



DICE: End-to-end Deformation Capture of Hand-Face Interactions from a Single Image Qingxuan Wu¹, Zhiyang Dou^{1,2,7,*} Sirui Xu³, Soshi Shimada⁴, Chen Wang¹, Zhengming Yu⁶, Yuan Liu², Cheng Lin²,

(*Corresponding Authors)



™ Video **ICLR 2025**



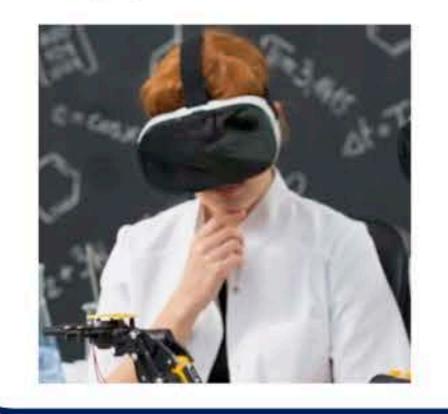




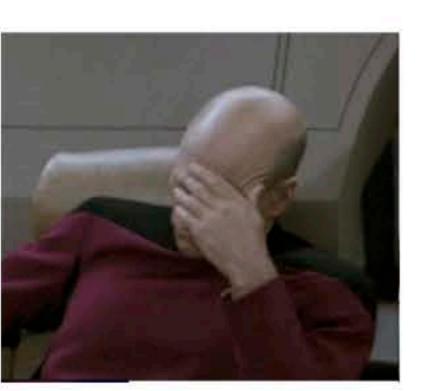
Zeyu Cao⁵, Taku Komura^{2,7}, Vladislav Golyanik⁴, Christian Theobalt⁴, Wenping Wang⁶, Lingjie Liu^{1,*} University of Pennsylvania¹, The University of Hong Kong², University of Illinois Urbana-Champaign³, Max Planck Institute for Informatics⁴, University of Cambridge⁵, Texas A&M University⁶, TransGP⁷

Motivation

- Hand-face interaction is a common behavior observed up to 800 times per day across all ages and genders.
- Hand-face interaction recovery with deformations has applications in AR/VR, character animation, and human behavior analysis.
- Accurate + real-time method required for time-sensitive applications.





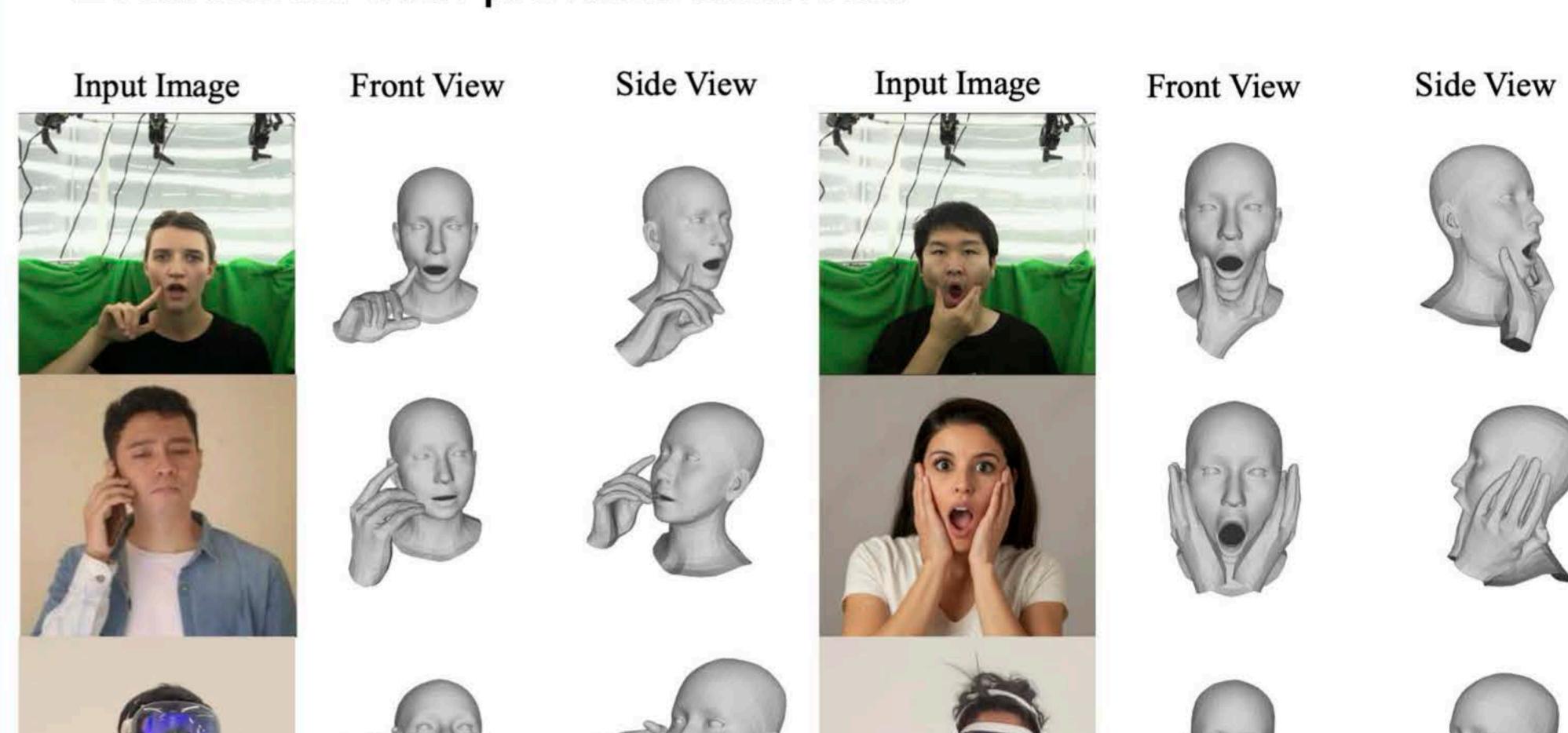




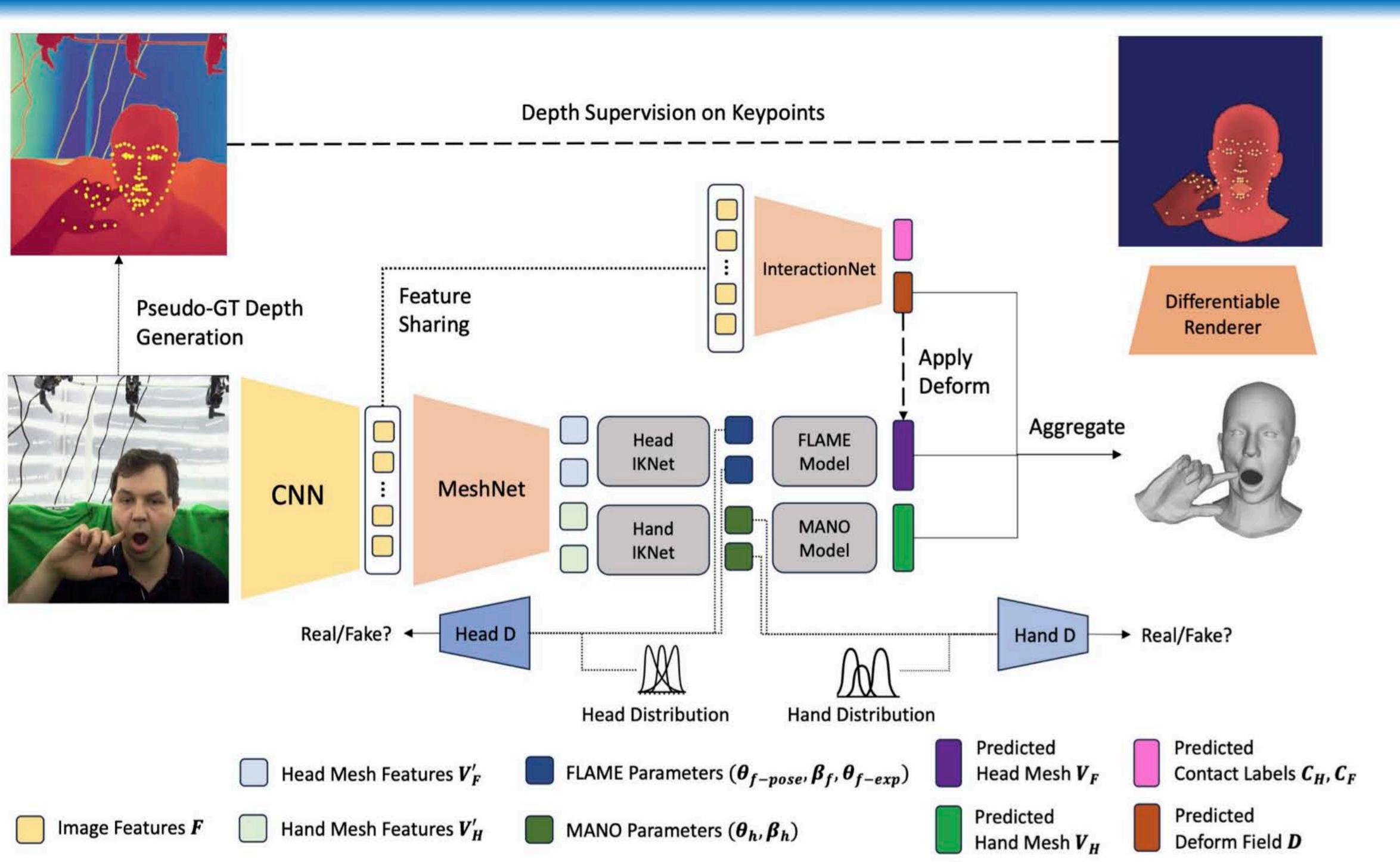


Introduction

- DICE is the first end-to-end method for Deformation aware handface Interaction recovery from a single image.
- DICE achieves SOTA performance on standard benchmark and in-the-wild data in terms of accuracy and physical plausibility.
- Additionally, DICE runs at 20 fps on an Nvidia 4090 GPU, up to 200x faster than previous methods.



Method



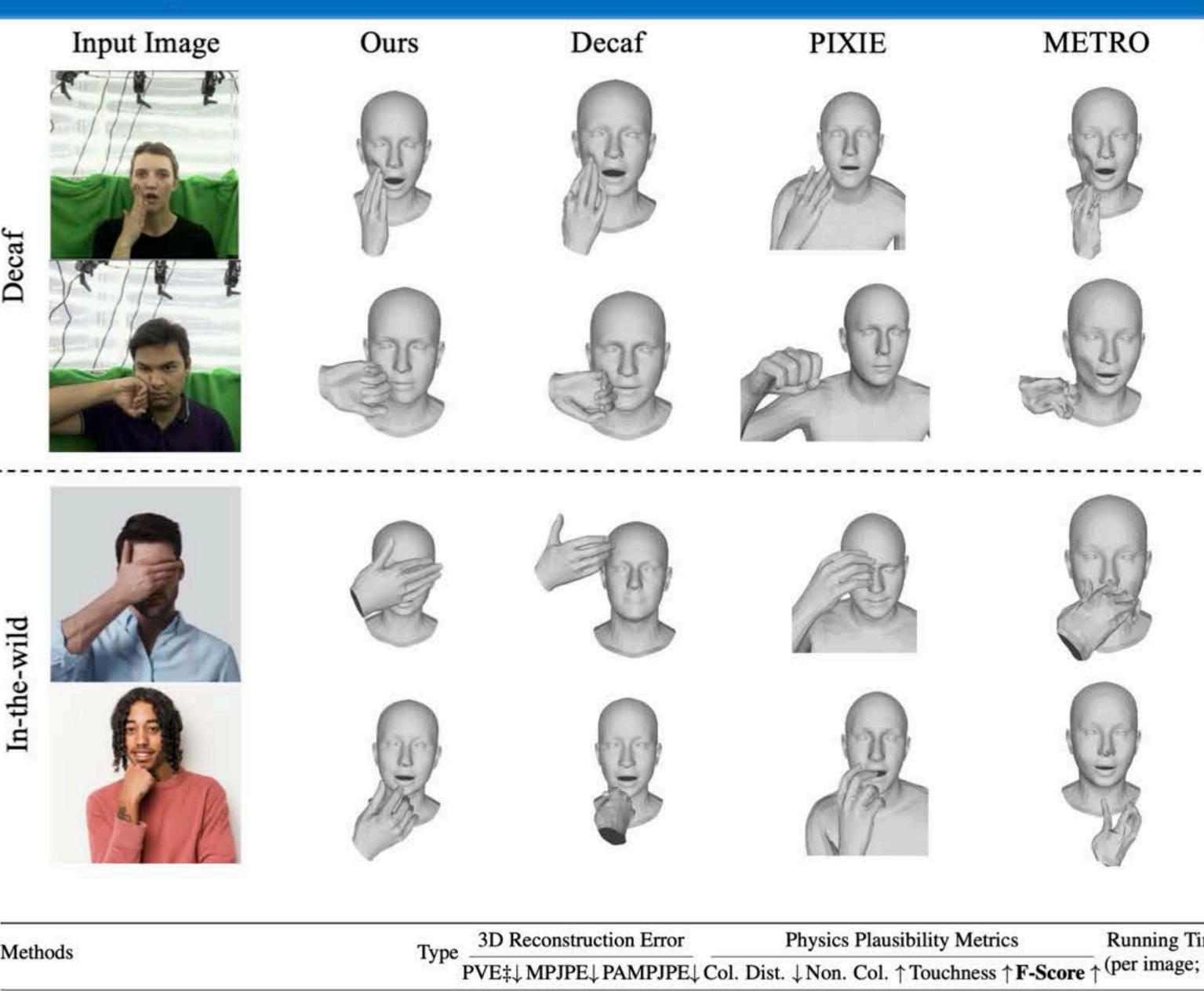
Transformer-based Hand-face Interaction Recovery

- HRNet-W64 CNN extracts feature from single-image input.
- Feature is passed to Transformer-based MeshNet and InteractionNet:
- MeshNet extracts hand and face mesh features;
- InteractionNet predicts per-vertex hand-face contact probabilities and face deform fields.
- The IKNets regress FLAME (face) and MANO (hand) parameters as well as rotation/translation parameters.
- Face and hand mesh is obtained from FLAME and MANO forward pass.
- The deformation field predicted by InteractionNet is applied to the face mesh.

Weakly-Supervised Training Scheme

- In-the-wild images are used to enhance generalizing capability.
- Pseudo-GT depth and 2D keypoints are annotated with off-the-shelf models and used for supervision.
- Adversarial training with hand-/face- only dataset is employed to constrain the face and hand parameter distribution.

Comparison with Previous Methods



Methods	Type	3D Reconstruction Life			Thysics Tlausionity Wicties				Running Time
		PVE‡↓	MPJPE.	PAMPJPE.	Col. Dist.	↓Non. Col.	↑Touchness	↑F-Score	↑ (per image; s)↓
Compa						ed methods			
Decaf (Shimada et al., 2023)	0	9.65	5 2	-	1.03	83.6	96.6	89.6	19.59
Benchmark (Lugaresi et al., 2019; Li et al., 2017)	0	17.7	1	2-2	19.3	64.2	73.2	68.4	16.40
PIXIE (hand+face) (Feng et al., 2021a)	O	26.3	1/	1 5 - 1 3	7.04	75.9	75.1	75.5	=
DICE (Ours)	R	8.32	9.95	7.27	0.16	66.6	79.9	72.7	0.088
Comp	ariso	n betwe	en DICI	E and regres	ssion-base	d methods			
PIXIE (whole-body) (Feng et al., 2021a)	R	39.7		1 - 1	0.11	97.1	51.8	67.6	0.070
PIXIE-R (Feng et al., 2021a)	R	11.0	22.0	21.2	0.27	62.6	83.0	72.0	0.070
METRO* (hand+face) (Lin et al., 2021a)	R	11.8	15.4	11.9	0.08	80.7	54.8	65.2	0.103
FastMETRO* (single-target) (Cho et al., 2022)	R	9.27	11.8	9.41	0.09	82.2	55.5	66.2	0.110
DICE (Ours)	R	8.32	9.95	7.27	0.16	66.6	79.9	72.7	0.088

version. O and R denote optimization-based and regression-based methods, respectively. ‡ calculated after translating the center of the head to the origin. bold denotes the best result in a comparison group. Note our method operates at an interactive rate (20 fps; 0.049s per image) on an Nvidia 4090 GPU. Here we report the runtime performance on an A6000 GPU for a fair comparison.

Qualitative Results



