

## Privately Counting Partially Ordered Data

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## Background

## Partially Ordered Data

- A poset (P, ≤) is a finite set P together with a reflexive, transitive, and anti-symmetric relation ≤.
- Example: Consider the survey:
  - $\circ$   $x_1$ : Have you been told you have hypertension?
  - x<sub>2</sub>: Have you been told multiple times?
  - $\circ$   $x_3$ : Have you had high cholesterol?

The survey structure imposes partial order  $x_2 \le x_1$ ,  $x_3$ .

 Other examples of partially ordered data include software library dependencies, coursework prerequisites, and any data encoded using directed acyclic graphs.

# Differential Privacy and the K-norm mechanism

**Definition**: Given a dataset  $D=\{d_1,\ldots,d_n\}\in\mathcal{D}$ , a randomized mechanism satisfies  $\epsilon$ -differential privacy (DP) if for any pair of databases (D, D') differing in one record, and any set of outputs

$$\mathbb{P}(\mathcal{M}(D) \in S) \leq e^{\epsilon} \mathbb{P}(\mathcal{M}(D') \in S)$$

**Lemma 1 [2]:** Given norm  $|||\cdot||$ , statistic T with  $||\cdot||$ -sensitivity  $\Delta$ , database X, the K-norm mechanism satisfies  $\epsilon$ -DP and has output density

$$f_X(y) \propto \exp\left(-\frac{\varepsilon}{\Delta} \cdot \|y - T(X)\|\right)$$

**Lemma 2 [2]:** Running the K-norm mechanism reduces to sampling the unit ball for the norm  $\|\cdot\|$ .

#### **Related Work**

- Projection [15, 13], matrix [10, 11], and factorization [4, 14] offer general but potentially slow approximations for optimal, problem-specific private additive noise. We provide a problem-specific, optimal, and fast alternative.
- Joseph and Yu [3] efficiently implemented the K-norm mechanism for improved noise distributions in sum, count, and vote problems with contribution bounds.
- Our work differs from Joseph and Yu [7] by addressing different problems needing different sampling techniques due to their unique underlying combinatorial structures and the resulting challenges in sampling their respective norm balls.

## **Contributions and Methods**

For partially ordered data, tailoring an instance of the K-norm mechanism produces a more accurate algorithm that's still fast enough to be practical.

Step 1: relate the poset ball to a known combinatorial object.

**Lemma 3.4.** The poset ball for poset  $(P^*, \preceq)$  is  $\mathcal{O}_2(P^*-r)$ , the double order polytope on the double order poset  $(P^*-r, \preceq, \preceq)$ .

#### Step 2: Efficiently sample the "known" object:

Idea:

- 1. Find *unimodular triangulation* of the polytope.
  - Disjoint subdivision of the polytope into minimal volume simplices.
  - Extended bipartitions are partitions of the nodes in two sets where each part can be extended to a total order that is compatible with the underlying partial order.
  - Extended bipartitions index a triangulation of the polytope.
- 2. Sample one simplex in the triangulation.
  - Extended bipartitions can be efficiently sampled.
  - The indexing structure can be efficiently translated into vertices of the corresponding simplex.
- 3. Sample uniformly at random from the corresponding simplex.

**Theorem 3.15.** The poset ball for  $(P^*, \preceq)$  can be sampled in time  $O(d^2)$ .

Why not rejection sampling?

**Theorem 3.17.** Rejection sampling the poset ball using any  $\ell_p$  ball is inefficient.

### Results

## Error introduced by different norms

Lemma 3.16. Proves the is the  $B^d_\infty$  is the minimum  $\ell_p$  ball containing the poset ball. Below we empirically evaluate the expected  $\ell_2$ -norm of a vector sampled from different  $\ell_p$  balls.

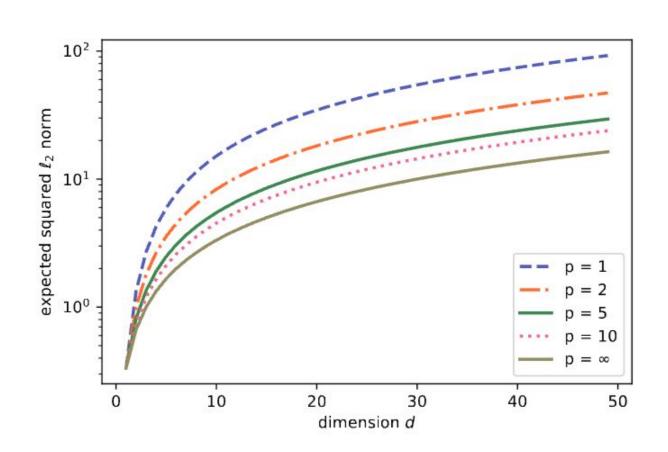
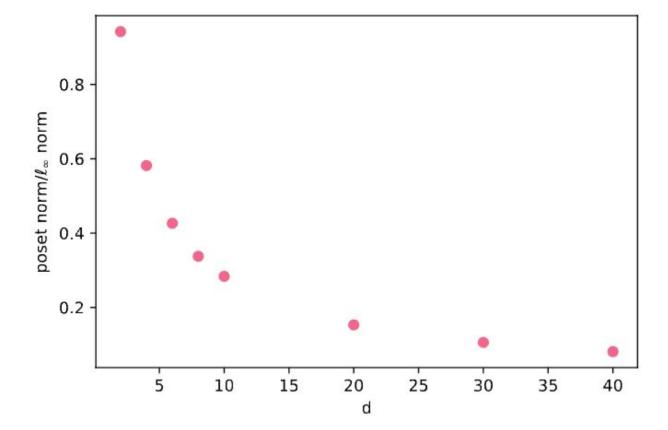


Figure 1:  $r_{p,d}^2 \mathbb{E}_2^2(B_p^d)$  (see Lemma 4.1).

## Poset mechanism vs $\ell_{\infty}$ mechanism

We uniformly sample a directed acyclic graph on a fixed number d of uniquely labeled vertices. our algorithm's advantage in terms of expected squared {2 norm widens with d.



## Error reduction on a real survey

# survey sections	poset ball squared $\ell_2$ norm / $l_\infty$ ball squared $\ell_2$ norm
1	0.414
2	0.427
3	0.408

Figure 4: NHIS average mean squared  $\ell_2$  norm ratios, from 10,000 trials each

#### References

- [1] Center for Medicare Services and Medicaid. National health interview survey. https://www.cms.gov/
- [2] Hardt, Moritz, and Kunal Talwar. "On the geometry of differential privacy. STOC 2010.