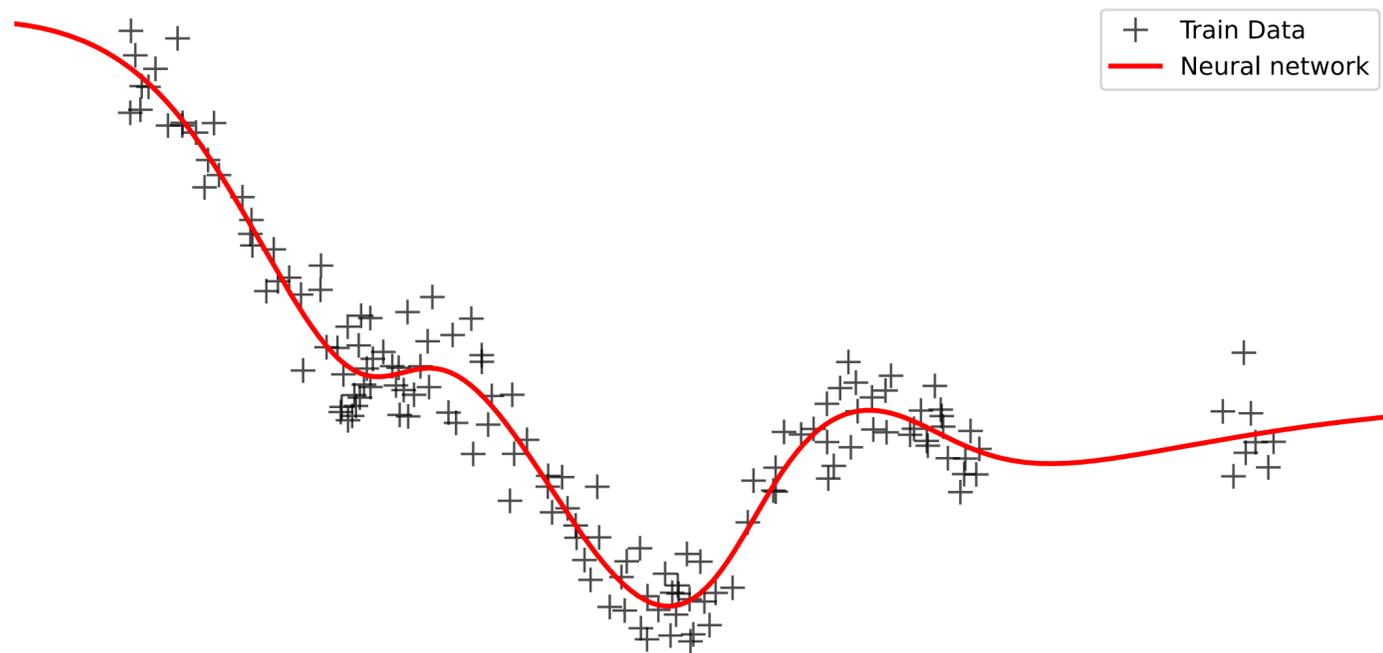
Neural network



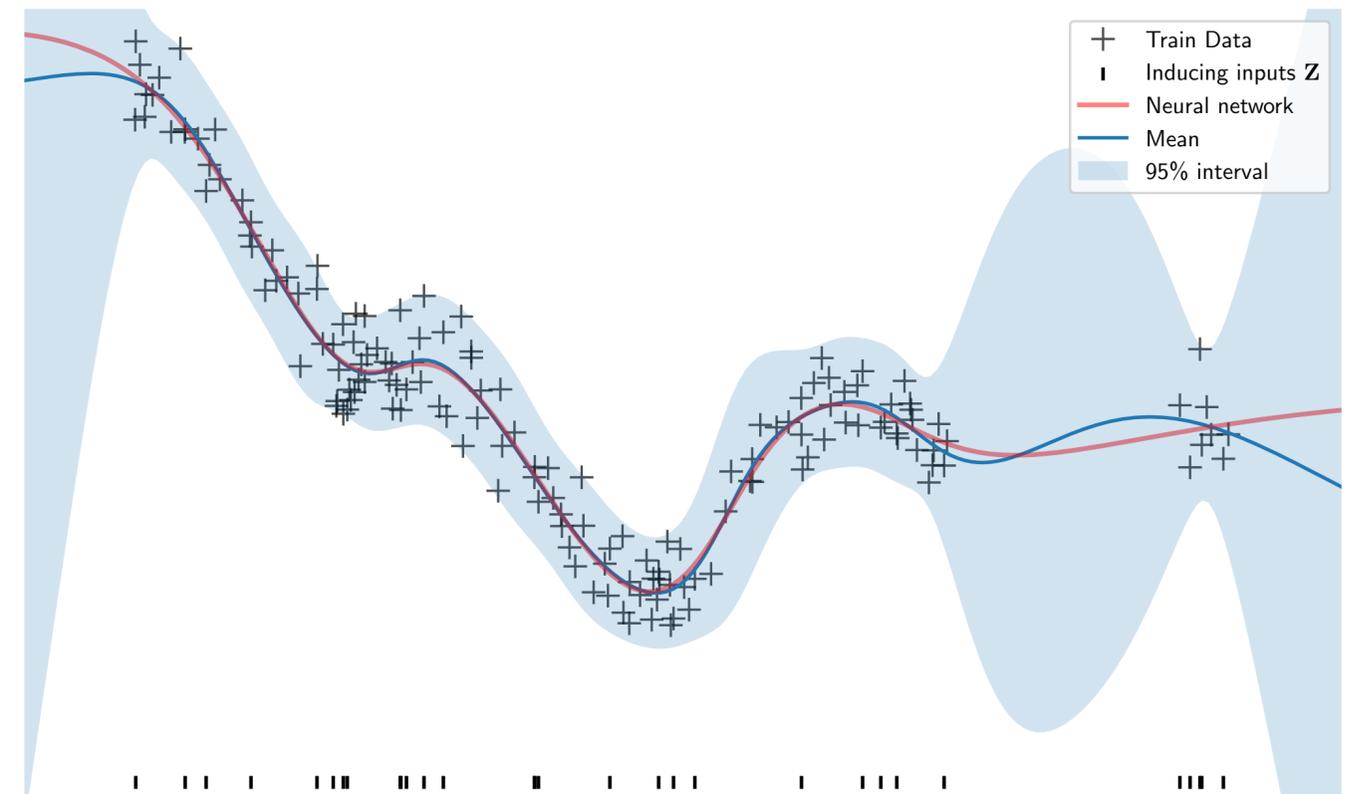
# Uncertainty Quantification

Neural networks lack uncertainty estimates

Neural network



Gaussian process



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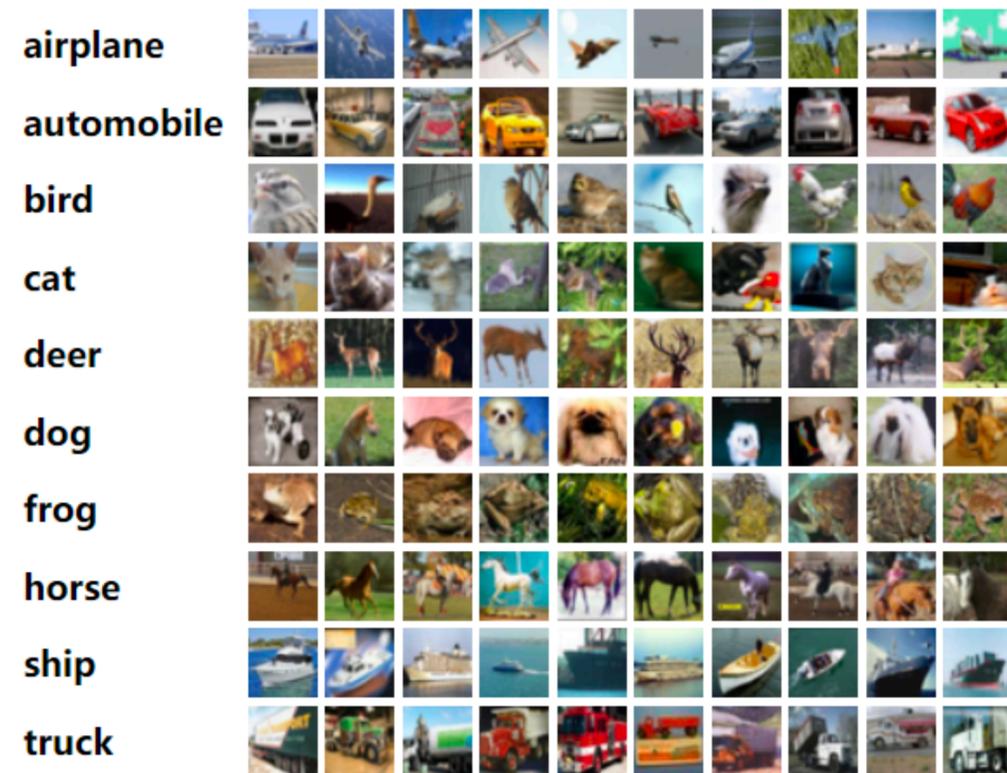
# Image Inputs

Neural networks scale to **high-dimensional inputs**

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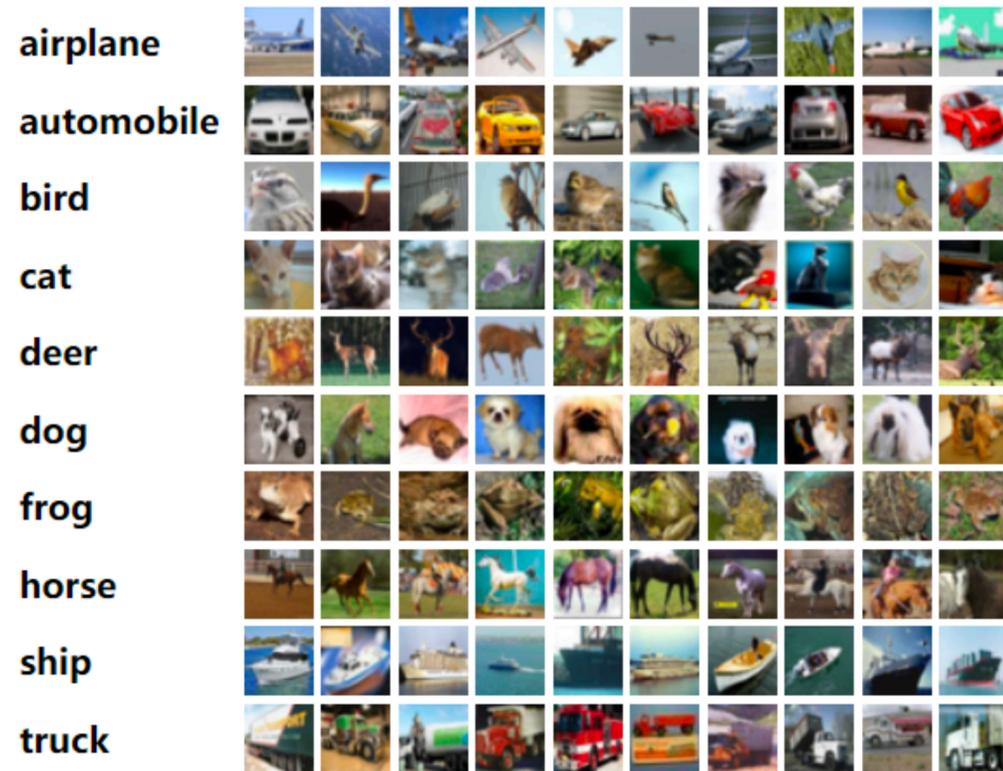
## Neural network



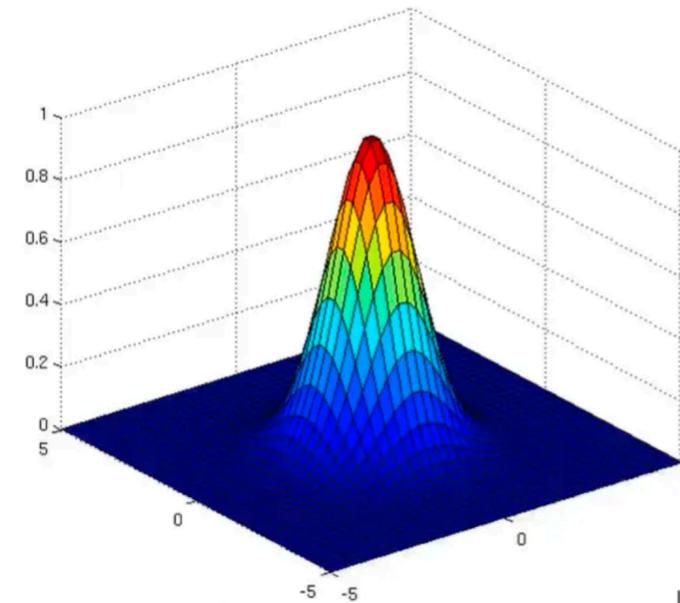
# Image Inputs

Neural networks scale to **high-dimensional inputs**

Neural network



Gaussian process



$$K(\vec{x}, \vec{l}^i) = e^{-\frac{\|\vec{x} - \vec{l}^i\|^2}{2\sigma^2}}$$

Image source: <http://www.cs.toronto.edu/~duvenaud/cookbook/index.html>

# Large Data Sets

Neural networks scale to **large data sets**

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**Neural network**



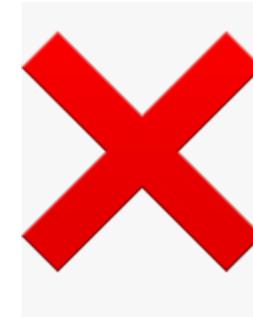
# Large Data Sets

Neural networks scale to **large data sets**

**Neural network**



**Gaussian process**



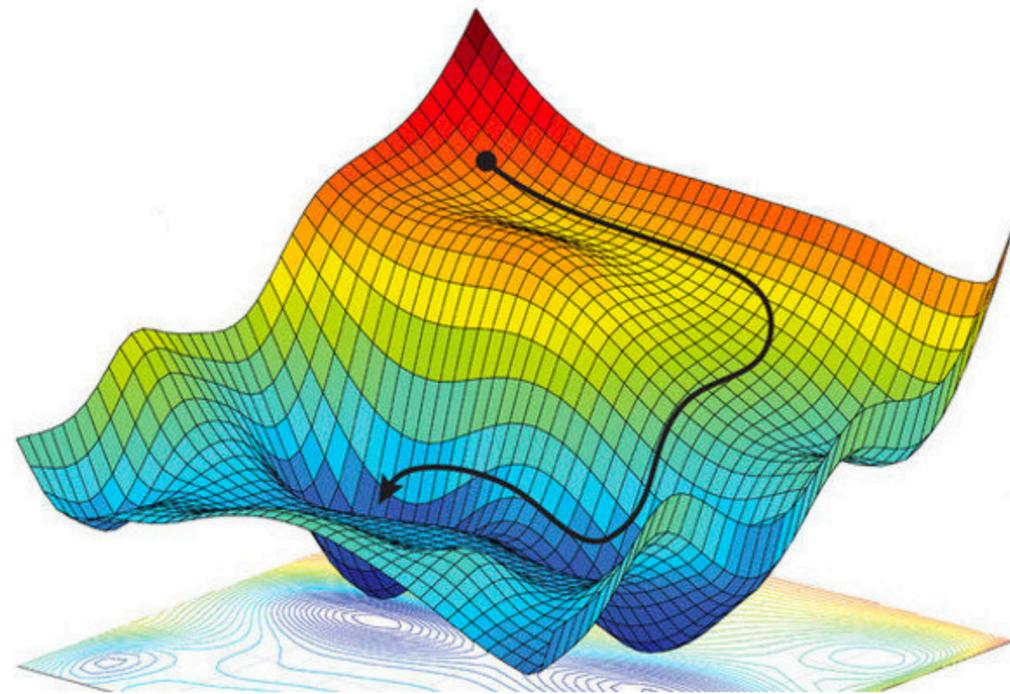
# Incorporating New Data

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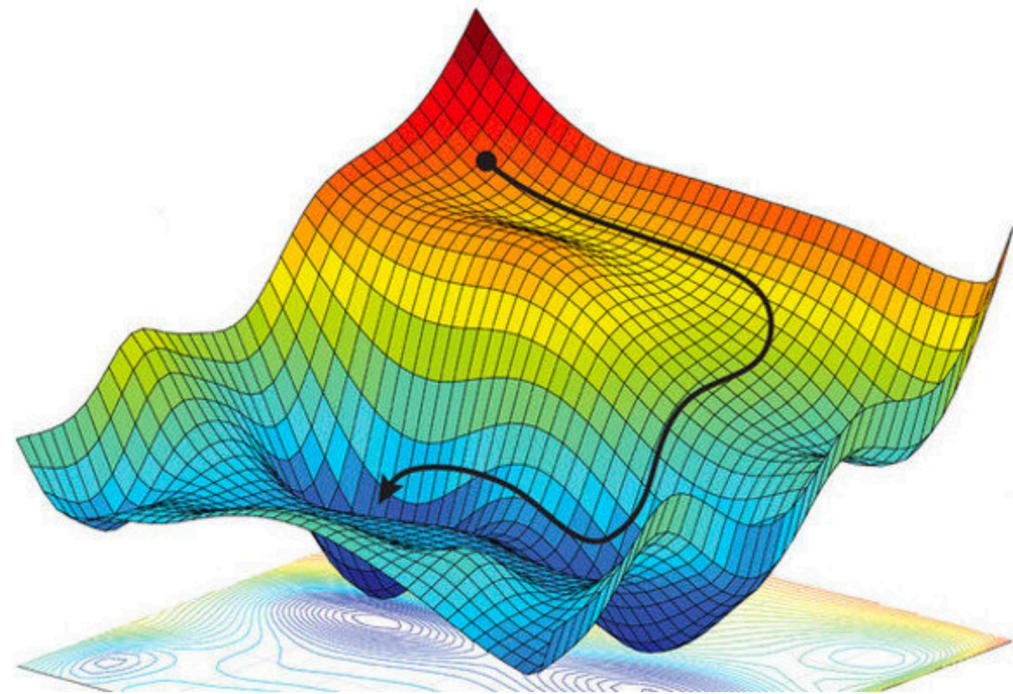
**Neural network**



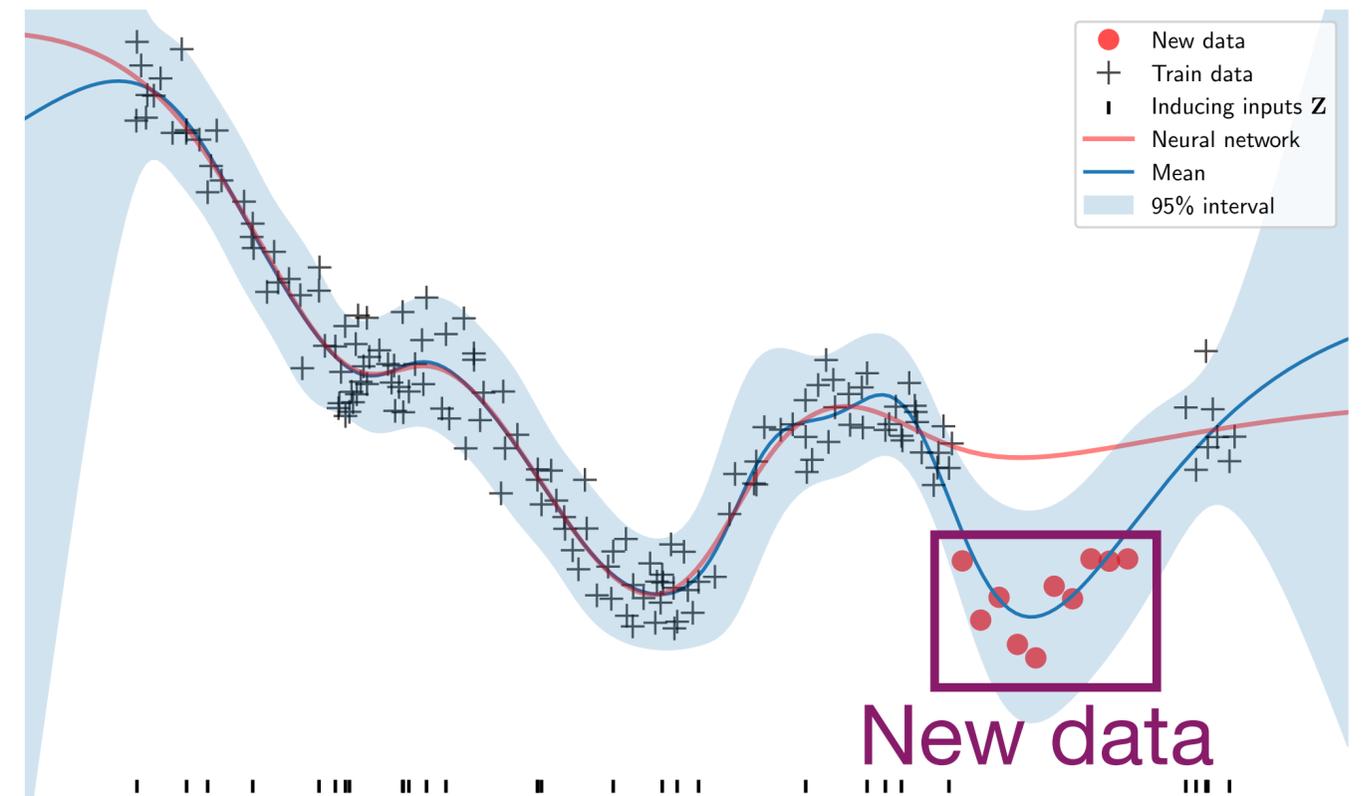
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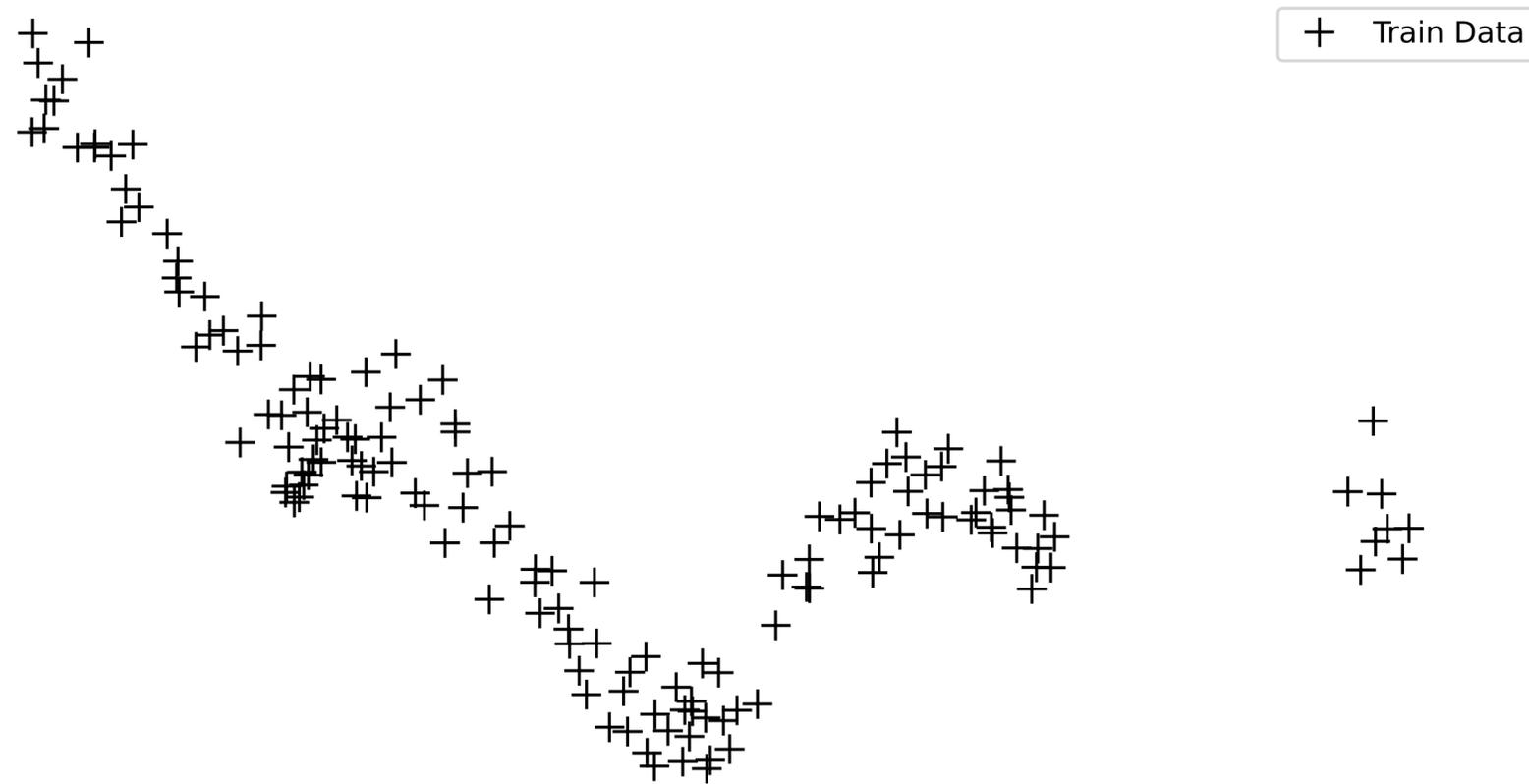
**Gaussian process**



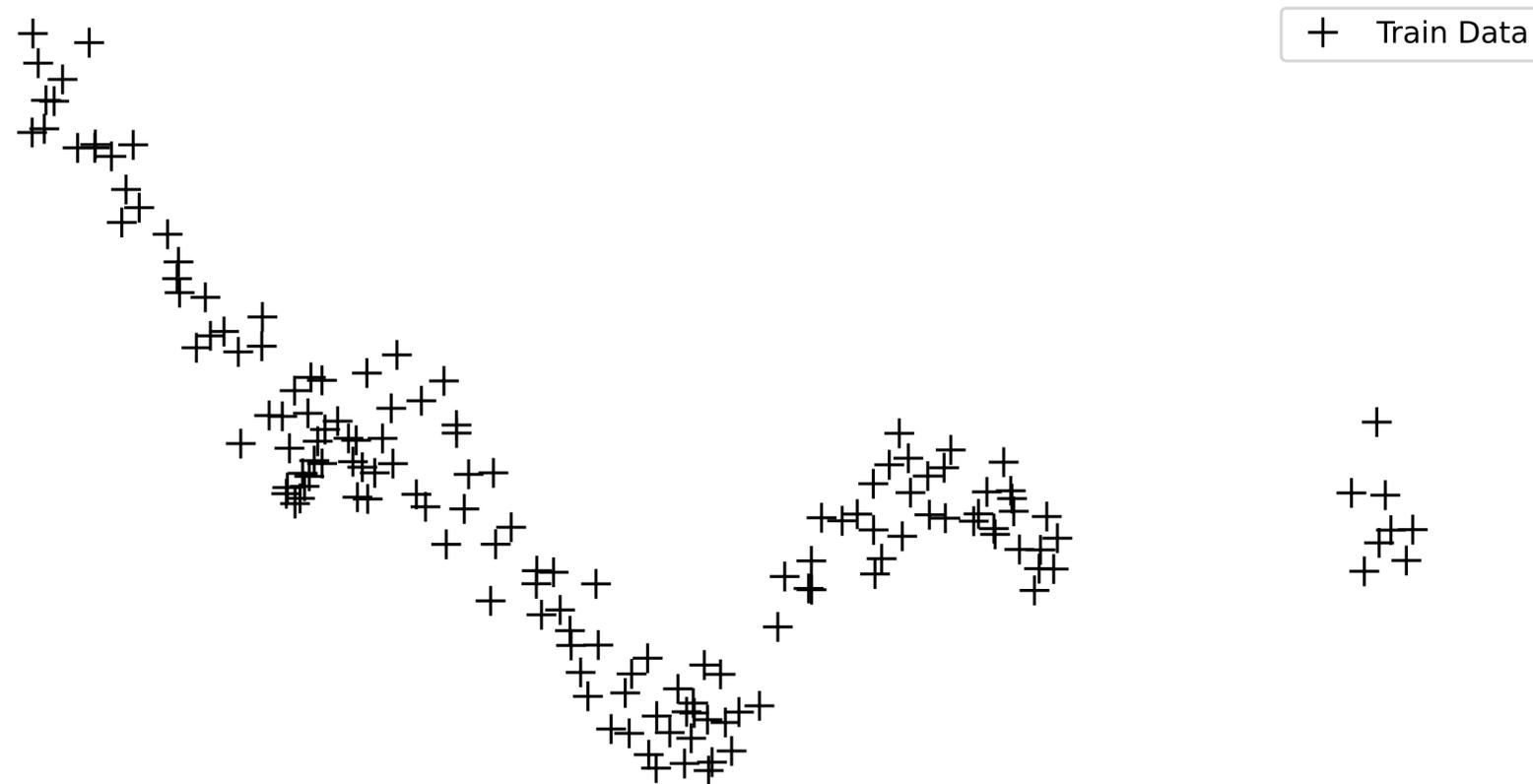
# SFR: Sparse Function-space Representation

Combines benefits of neural networks and Gaussian processes

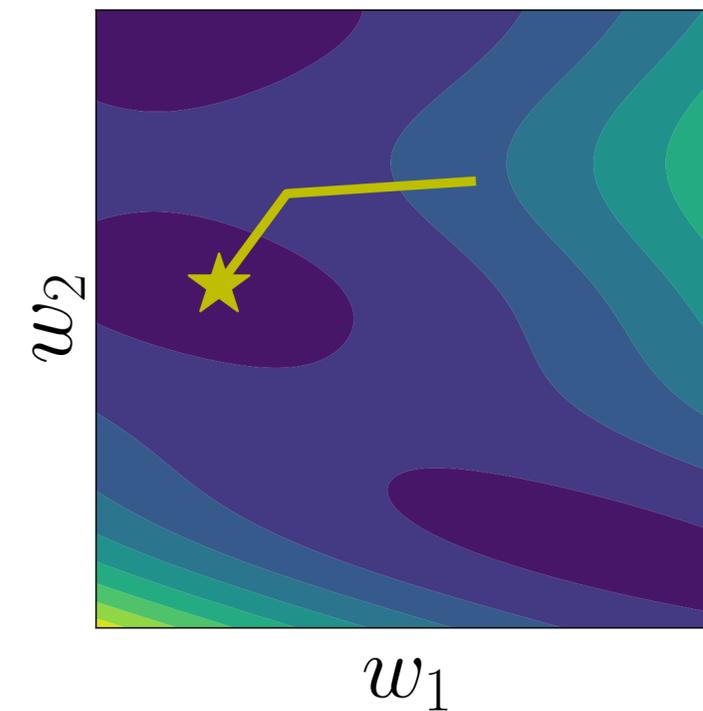
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Weight-space NN training

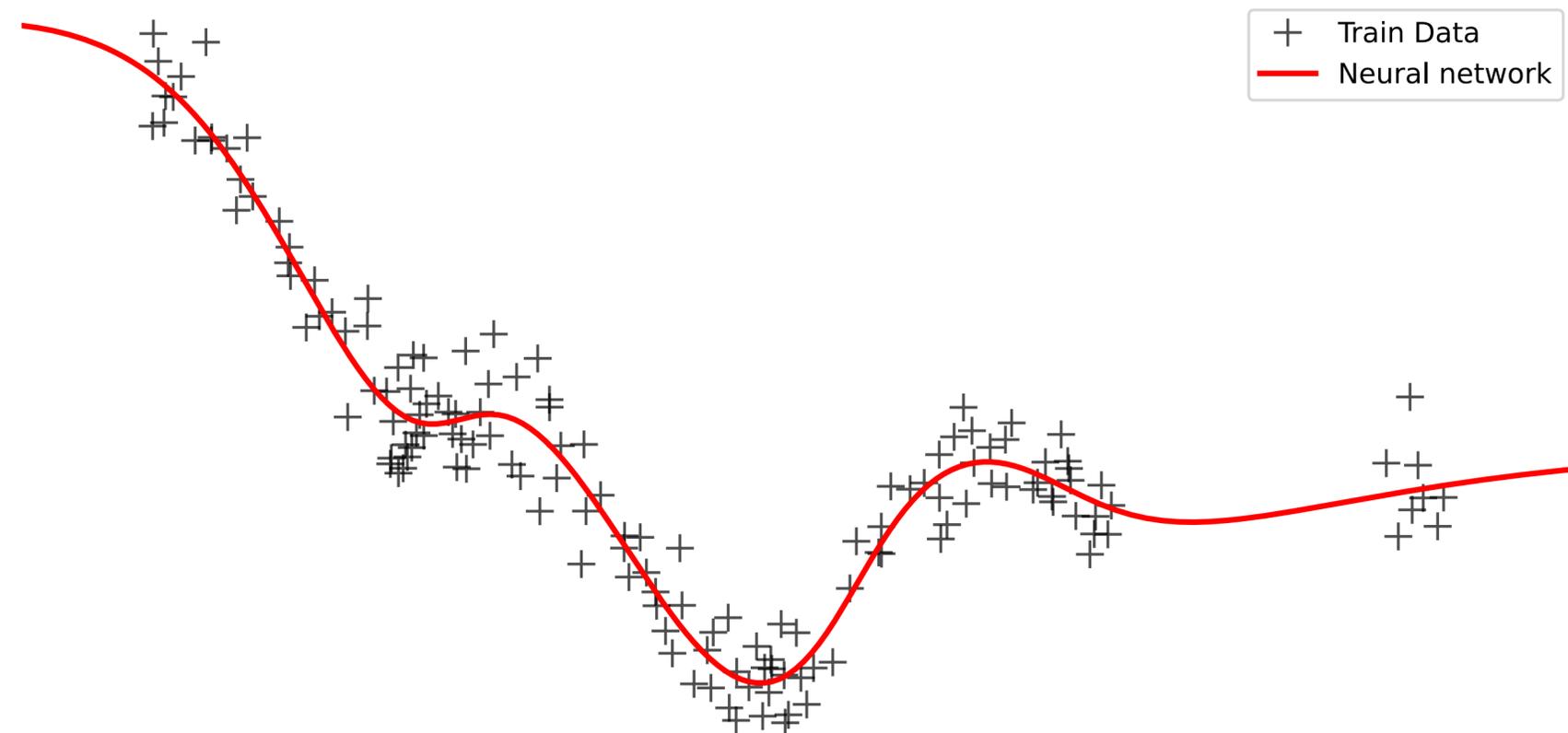


$$\mathbf{w}^* = \arg \min_{\mathbf{w}} \underbrace{\sum_{i=1}^N l(f_{\mathbf{w}}(\mathbf{x}_i), y_i)}_{-\log p(y_i|f_{\mathbf{w}}(\mathbf{x}_i))} + \underbrace{\mathcal{R}(\mathbf{w})}_{-\log p(\mathbf{w})}$$

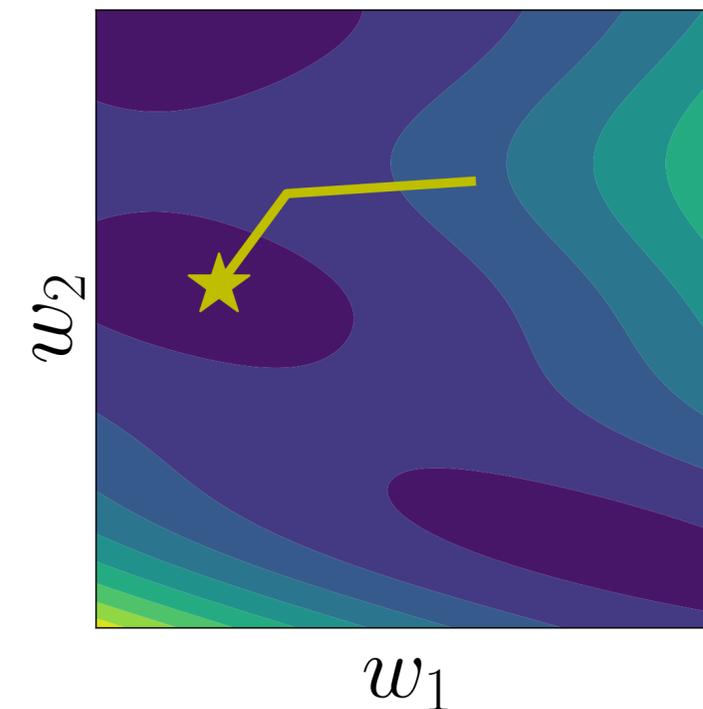
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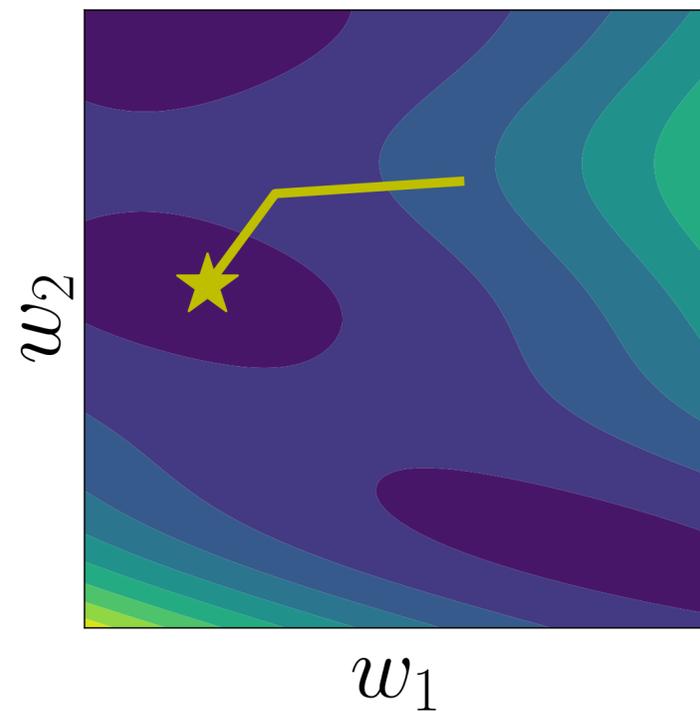
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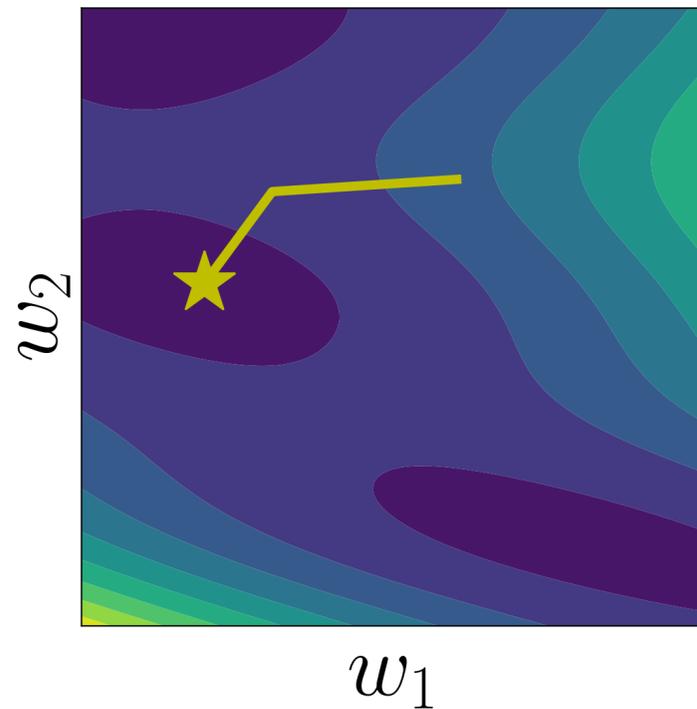
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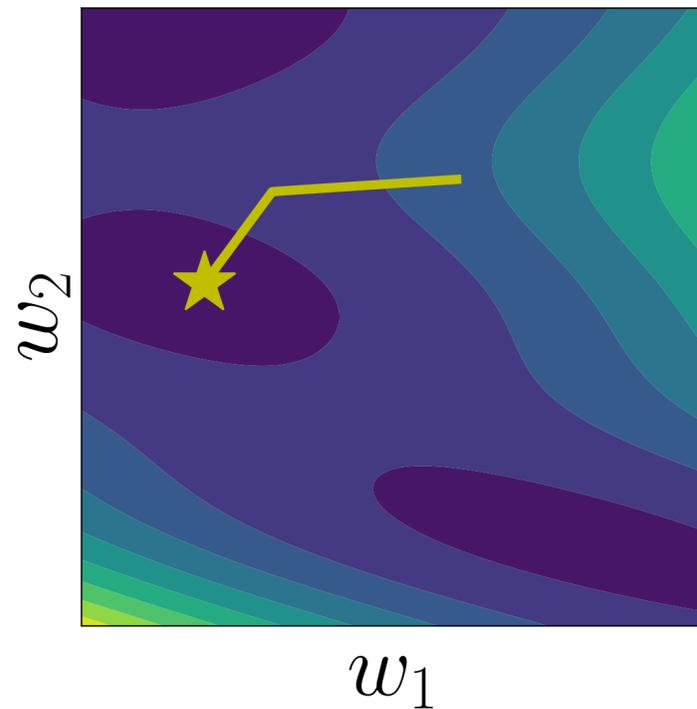
Linearise to get  
kernel formulation



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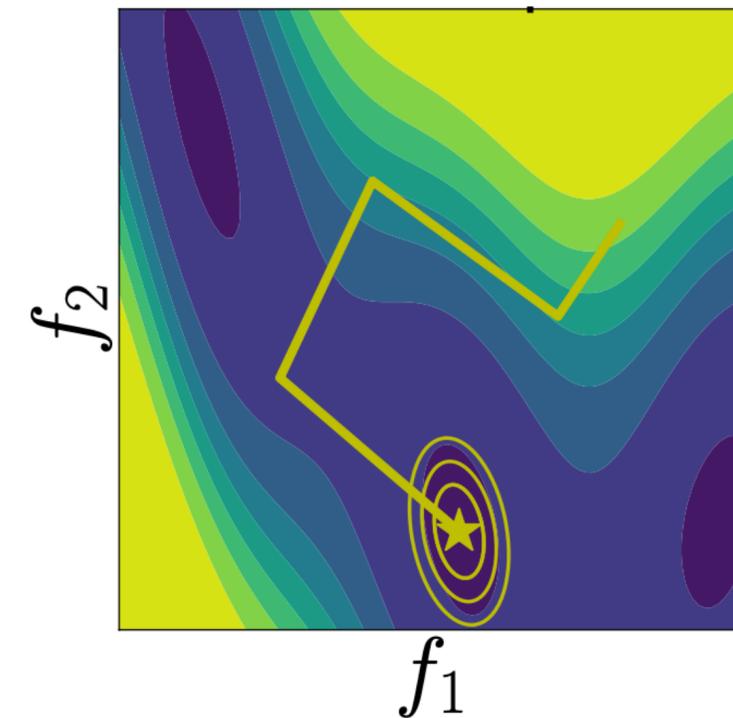
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Linearise to get  
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Function-space inference



$$\mathbf{w}^* = \arg \min_{\mathbf{w}} \sum_{i=1}^N \underbrace{l(f_{\mathbf{w}}(\mathbf{x}_i), y_i)}_{-\log p(y_i | f_{\mathbf{w}}(\mathbf{x}_i))} + \underbrace{\mathcal{R}(\mathbf{w})}_{-\log p(\mathbf{w})}$$

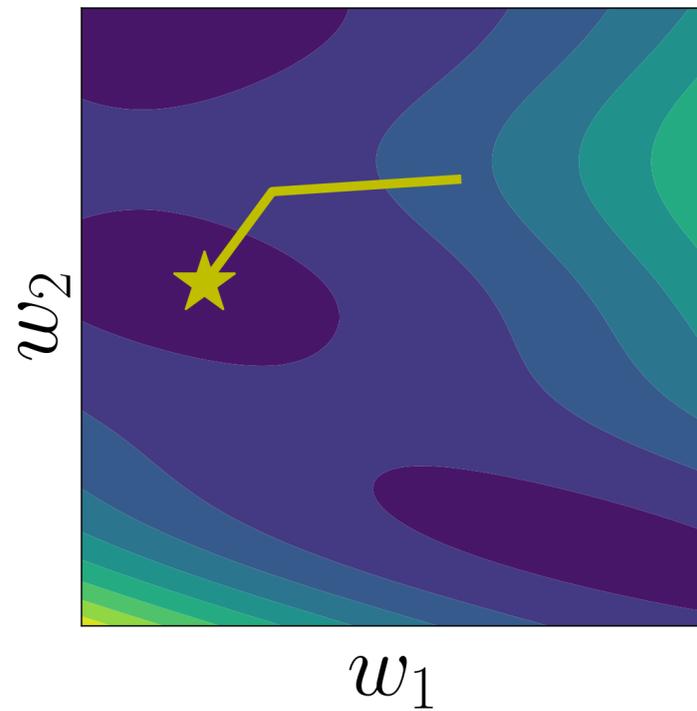
**FCAI**

$$\mathbf{f}^* = \arg \min_{\mathbf{f}} \sum_{i=1}^N -\log p(y_i | f_{\mathbf{w}}(\mathbf{x}_i)) - \log p(\mathbf{f})$$

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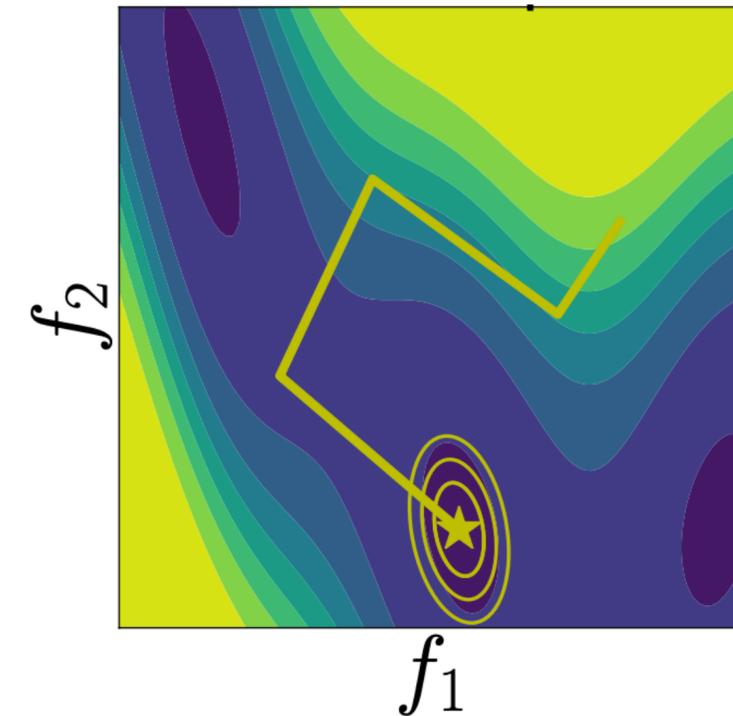
Weight-space NN training



Linearise to get kernel formulation



Function-space inference



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**FCAI**

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$$p(\mathbf{f} | \mathcal{D}) \approx q(\mathbf{f}) = \mathcal{N}(\mathbf{f} | \mathbf{f}^*, \mathbf{S}_{\mathbf{f}})$$

Function-space  
Laplace approx.

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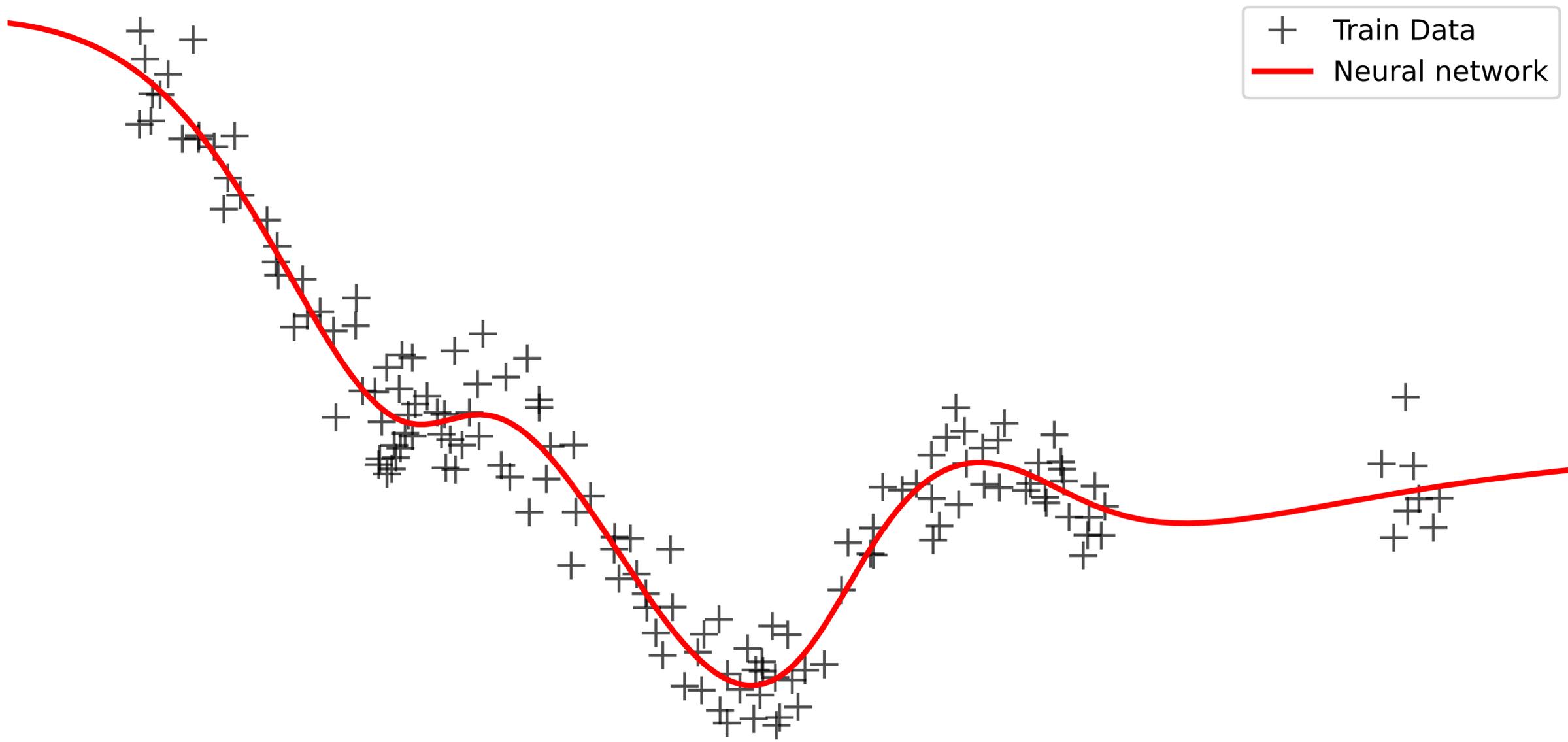
- ⚠ GP predictive posterior is computationally expensive

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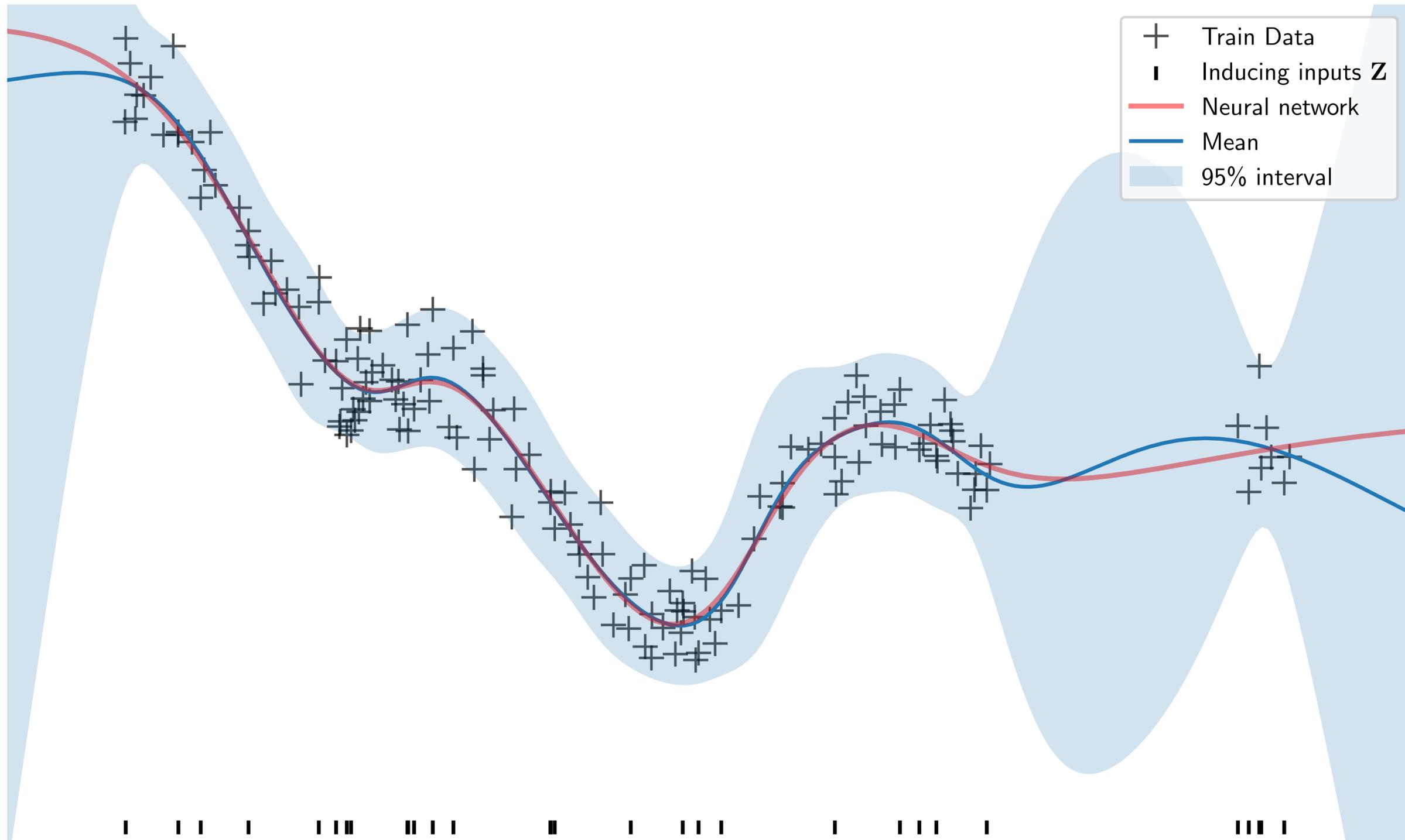
Function-space  
Laplace approx.

- **⚠ GP predictive posterior is computationally expensive**
- **We sparsify the GP using a dual parameterization**



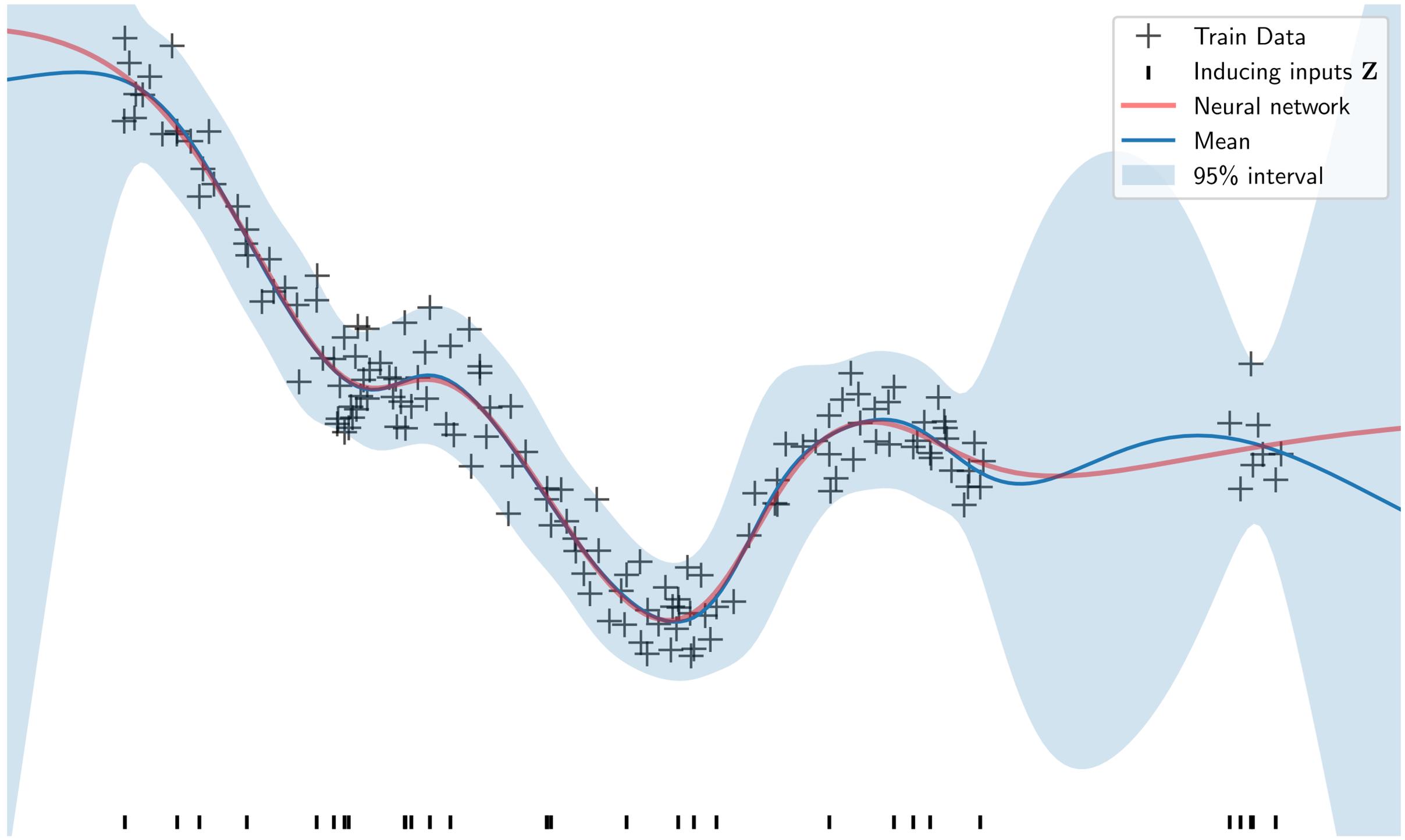
+ Train Data  
— Neural network

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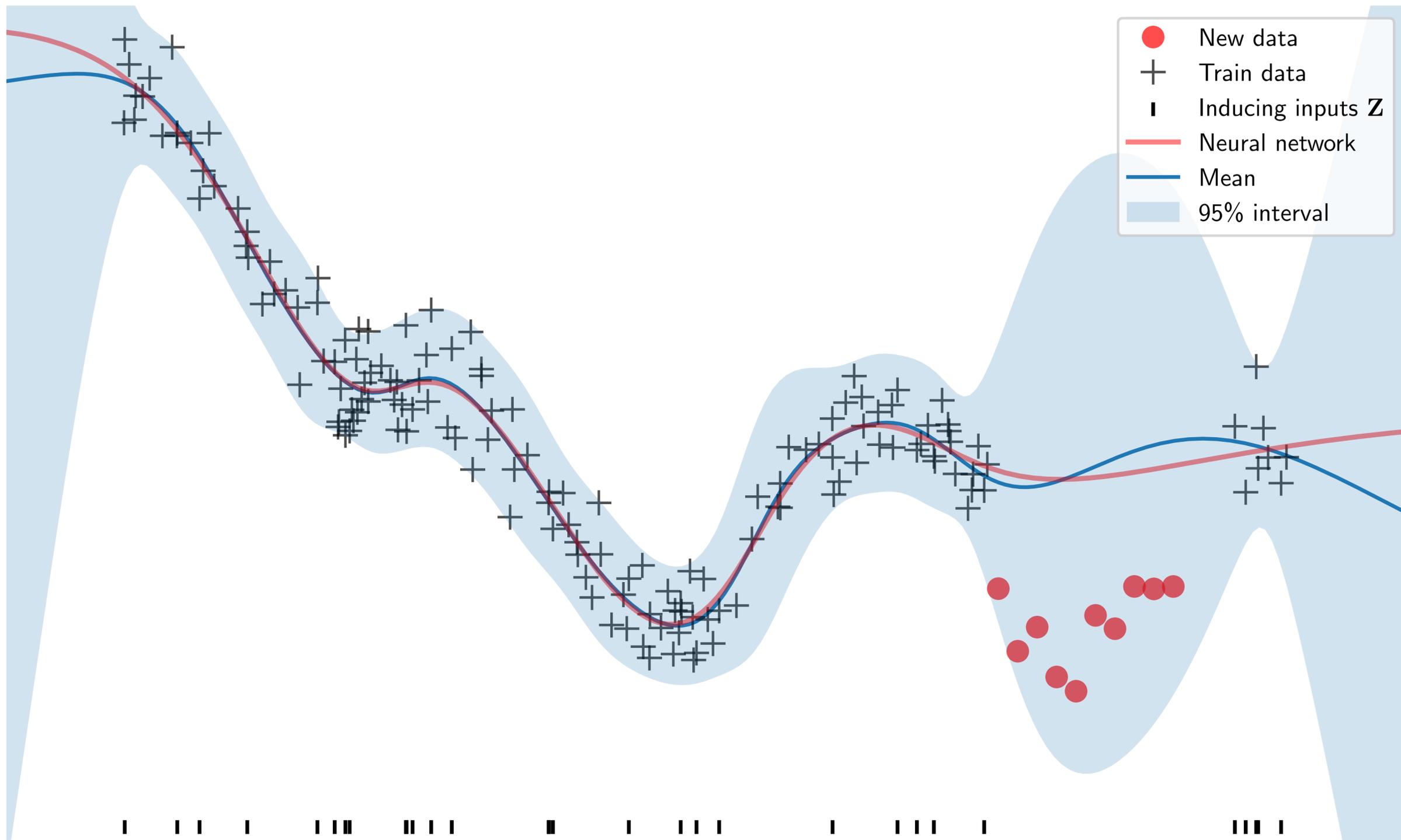
# Uncertainty estimates



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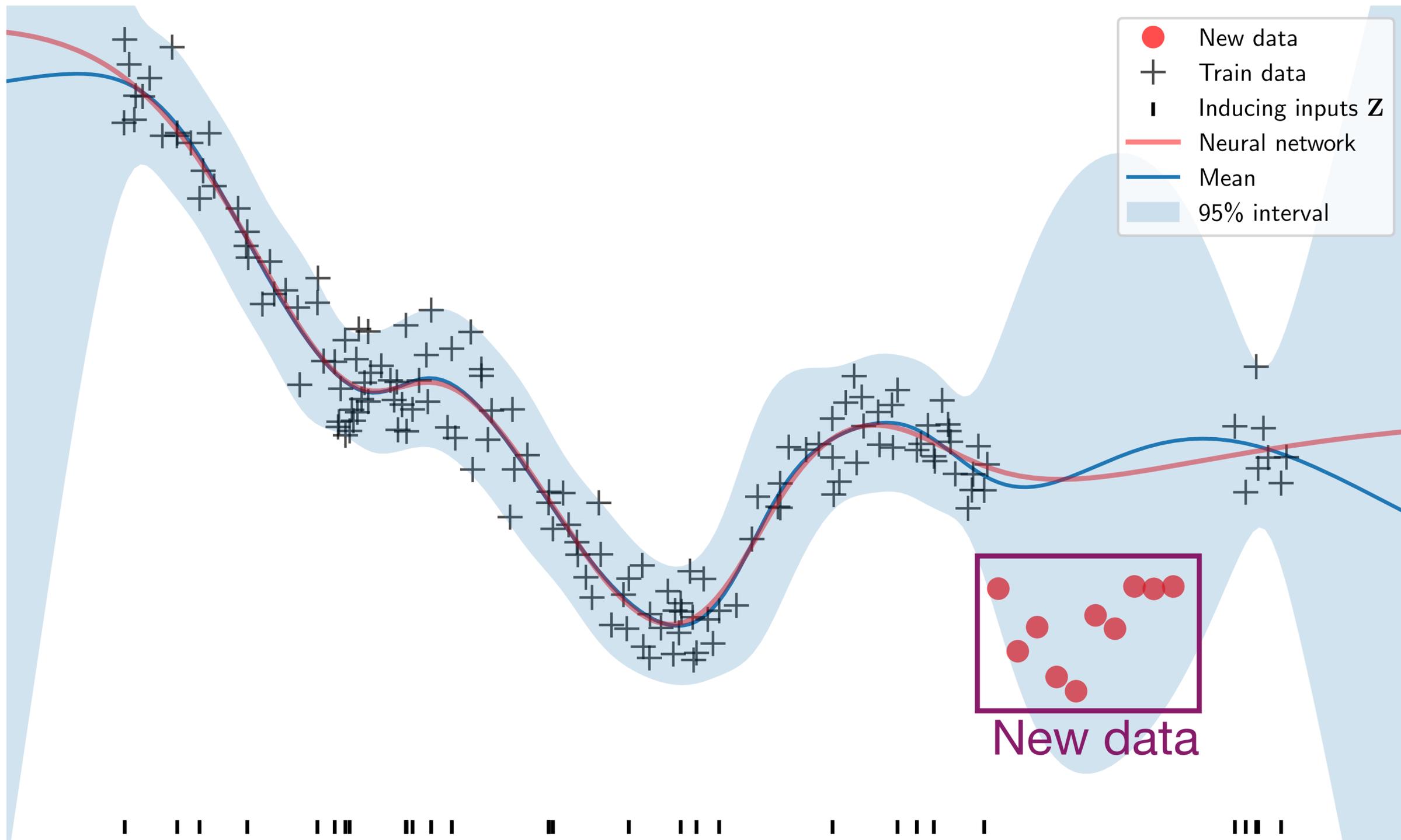
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**FCAI**



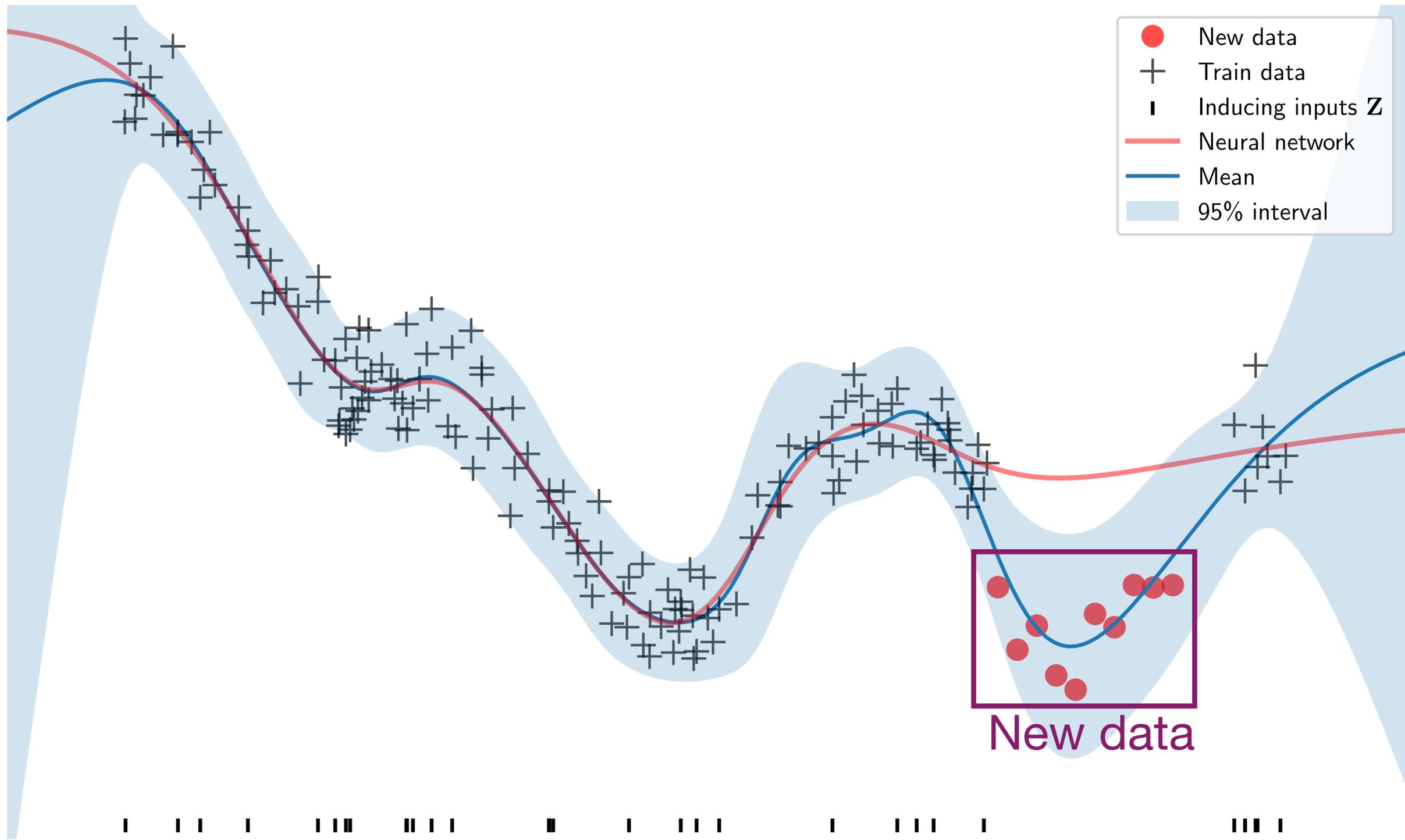
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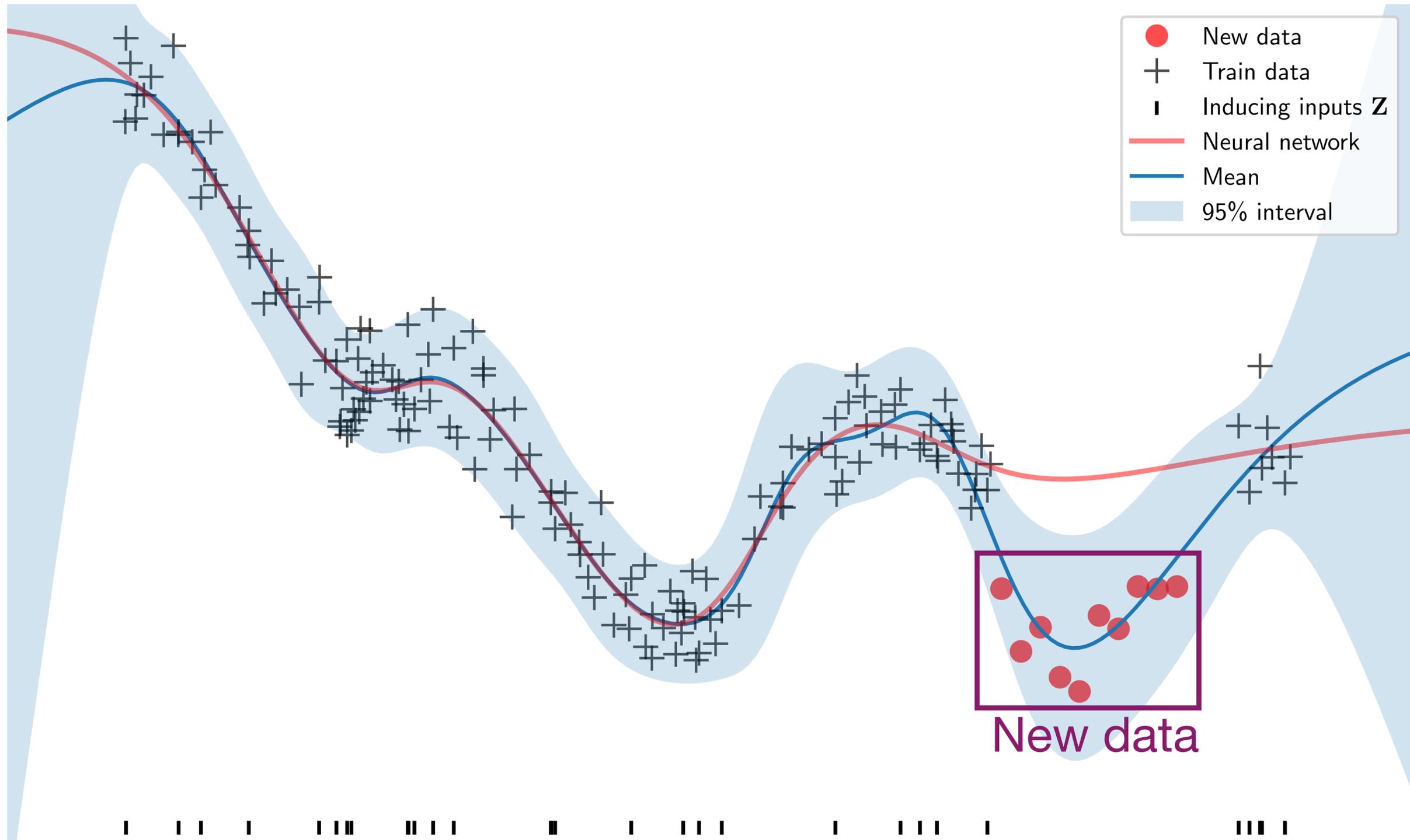
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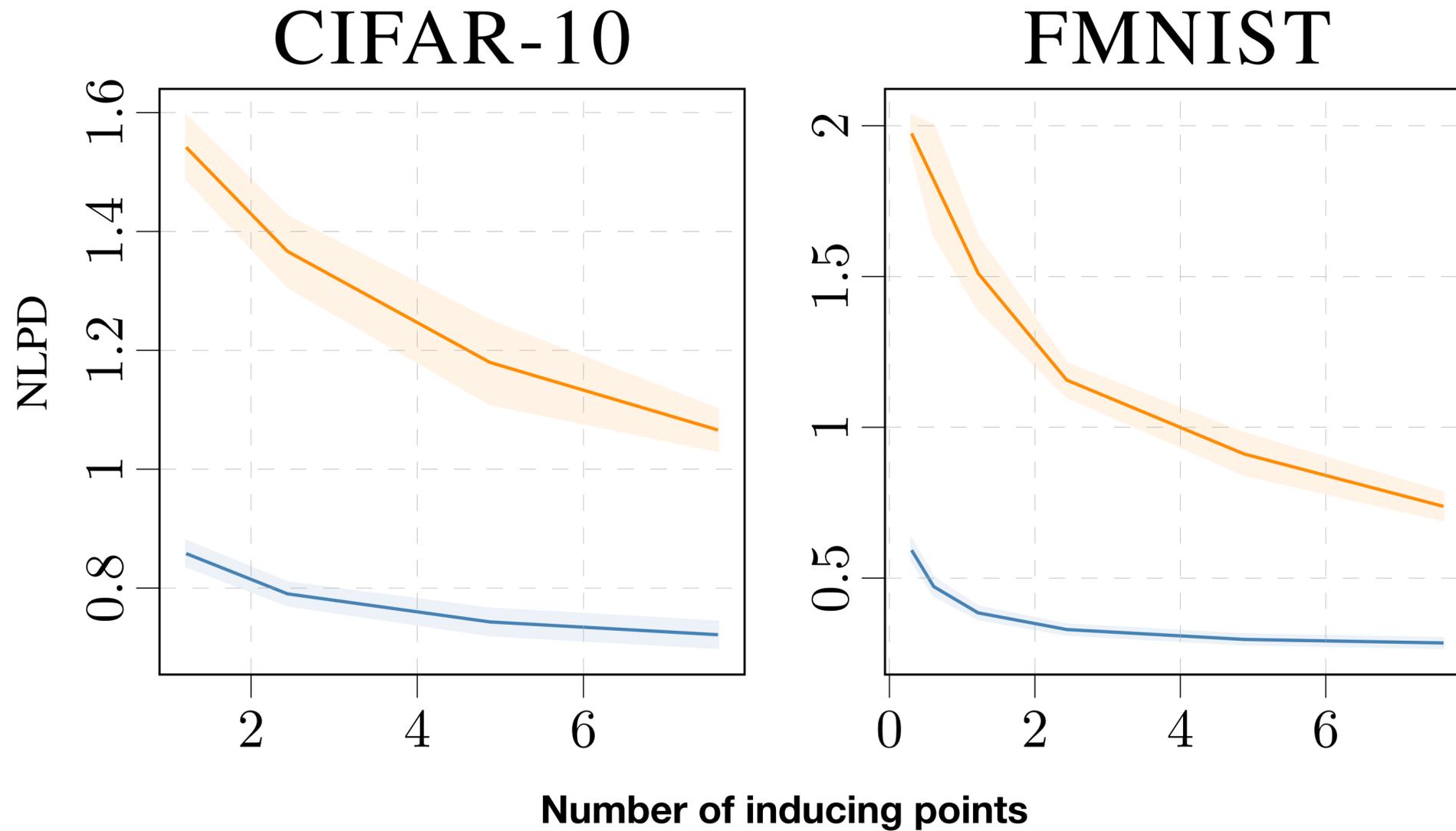
Incorporate new data fast 



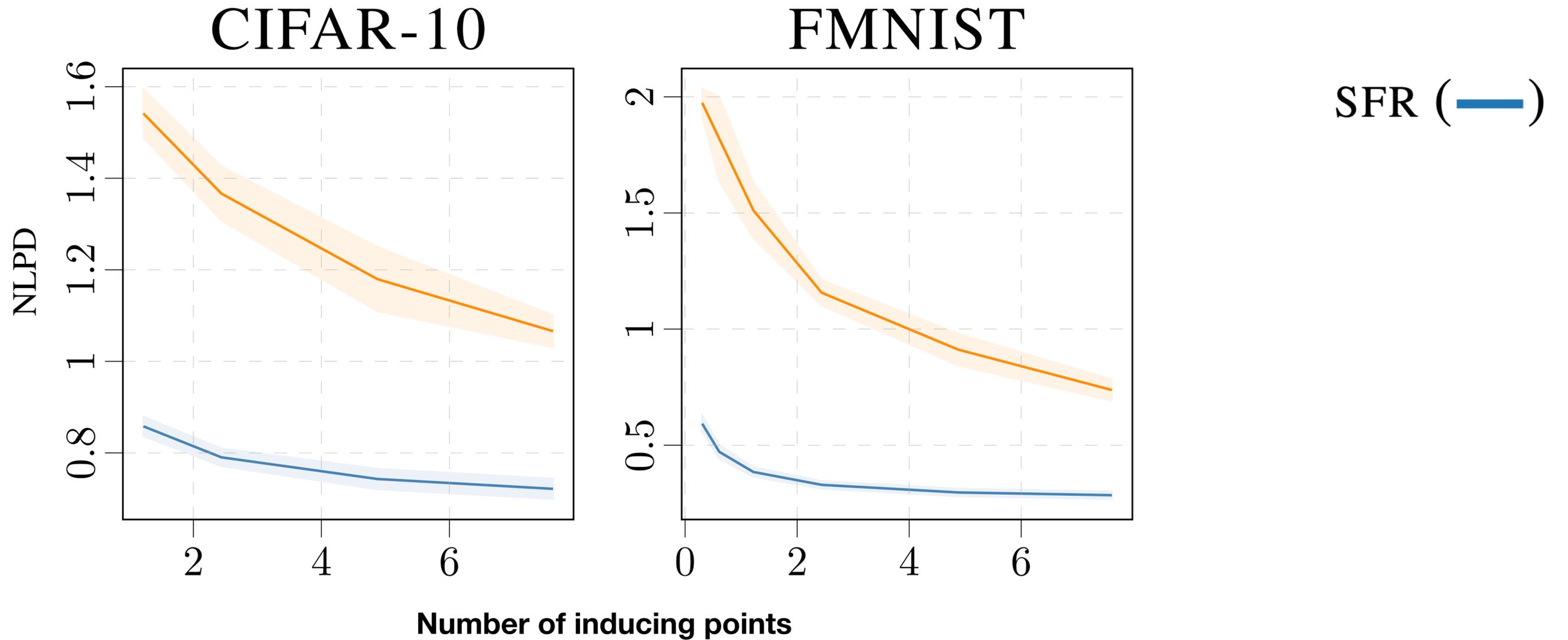
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# Results: Effective Sparsification



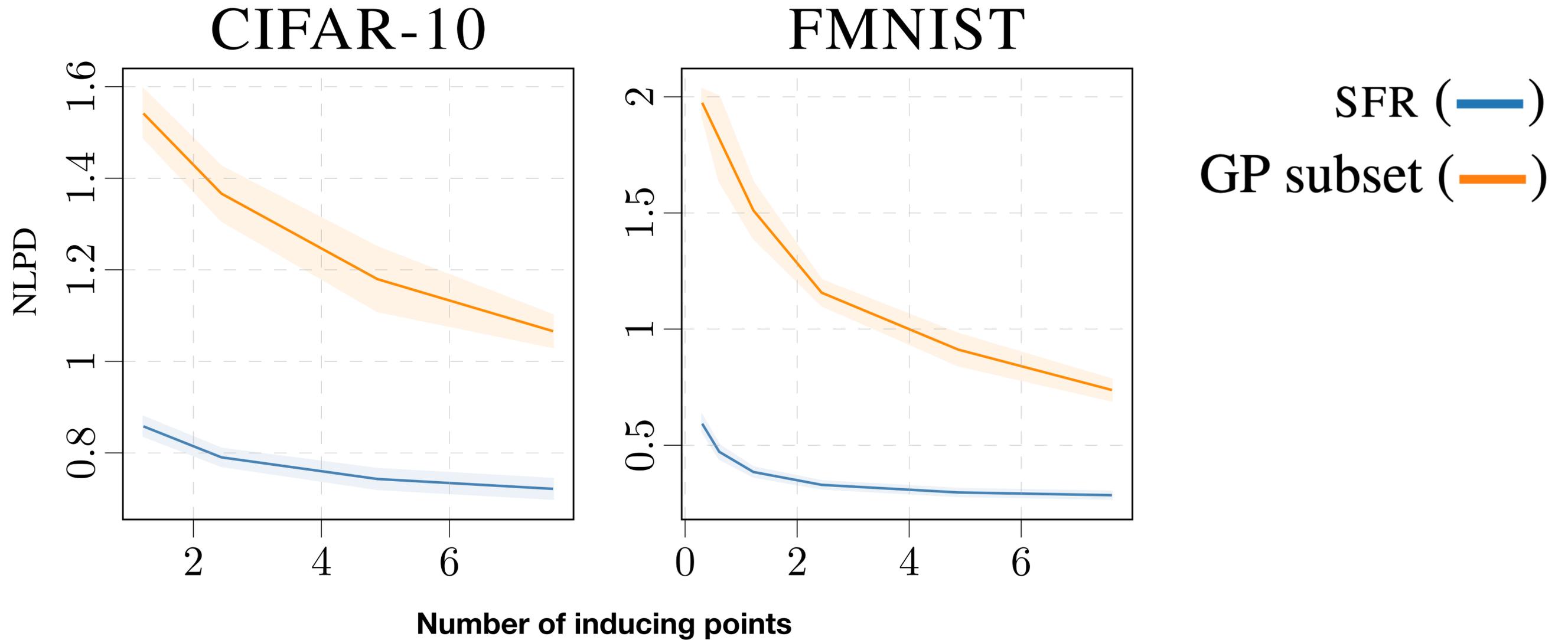
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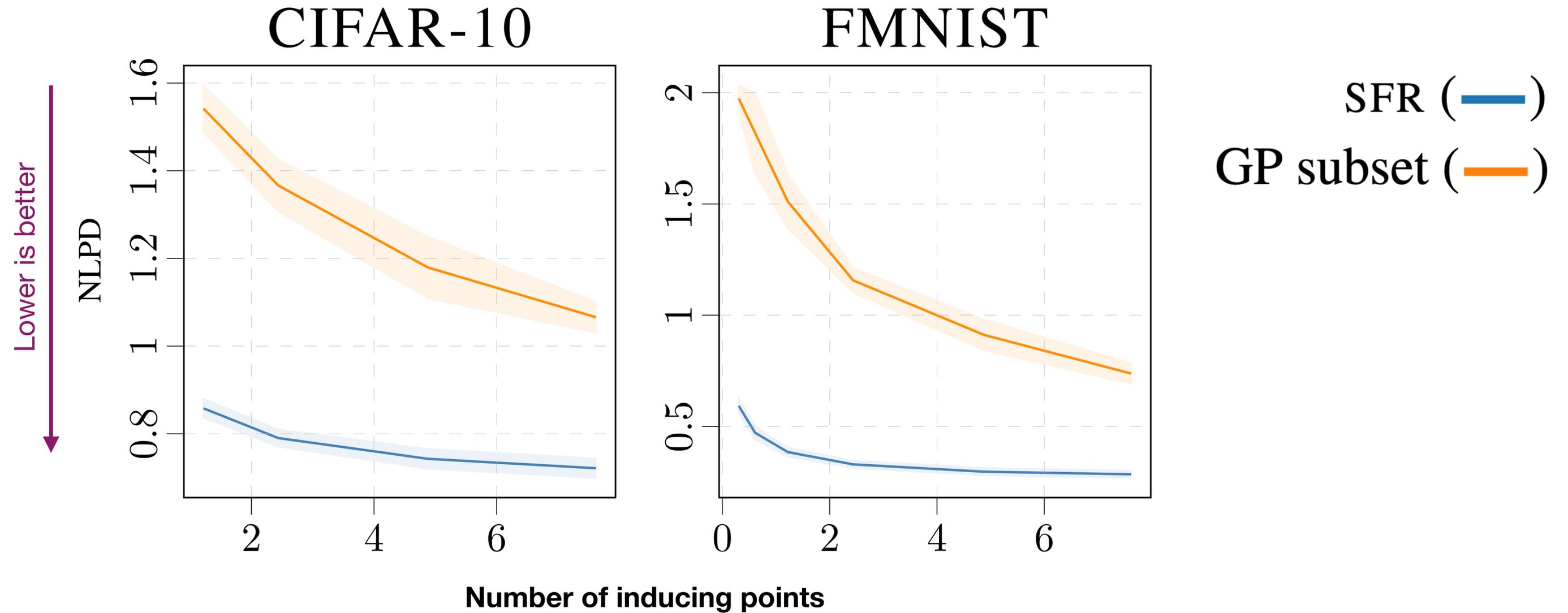
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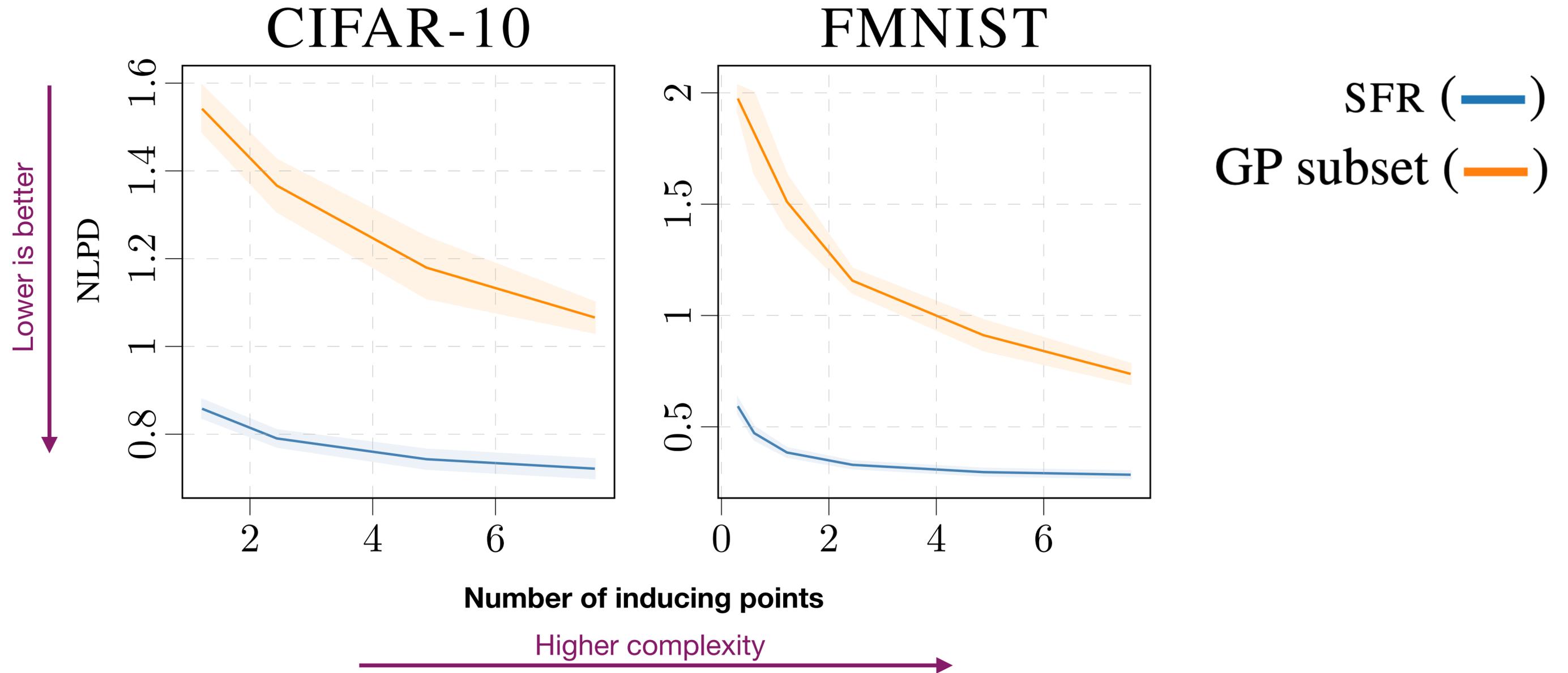
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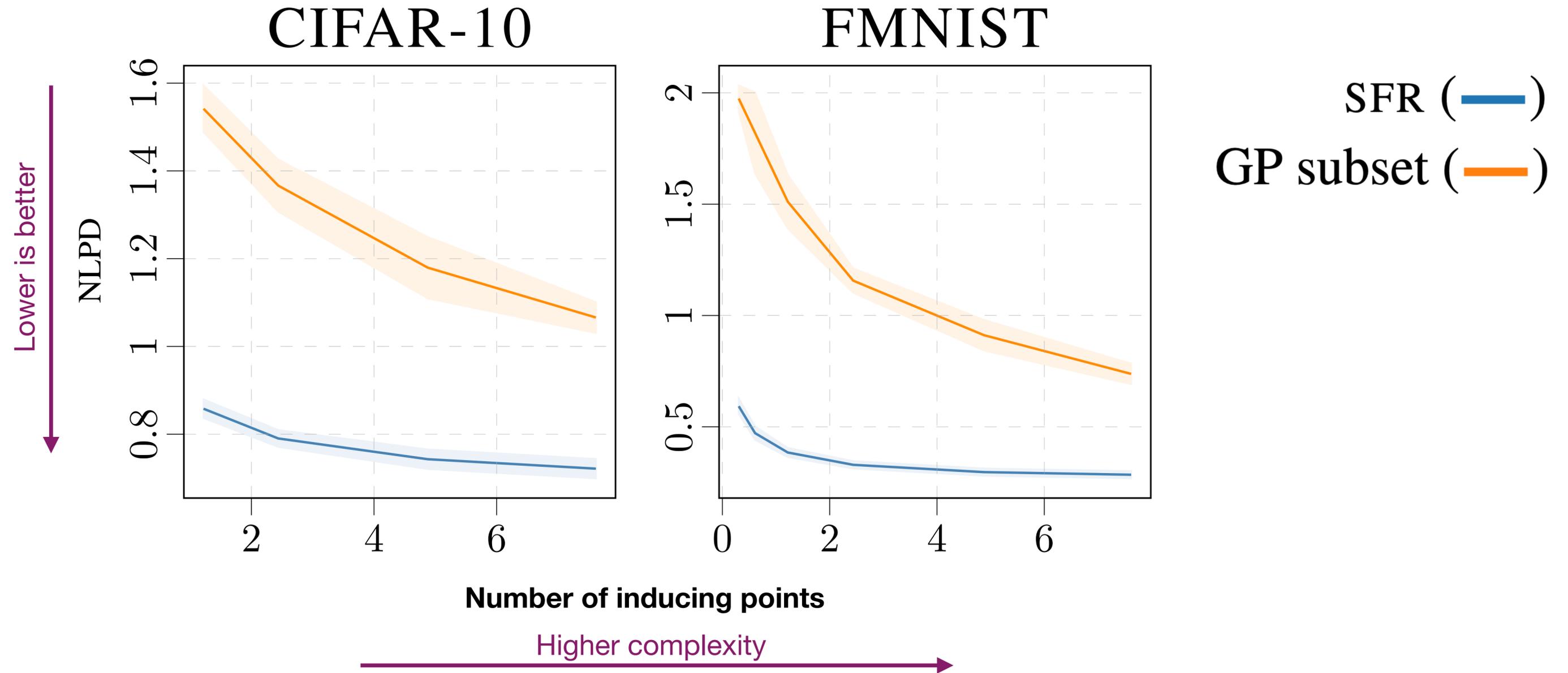


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# Results: Effective Sparsification

SFR makes better predictions with lower complexity

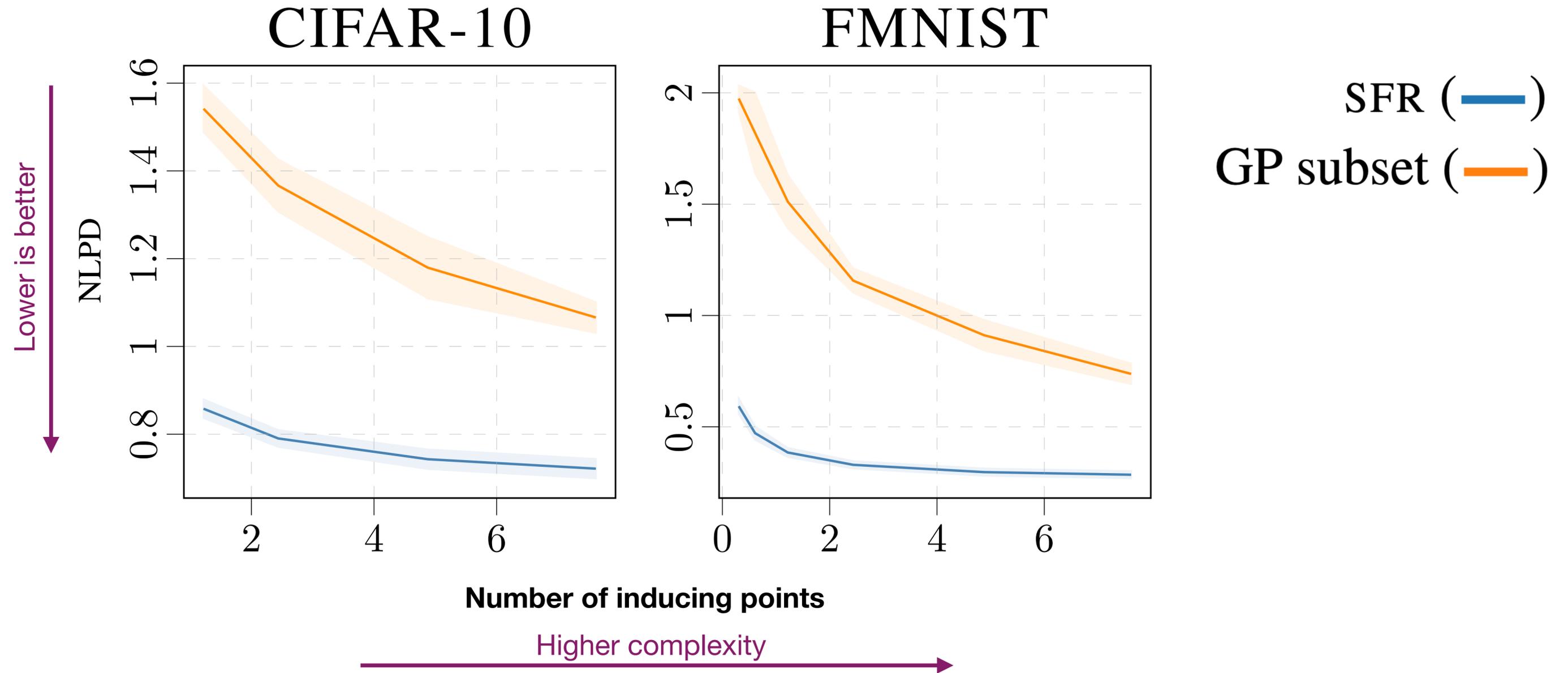


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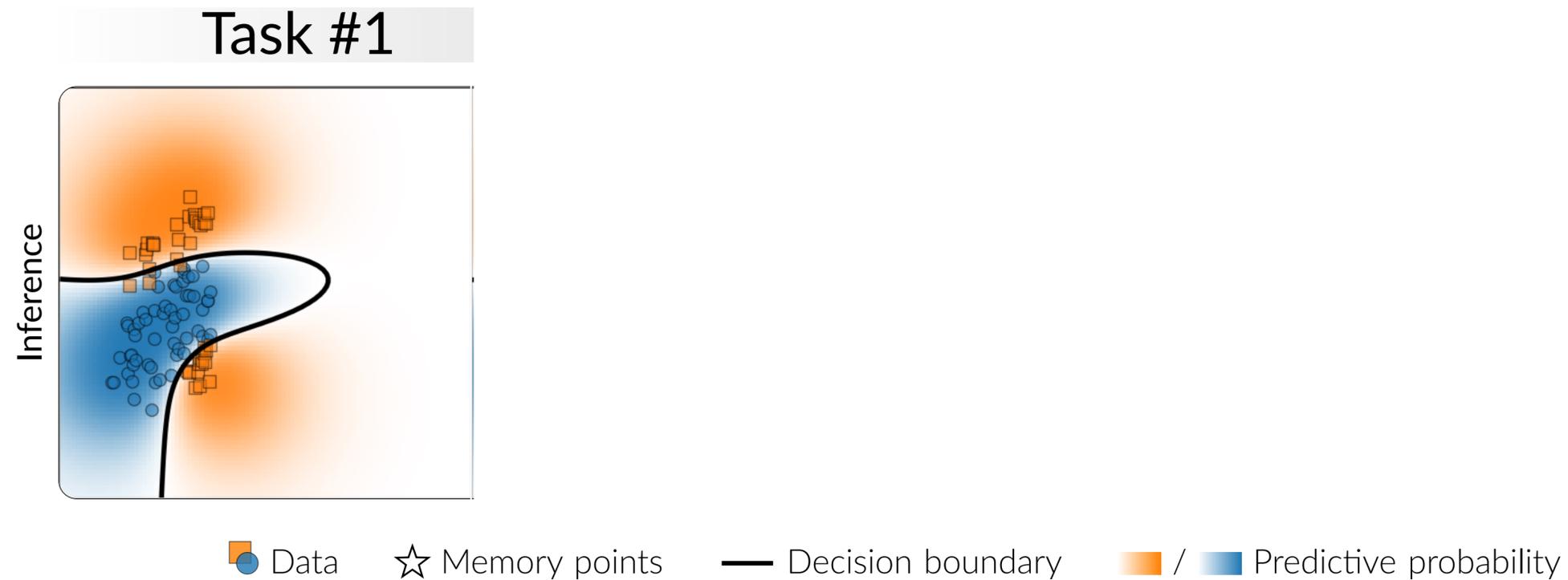
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# SFR for Sequential Learning

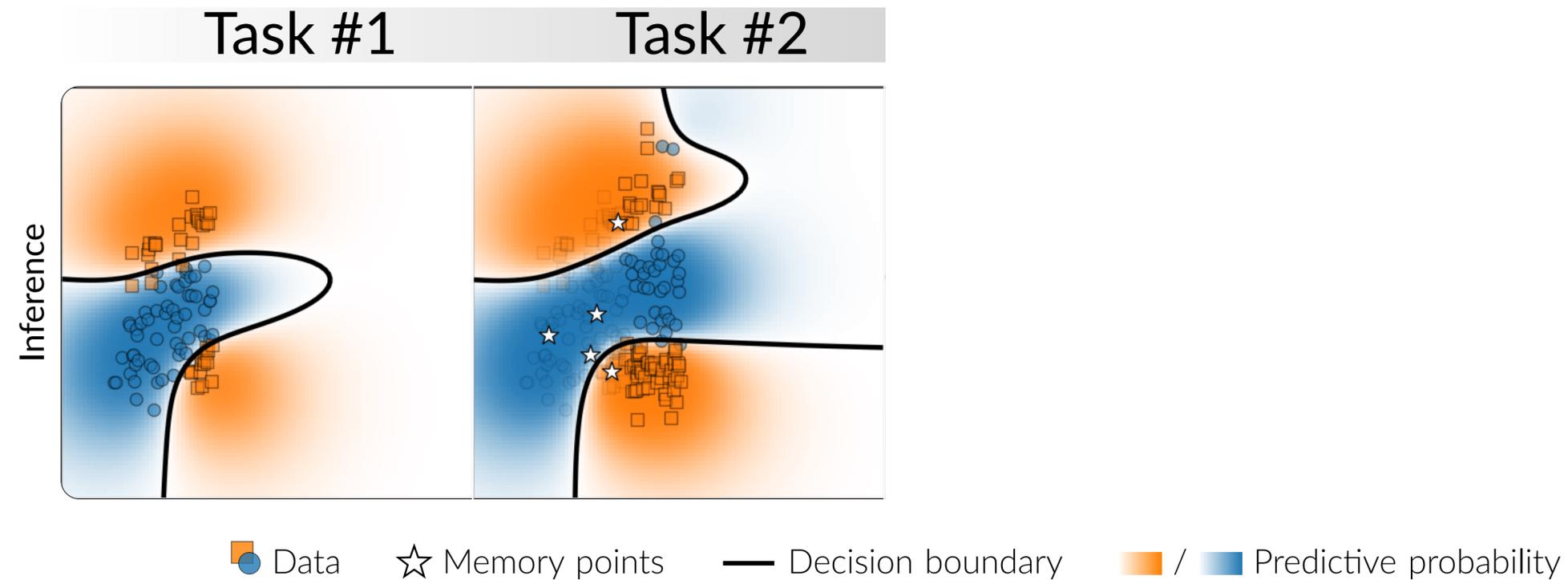
# Continual Learning

SFR maintains a **functional representation** for continual learning



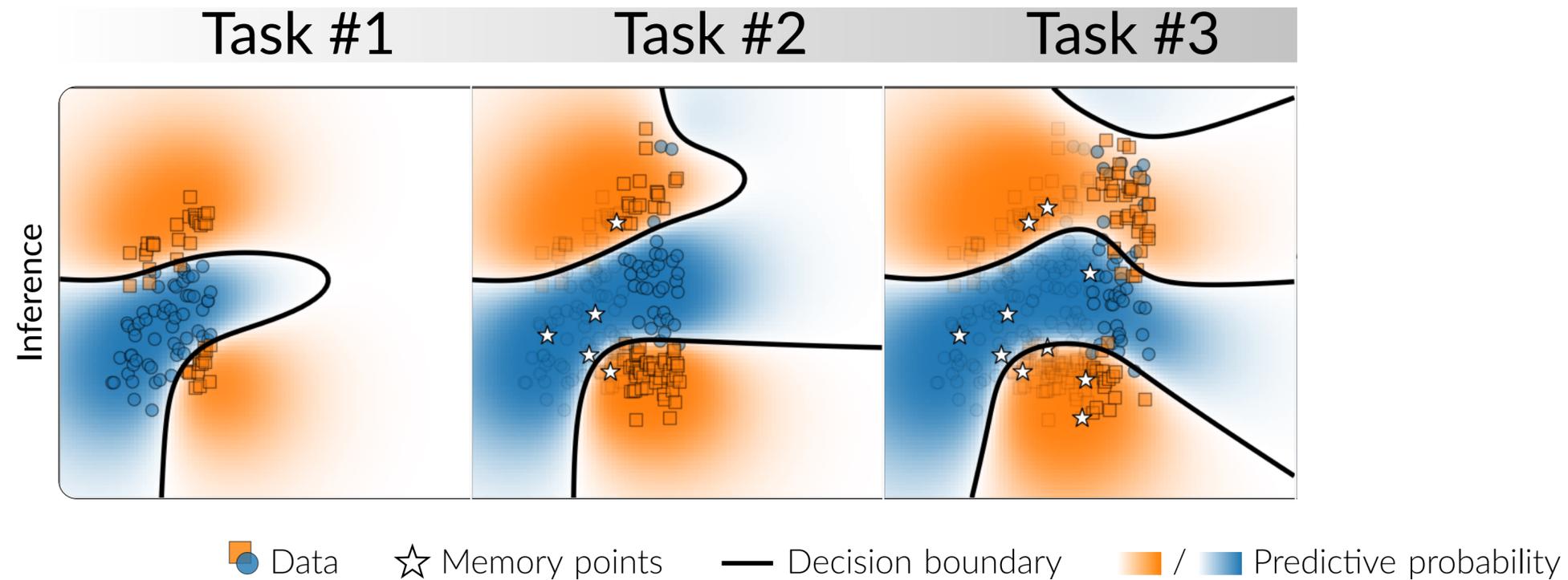
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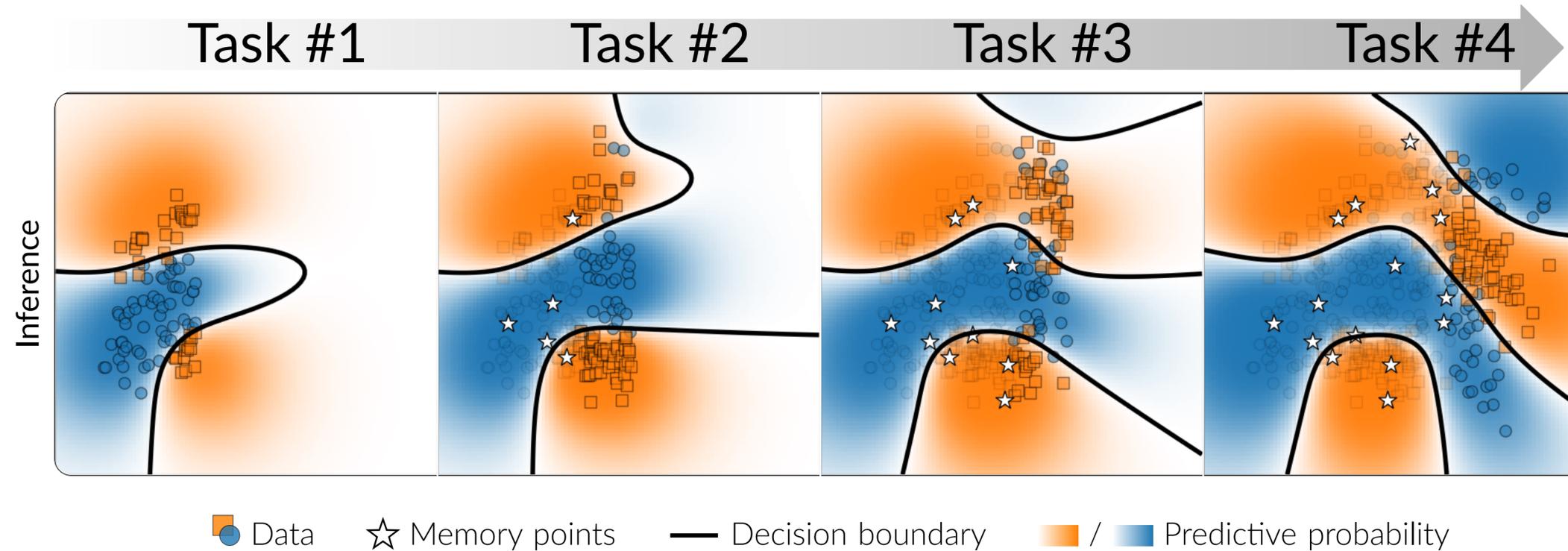
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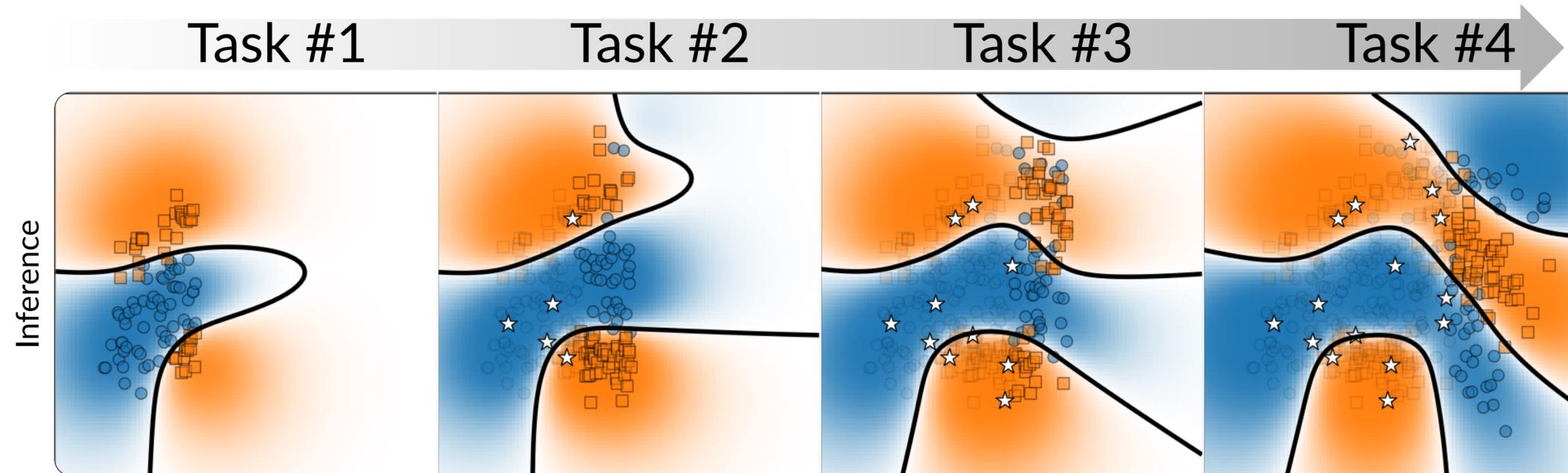
# Continual Learning

SFR maintains a **functional representation** for continual learning



# Continual Learning

SFR maintains a **functional representation** for continual learning



■ Data ● Data ☆ Memory points — Decision boundary ■ / ■ Predictive probability

Method	S-MNIST (SH) 40 pts./task	S-MNIST (SH) 200 pts./task	S-FMNIST (SH) 200 pts./task	P-MNIST (SH) 200 pts./task
DER	85.26 $\pm$ 0.54	92.13 $\pm$ 0.45	<b>82.03</b> $\pm$ 0.57	93.08 $\pm$ 0.11
FROMP	75.21 $\pm$ 2.05	89.54 $\pm$ 0.72	78.83 $\pm$ 0.46	94.90 $\pm$ 0.04
S-FSVI	84.51 $\pm$ 1.30	92.87 $\pm$ 0.14	77.54 $\pm$ 0.40	<b>95.76</b> $\pm$ 0.02
SFR (Ours)	<b>89.22</b> $\pm$ 0.76	<b>94.19</b> $\pm$ 0.26	<b>81.96</b> $\pm$ 0.24	95.58 $\pm$ 0.08

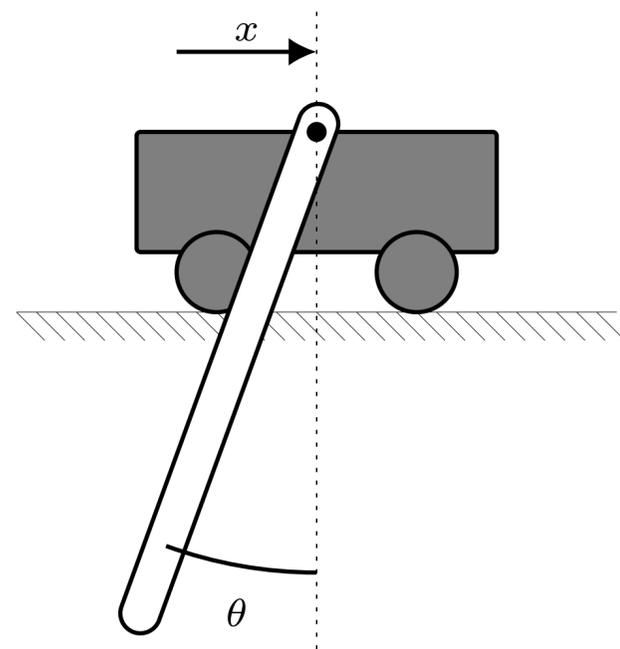
# Reinforcement Learning

SFR's uncertainty can guide exploration in model-based RL

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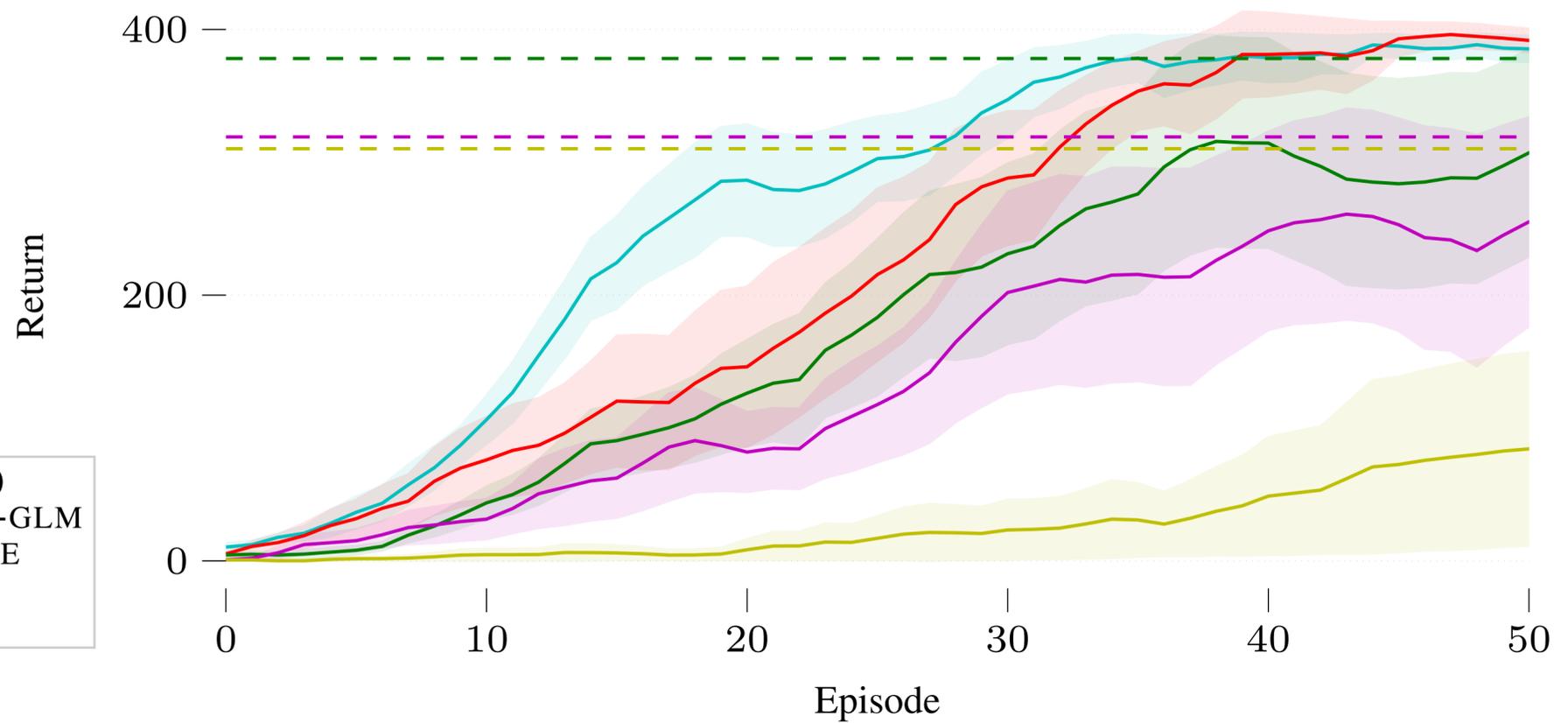
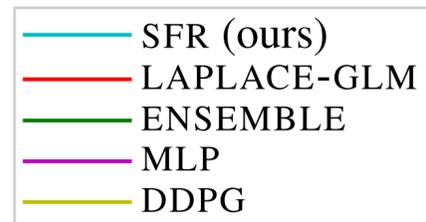
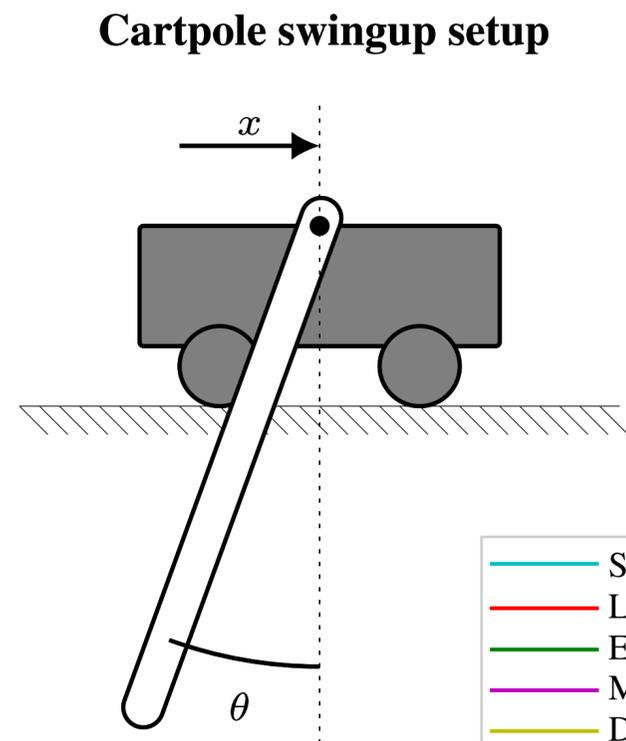
SFR's uncertainty can guide exploration in model-based RL

Cartpole swingup setup



# Reinforcement Learning

SFR's uncertainty can guide exploration in model-based RL



# Overview

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	<b>SFR (Ours)</b>	<b>GP</b>	<b>NN</b>
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# Overview

	SFR (Ours)	GP	NN
Uncertainty estimates	✓	✓	✗

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Large data	✓	✗	✓

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	SFR (Ours)	GP	NN
Uncertainty estimates	✓	✓	✗
Image inputs	✓	✗	✓
Large data	✓	✗	✓
Incorporate new data fast	✓	✓	✗

# Thanks!

Project Website



<https://aaltoml.github.io/sfr/>

Code



**Aidan Scannell\*, Riccardo Mereu\*, Paul Edmund Chang, Ella Tamir, Joni Pajarinen, Arno Solin**

*\*Equal contribution*