

Nonlinear Model Reduction for Operator Learning

Hamidreza Eivazi*, Stefan Wittek & Andreas Rausch
ISSE, Clausthal University of Technology, 38678 Clausthal-Zellerfeld, DE

The Twelfth International Conference on Learning Representations
May 7-11 2024, Vienna, Austria

✉ *he76@tu-clausthal.de

Operator learning

Let us consider \mathcal{U} and \mathcal{V} as two separable Banach spaces and assume that

$$\mathcal{G} : \mathcal{U} \longrightarrow \mathcal{V}$$

is an arbitrary operator.

Operator learning

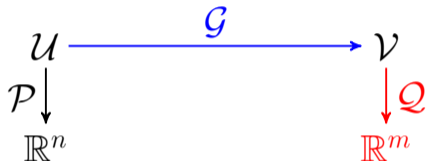
Let us consider \mathcal{U} and \mathcal{V} as two separable Banach spaces and assume that

$$\mathcal{G} : \mathcal{U} \longrightarrow \mathcal{V}$$

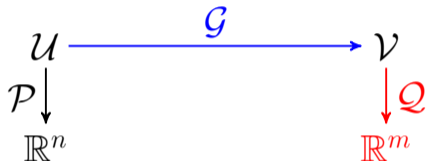
is an arbitrary operator. We only have access to partially observed input and output data $\{u_i, v_i\}_{i=1}^N$ as N elements of $\mathcal{U} \times \mathcal{V}$ such that

$$\mathcal{G}(u_i) = v_i, \quad i = 1, \dots, N.$$

Operator learning



Operator learning

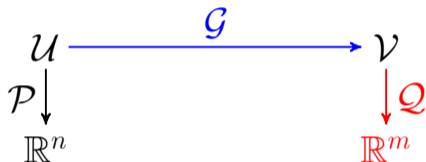


We consider \mathcal{P} and \mathcal{Q} as two linear and bounded evaluation operators

$$\mathcal{P} : u \mapsto (u(\mathbf{x}_1), u(\mathbf{x}_2), \dots, u(\mathbf{x}_n))^T,$$

$$\mathcal{Q} : v \mapsto (v(\mathbf{y}_1), v(\mathbf{y}_2), \dots, v(\mathbf{y}_m))^T.$$

Operator learning



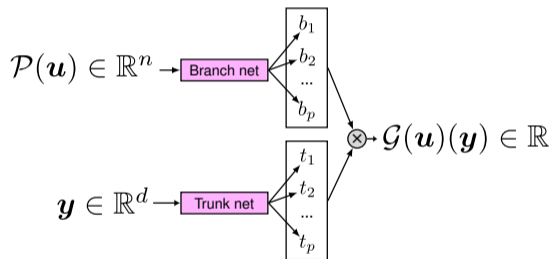
We consider \mathcal{P} and \mathcal{Q} as two linear and bounded evaluation operators

$$\mathcal{P} : u \mapsto (u(\mathbf{x}_1), u(\mathbf{x}_2), \dots, u(\mathbf{x}_n))^T,$$

$$\mathcal{Q} : v \mapsto (v(\mathbf{y}_1), v(\mathbf{y}_2), \dots, v(\mathbf{y}_m))^T.$$

Considering $U_i = \mathcal{P}(u_i)$ and $V_i = \mathcal{Q}(v_i)$, our goal is to learn \mathcal{G} from dataset $\{U_i, V_i\}_{i=1}^N$.

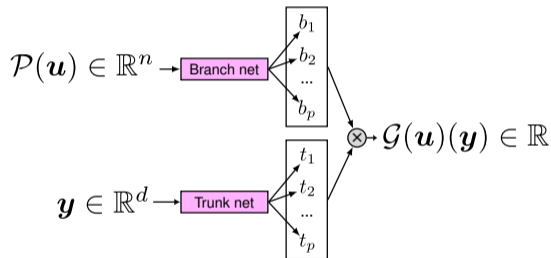
Deep operator networks (DeepONets)



Deep operator networks (DeepONets)

Operator \mathcal{G} can be approximated as

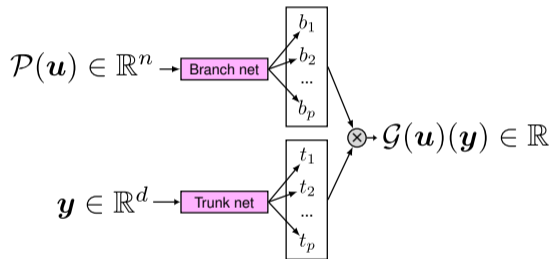
$$\mathcal{G}(u)(\mathbf{y}) \approx \sum_{k=1}^p b_k(U)t_k(\mathbf{y}) + b_0$$



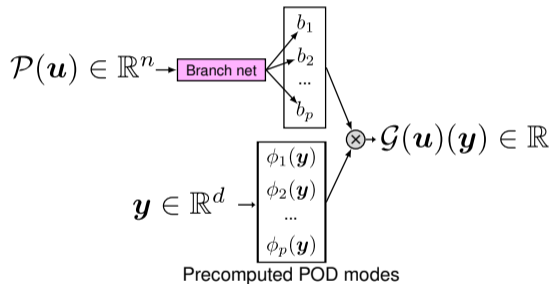
Deep operator networks (DeepONets)

Operator \mathcal{G} can be approximated as

$$\mathcal{G}(u)(\mathbf{y}) \approx \sum_{k=1}^p \underbrace{b_k(U)t_k(\mathbf{y})}_{\text{linear reconstruction}} + b_0$$



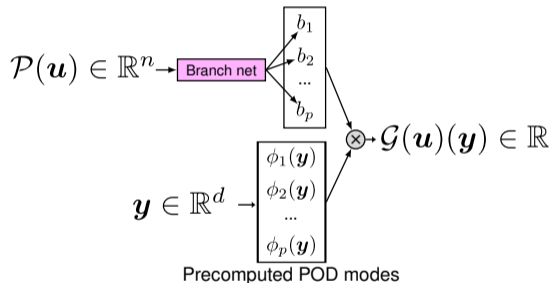
Proper orthogonal decomposition (POD)-DeepONets



Proper orthogonal decomposition (POD)-DeepONets

Trunk net is replaced by a set of POD basis functions

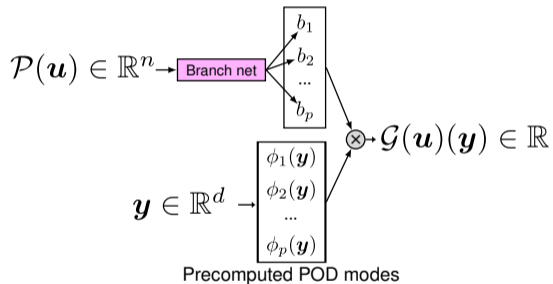
$$\mathcal{G}(u)(\mathbf{y}) \approx \sum_{k=1}^p b_k(U) \phi_k(\mathbf{y}) + \phi_0(\mathbf{y})$$



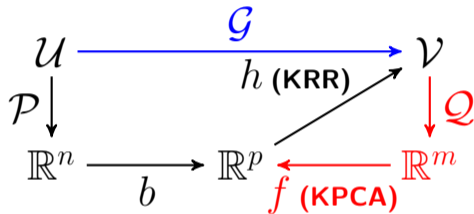
Proper orthogonal decomposition (POD)-DeepONets

Trunk net is replaced by a set of POD basis functions

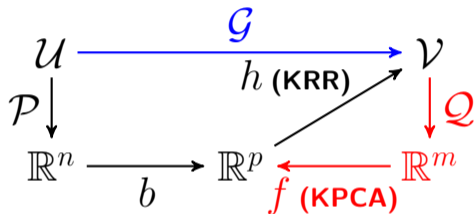
$$\mathcal{G}(u)(\mathbf{y}) \approx \sum_{k=1}^p \underbrace{b_k(U)\phi_k(\mathbf{y})}_{\text{linear reconstruction}} + \phi_0(\mathbf{y})$$



Kernel principal component analysis (KPCA)-DeepONets



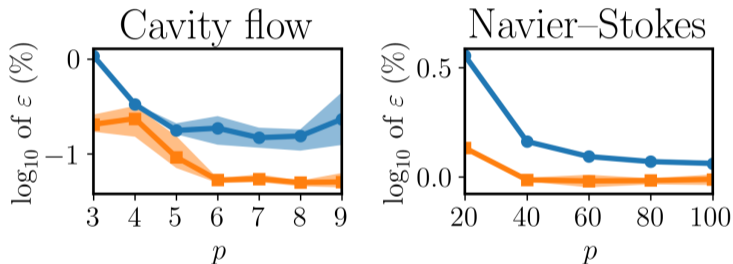
Kernel principal component analysis (KPCA)-DeepONets



Operator \mathcal{G} can be approximated as

$$\mathcal{G}(u)(\mathbf{y}) \approx \sum_{i=1}^N \alpha_i(\mathbf{y}) k_z(\mathbf{b}(U), \mathbf{z}_i^t) + \phi_0(\mathbf{y}).$$

Numerical experiments



Comparison of KPCA-DeepONet (orange, ■) and POD-DeepONet (blue, ●).

Numerical experiments

The ℓ_2 relative errors. Results for models marked with * are taken from Lu et al. (2022)¹.

Models	Cavity flow	Navier–Stokes
KPCA-DeepONet	0.05 ± 0.00%	0.96 ± 0.05%
POD-DeepONet*	0.33 ± 0.08%	1.36 ± 0.03%
DeepONet*	1.20 ± 0.23%	1.78 ± 0.02%
FNO*	0.63 ± 0.04%	1.81 ± 0.02%

¹Lu Lu et al. A comprehensive and fair comparison of two neural operators (with practical extensions) based on FAIR data. Comput. Methods Appl. Mech. Eng., 2022.

Summary and conclusions

- KPCA-DeepONet benefits from kernel methods and non-linear model reduction.
- KPCA-DeepONet provides a non-linear reconstruction.
- Our method results in less than 1% error for the Navier–Stokes test case.

Thank you!

Any questions?

Installation

```
pip install kpca-deeponet
```

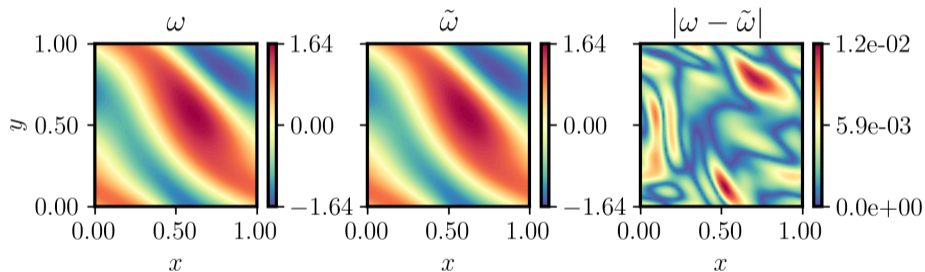
GitHub



Paper

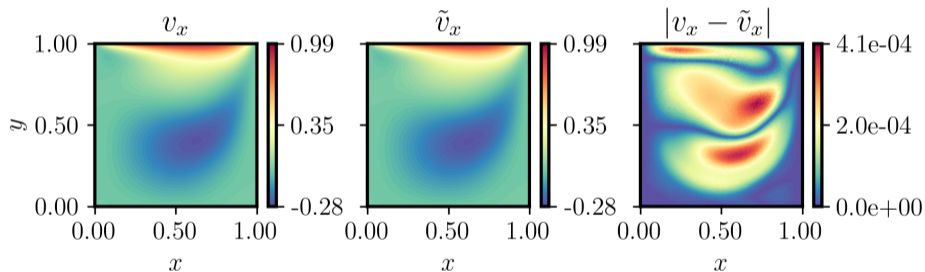


Numerical experiments



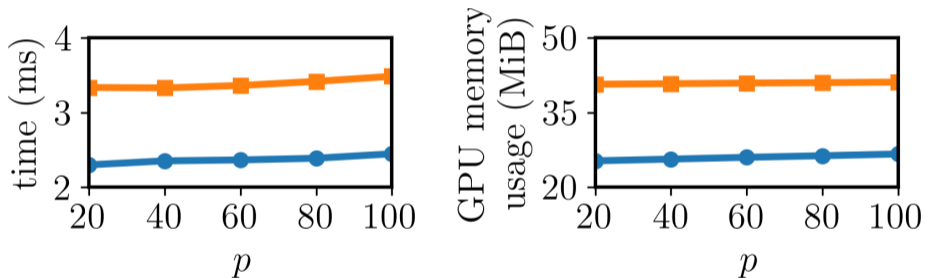
KPCA-DeepONet prediction against the reference data for one sample of the test dataset for the Navier–Stokes equation. $\tilde{\omega}$ indicates the KPCA-DeepONet prediction.

Numerical experiments



KPCA-DeepONet prediction against the reference data for one sample of the test dataset for the cavity flow. $\tilde{\cdot}$ indicates the KPCA-DeepONet prediction.

Computational cost



Comp. cost and GPU mem. usage for the proposed KPCA-DeepONet (orange, ■) and POD-DeepONet (blue, ●).