

# **Reward Dimension Reduction for Scalable Multi-Objective Reinforcement Learning**

**(QR code is changed. Use the one here :) )**

Giseung Park, Youngchul Sung



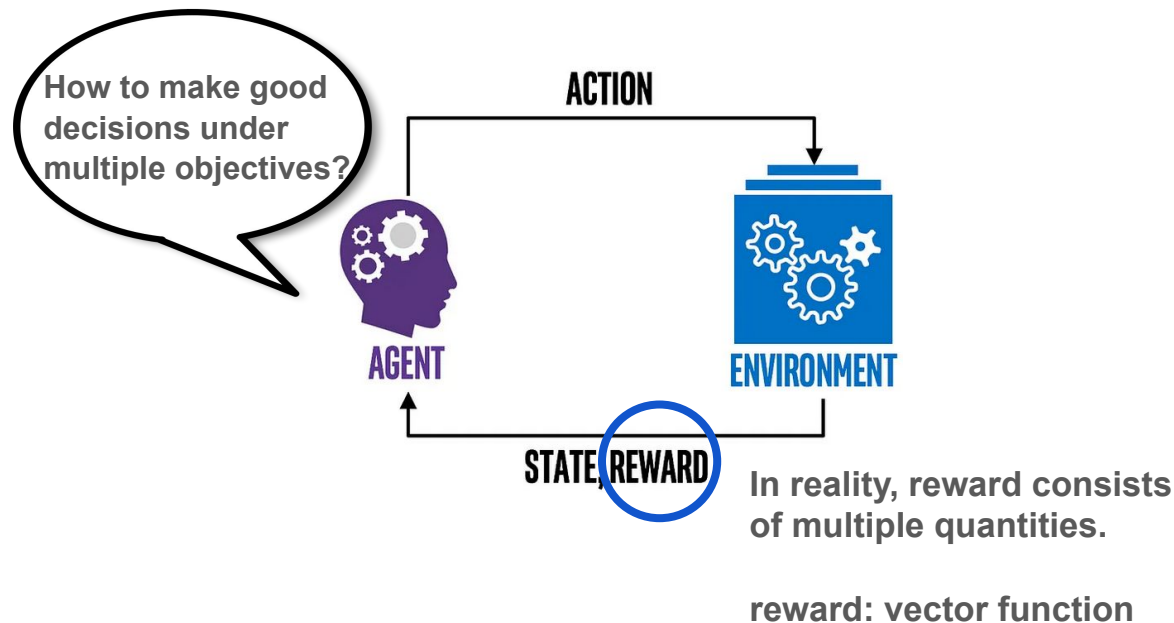
# Giseung Park

Giseung Park is seeking a **postdoctoral position** in RL!



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# Multi-Objective Reinforcement Learning (MORL)



# MORL and Reward Uncertainty

## (Scalar) Reward uncertainty set $\mathbf{R}$ (Regan and Boutilier, 2010)

- Strategy: conservative vs multiple-trial
  - Bounded convex polytope
  - Vertex functions = quantities we are interested in or able to measure.
1. Conservative strategy = max-min MORL (Park et al., 2024)
  2. Multiple-trial strategy = multi-policy MORL with linear scalarization

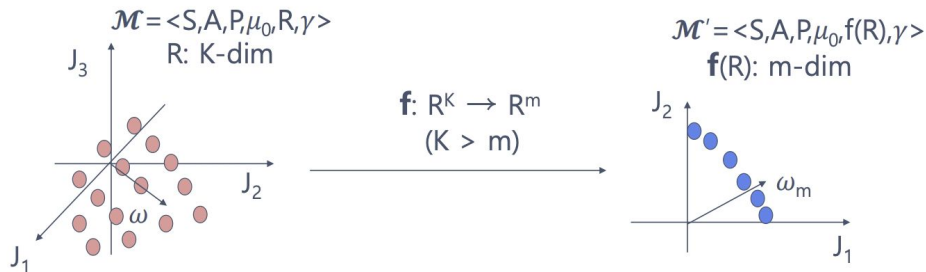
$$\max_{\pi(\cdot|\cdot, \omega)} \omega^\top \left( \mathbb{E}_\pi \left[ \sum_{t=0}^{\infty} \gamma^t \mathbf{r}_t \right] \right) = \mathbb{E}_\pi \left[ \sum_{t=0}^{\infty} \gamma^t (\omega^\top \mathbf{r}_t) \right], \forall \omega \in \Omega.$$

# Multi-Policy MORL

## Key Challenge

Multi-policy MORL struggles with scalability, but objectives often exhibit correlations. However, few online dimension reduction methods exist.

**Solution:** **Online** reward dimension reduction method ensuring Pareto-optimality



	Base	PCA	AE	NPCA	Ours
<b>HV</b> ( $\times 10^{61}$ , $\uparrow$ )	$4.4 \pm 6.8$	0	$0.007 \pm 0.018$	$19.4 \pm 15.3$	<b><math>166.9 \pm 48.1</math></b>
<b>SP</b> ( $\times 10^5$ , $\downarrow$ )	$1842 \pm 1290$	$3837 \pm 2164$	$7834 \pm 3323$	$34.2 \pm 52.3$	<b><math>2.3 \pm 1.0</math></b>

# Poster Information + more

- Thu 24 April. Hall 3 + Hall 2B #398
- 3 p.m. — 5:30 p.m. Singapore time
- Let's chat!

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