









VCR: A Task for Pixel-Level Complex Reasoning in Vision Language Models via Restoring Occluded Text

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Visual Caption Restoration (VCR) Overview

In this paper, we introduce:

- A Task: <u>Visual Caption Restoration (VCR)</u>
- 2. A Dataset + Benchmark: VCR-Wiki
- 3. A Hidden Test: VCR-Hidden

"What are the covered texts in the image?"



difficient of American automobile manufacturer Ford. Marketed brands in the United States, for

The VCR Task





division of American automobile manufacturer Ford. Marketed

English

Chinese



Hard



manufacturer Ford. Marketed



The <u>VCR-Wiki Dataset</u>

Latest data source, multi-lingual, multi-fonts, multi-resolution, multi-layout

Should people with become for parking? As part of a public consultation, it is asking for views on whether residents with become which should pay more for permits.



The <u>VCR-Hidden Test</u>

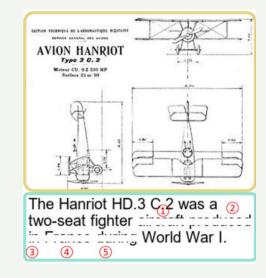


The Visual Caption Restoration (VCR) Task

- 1. A task: <u>Visual Caption Restoration (VCR)</u>
 - Task: given an image with two parts: a visual element and partly-occluded text-in-image, restore the covered text
 - A typical thinking process for this task involves using pixel-level hints for texts and multi-step reasoning

Characteristics:

- Unsolvable by OCR: the remaining pixels of the covered texts are crucial and hard to use
- Have deterministic answer: the remaining pixels gives definitive answer; No LLM-as-a-judge needed
- Flexibility: over covered area size, text to cover...



- **1**. This image is very likely about a manual of an old fashion plane.
- **2**. The visible pixel level hint of 1 shows that it is a word ending with "ft". Given the previous word is "fighter", the first blank is likely "aircraft".
- 3. The title of the manual mentioned "HANRIOT" which is a French manufacturer.
- 4. 4 start from "F" thus, combined with 4, we induce it should be "France".
- 5. It is very likely that we need a "adj." between "France" and "World War I". Given 5 ends with "g" and start with "d". We can infer it is "during".
- **6**. **2** start from "p" and end with "d". It needs to be a verb. Connecting with **4**, it is "produced".
- 7. 3 is a word starting from "i" and only has 2 character. It evident that it is "in".



The VCR-Wiki Dataset

- 2. A Dataset + Benchmark: <u>VCR-Wiki</u>
 - Sourced from Wikipedia dump
 - Multilingual: Contains En and Zh splits
 - Multi-difficulty: Contains easy and hard splits:
 - Easy: The text cover causes OCR to completely fail
 - Hard: Only 1-2 pixels left on the top and bottom
 - The easy / hard performance are directly comparable, with exact same splits and texts and only pixel-level difference on the cover
 - Contains train / val / test sets
 - SFT on the training set can improve real-world occluded text recognition

Easy



Lincoln is the lummy rehiels
division of American automobile
manufacturer Ford. Marketed
among the top lummy rehiels
brands in the United States for



料西嘉是地中海西部的一座岛屿, 也是法国的 个学 领土集体,位于法国大陆部分的东南面,意大利 半岛的西面,最近的地块是紧邻志 大和的撒丁岛。科西嘉岛三分之二

Hard



Lincoln : " ' of American automobile manufacturer Ford. Marketed brands in the United States, for



科西嘉是地中海西部的一座岛屿, 也二二二二二二二二二条 领土集体,二 丁二二二二二二二二条 南面,意大利 半岛的西面,最近的地块二二二二 半岛的西面,最近的地块二二二二



The VCR-Hidden Hidden Test

- 3. A Hidden Test: <u>VCR-Hidden</u>
 - To avoid data contamination on VCR-Wiki's test set, we created a hidden test for VCR:
 - Up-to-date source: we use latest news to update the data source
 - More flexible data: the data contains multilingual, multi-fonts, multi-resolution, multilayout VCR images for maximum flexibility

Should people with bigger and pury more for parking? As part of a public consultation, it is asking for views on whether and dente with larger whiche should pay more for permits.







Huge Gap Between SoTA VLM and Human

Table 4: Human evaluation results on the VCR task for in terms of exact matches. N is the number of puzzles in each language.

	EN Easy (N = 169)		EN Hard (N = 169)		ZH Easy (N = 188)		ZH Hard (N = 188)	
	Mean (%)	SD (%)						
All	96.65	0.34	91.12	1.18	98.58	0.31	91.84	0.81
Filtered	98.62	0.34	97.63	2.13	99.47	0.00	96.63	1.11

Native speakers can very easily achieve ~100% restoration accuracy on VCR-Wiki!

Language	Mode	Model name	Model size	Exact match (%) ↑			Jaccard index (%) ↑			
				VI + TEI	TEI	Δ	VI + TEI	TEI	Δ	
			Closed-source models							
		Claude 3 Opus	-	37.80.28	$50.0_{0.33}$	-12.2	57.680.8	$70.16_{0.64}$	-12.48	
		Claude 3.5 Sonnet	-	$41.74_{1.69}$	$44.72_{1.78}$	-2.98	$56.15_{1.46}$	$58.54_{1.6}$	-2.4	
		Gemini 1.5 Pro	-	$28.07_{1.58}$	$38.76_{1.68}$	-10.68	$51.9_{1.22}$	$59.62_{1.27}$	-7.72	
		GPT-4 Turbo	-	$45.15_{0.28}$	$48.64_{0.57}$	-3.5	$65.72_{0.25}$	$67.86_{0.2}$	-2.14	
		GPT-40	-	$73.2_{0.16}$	$82.43_{0.17}$	-9.22	$86.17_{0.21}$	$92.01_{0.2}$	-5.84	
		GPT-4V	-	$25.83_{0.44}$	$14.95_{0.3}$	10.87	$44.63_{0.48}$	$30.08_{0.67}$	14.56	
		Qwen-VL-Max	-	$41.65_{0.32}$	$52.72_{0.2}$	-11.07	$61.18_{0.35}$	$70.19_{0.37}$	-9.01	
		Reka Core	-	$6.71_{0.89}$	$11.18_{1.15}$	-4.47	$25.84_{0.95}$	$35.83_{1.05}$	-9.99	
	Open-source models									
English	Hard	CogVLM2	19B	$37.98_{0.18}$	$17.68_{0.06}$	20.3	$59.99_{0.05}$	$39.69_{0.03}$	20.3	
		DeepSeek-VL	1.3B	$0.16_{0.01}$	$0.39_{0.02}$	-0.23	$11.89_{0.02}$	$11.47_{0.03}$	0.42	
		DeepSeek-VL	7B	$1.0_{0.02}$	$1.75_{0.03}$	-0.75	$15.9_{0.08}$	$17.2_{0.04}$	-1.3	
		DocOwl-1.5-Omni	8B	$0.04_{0.0}$	$0.02_{0.0}$	0.01	$7.76_{0.01}$	$7.74_{0.02}$	0.03	
		Monkey	7B	$1.96_{0.04}$	$2.43_{0.03}$	-0.48	$14.02_{0.03}$	$14.11_{0.03}$	-0.09	
		Idefics2	8B	$0.65_{0.01}$	$0.94_{0.02}$	-0.29	$9.93_{0.05}$	$12.57_{0.02}$	-2.64	
		InternLM-XComposer2-VL	7B	$0.7_{0.01}$	$0.92_{0.01}$	-0.22	$12.51_{0.02}$	$13.23_{0.02}$	-0.72	
		InternVL-V1.5	25.5B	$1.99_{0.02}$	$6.49_{0.04}$	-4.5	$16.73_{0.06}$	$26.4_{0.03}$	-9.67	
		MiniCPM-V2.5	8B	$1.41_{0.03}$	$1.96_{0.02}$	-0.55	$11.94_{0.02}$	$13.37_{0.04}$	-1.43	
		Qwen-VL	7B	$2.0_{0.03}$	$2.32_{0.03}$	-0.32	$15.04_{0.05}$	$14.27_{0.05}$	0.77	
		Yi-VL	34B	$0.07_{0.0}$	$0.05_{0.0}$	0.02	$4.31_{0.02}$	$5.89_{0.02}$	-1.58	

English Hard

			-	Closed-source model					
	Claude 3 Opus	-	$0.3_{0.18}$	$0.1_{0.1}$	0.2	$9.22_{0.38}$	$8.09_{0.33}$	1.13	
	Claude 3.5 Sonnet	-	$0.2_{0.15}$	$0.0_{0.0}$	0.2	$4.0_{0.33}$	$2.37_{0.23}$	1.63	
	Gemini 1.5 Pro	-	$0.7_{0.26}$	$0.5_{0.23}$	0.2	$11.82_{0.51}$	$11.75_{0.44}$	0.07	
	GPT-4o	-	$2.2_{0.47}$	$1.8_{0.4}$	0.4	$22.72_{0.67}$	$22.89_{0.65}$	-0.17	
	GPT-4 Turbo	-	$0.0_{0.0}$	$0.2_{0.13}$	-0.2	$8.58_{0.3}$	$6.87_{0.28}$	1.72	
	Qwen-VL-Max	-	$0.89_{0.06}$	$1.38_{0.1}$	-0.49	$5.4_{0.19}$	$12.29_{0.18}$	-6.89	
	Reka Core	-	$0.0_{0.0}$	$0.0_{0.0}$	0	$3.35_{0.23}$	$2.97_{0.2}$	0.38	
Open-source models									
Hard	CogVLM2-Chinese	19B	$1.34_{0.03}$	$2.67_{0.02}$	-1.32	17.350.03	$19.51_{0.03}$	-2.16	
	CogVLM2-Chinese-FT	19B	$42.11_{0.09}$	$45.63_{0.06}$	-3.51	$65.67_{0.15}$	$69.28_{0.04}$	-3.61	
	DeepSeek-VL	1.3B	$0.0_{0.0}$	$0.0_{0.0}$	0	$6.46_{0.01}$	$3.22_{0.02}$	3.24	
	DeepSeek-VL	7B	$0.0_{0.0}$	$0.0_{0.0}$	0	$5.11_{0.01}$	$7.21_{0.01}$	-2.1	
	DocOwl-1.5-Omni	8B	$0.0_{0.0}$	$0.0_{0.0}$	0	$1.37_{0.01}$	$4.07_{0.02}$	-2.7	
	Monkey	7B	$0.12_{0.01}$	$0.07_{0.0}$	0.05	$6.36_{0.01}$	$6.68_{0.03}$	-0.32	
	InternLM-XComposer2-VL	7B	$0.07_{0.01}$	$0.09_{0.0}$	-0.02	$8.97_{0.02}$	$8.51_{0.01}$	0.46	
	InternVL-V1.5	25.5B	$0.03_{0.0}$	$0.1_{0.01}$	-0.07	$8.46_{0.01}$	$6.27_{0.04}$	2.19	
	MiniCPM-V2.5	8B	$0.09_{0.0}$	$0.08_{0.0}$	0.01	$7.39_{0.02}$	$7.89_{0.01}$	-0.5	
	MiniCPM-V2.5-FT	8B	$1.53_{0.01}$	$1.11_{0.02}$	0.42	$18.0_{0.03}$	$15.35_{0.02}$	2.65	
	Qwen-VL	7B	$0.01_{0.0}$	$0.01_{0.0}$	0	$1.17_{0.01}$	$0.12_{0.0}$	1.06	
	Yi-VL	34B	$0.0_{0.0}$	$0.0_{0.0}$	0	$4.12_{0.0}$	$1.81_{0.01}$	2.31	
	Yi-VL	6B	$0.0_{0.0}$	$0.0_{0.0}$	0	$4.0_{0.01}$	$1.88_{0.01}$	2.12	

Chinese Hard

... Yet a lot of SoTA VLMs achieve <u>nearly 0 restoration accuracy</u> on VCR-Wiki

More interesting findings (and VLM development guidelines) in the paper





See You in Poster Session 2!









arXiv

GitHub

Hugging Face

OpenReview



Test with EvolvingLMMs-Lab/lmms-eval

EvolvingLMMs-Lab/Imms-eval:
Accelerating the development of large
multimodal models (LMMs) with Immseval (github.com)



Test with open-compass/VLMEvalKit

open-compass/VLMEvalKit: Opensource evaluation toolkit of large visionlanguage models (LVLMs), support GPT-4v, Gemini, QwenVLPlus, 50+ HF models, 20+ benchmarks (github.com)

