

3D StreetUnveiler with Semantic-aware 2DGS - a simple baseline

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Goal of StreetUnveiler

Remove the cars from the video captured by in-car cameras



Remove from both visual and geometry aspect

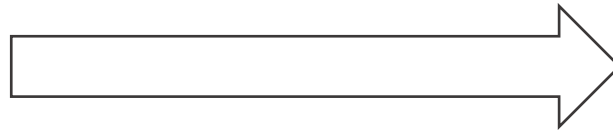


Lidar



Input

3D StreetUnveiler



Clean Street Results



Empty Street Mesh Extraction

Existing Works



[Mirzaei et.al 2023]

Small scale scenes
require ground-truth object masks

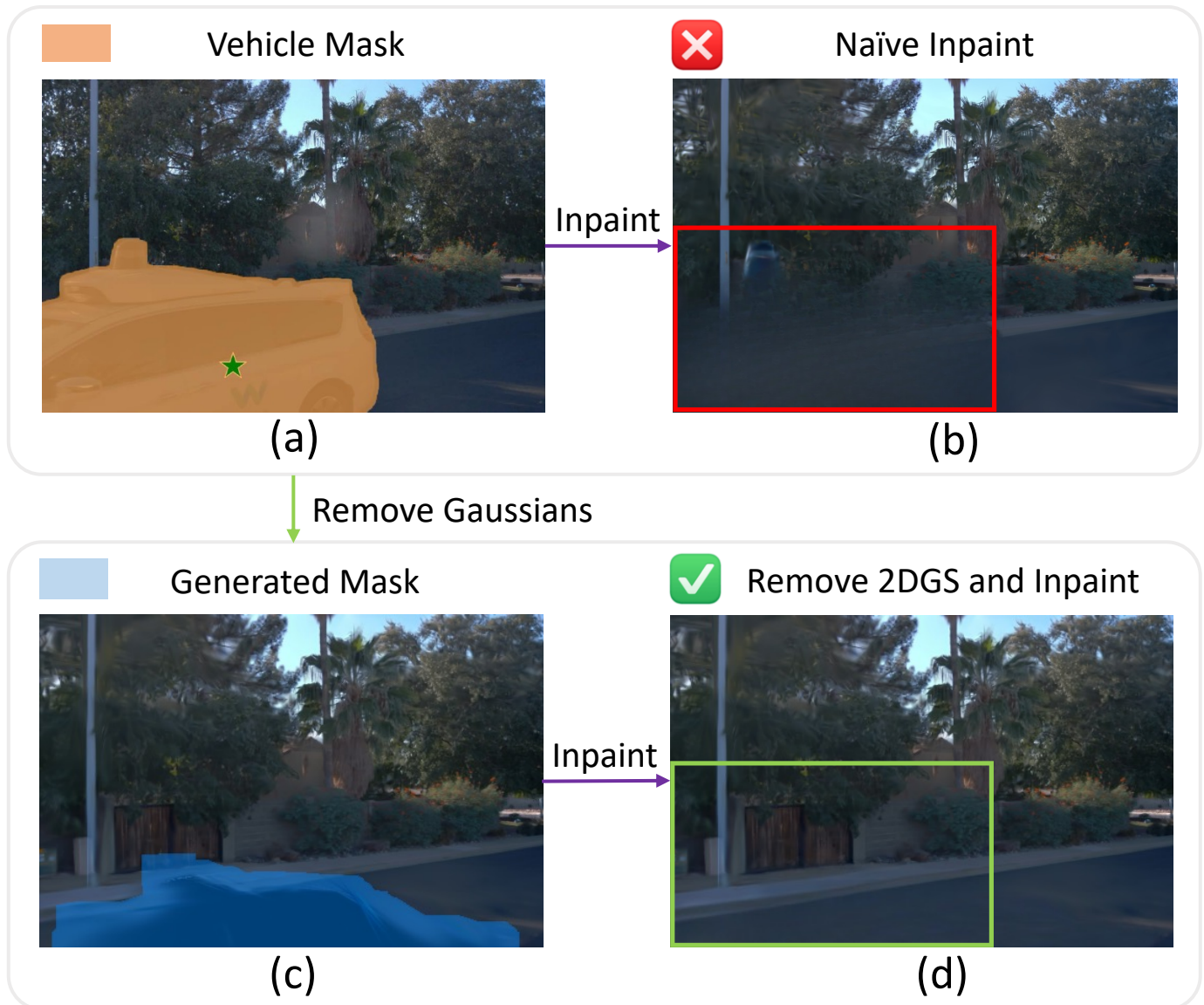
Unveiling Challenge

- Hard to get a reasonable inpainting mask
- Long trajectory / maintain consistency



Mask Challenge

- How to obtain the blue mask?



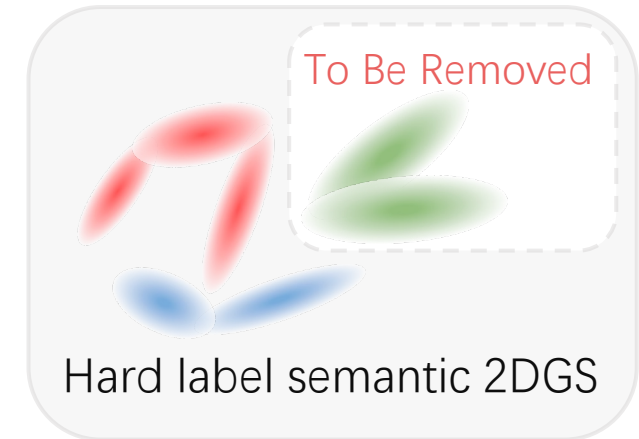
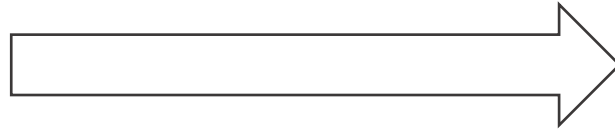
Long Trajectory Consistency Challenge



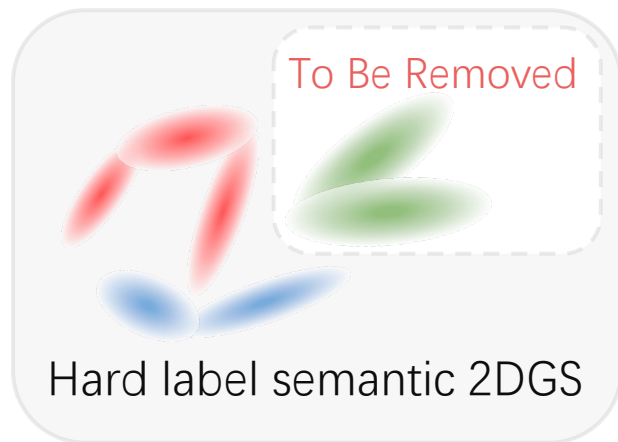
Inpaint each image seperately



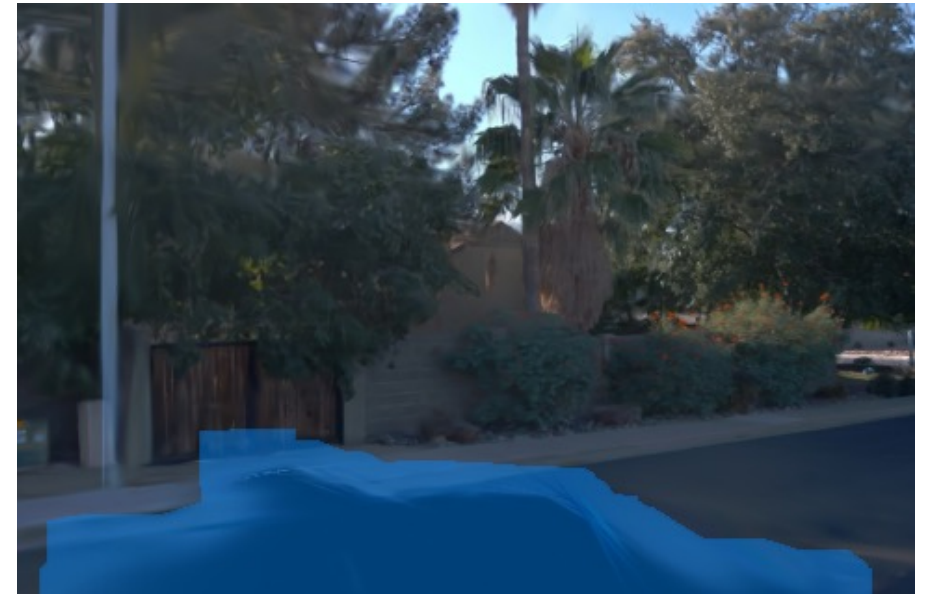
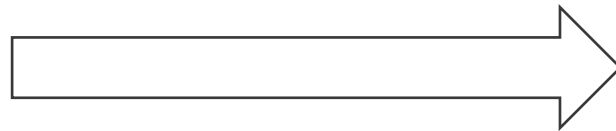
3D Reconstruction



Solution to mask challenge



Render



Some more training objectives:

$$\mathcal{L}_{\text{ds}} = \sum_k \mathcal{L}_{\text{d}}^k \quad \mathcal{L}_{\alpha} = \frac{1}{N} \sum_p \alpha_p$$

Get the mask through alpha value

Motivation: Nature of the captured video

Frame T_n

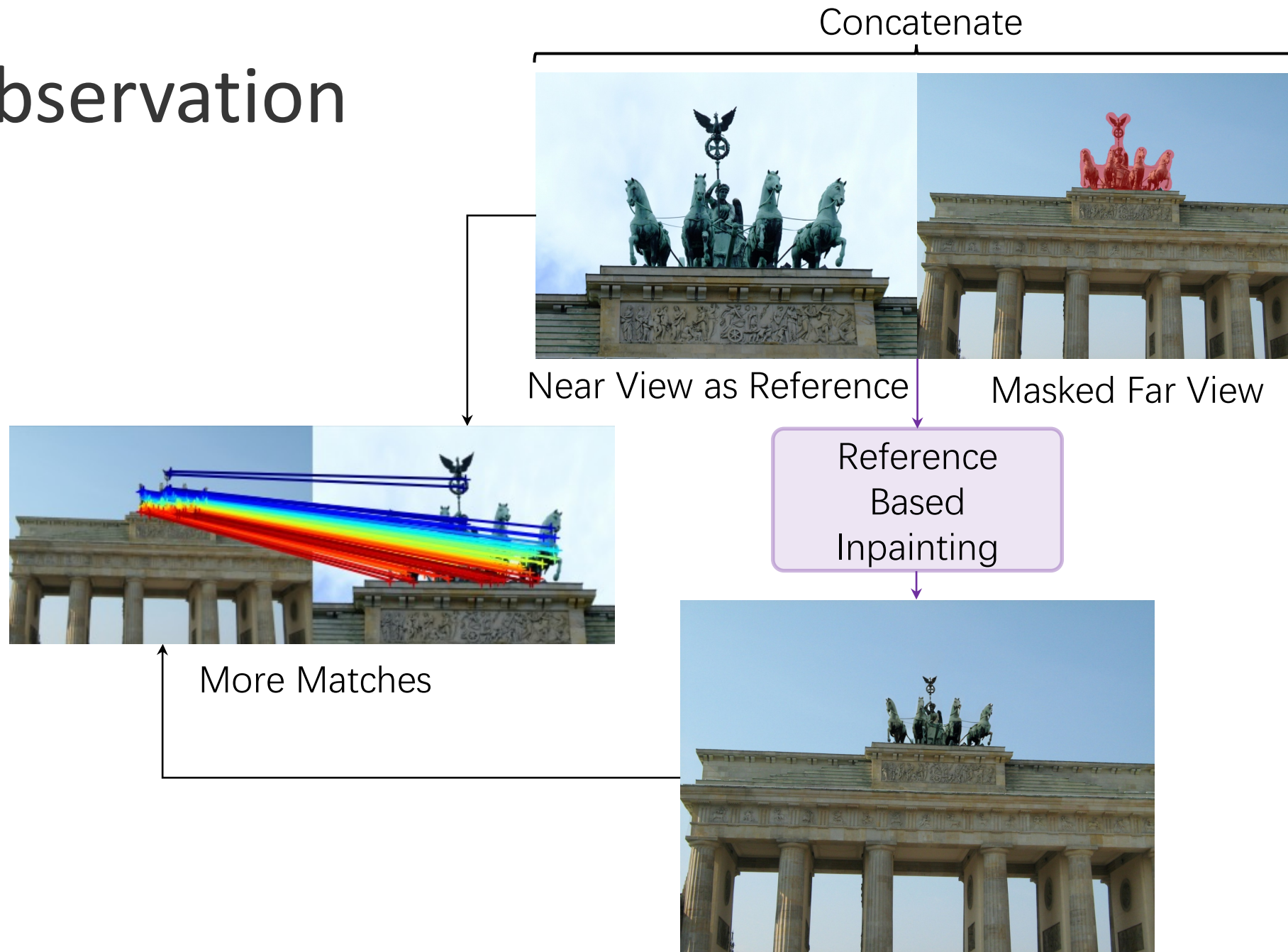


Frame T_{n+1}

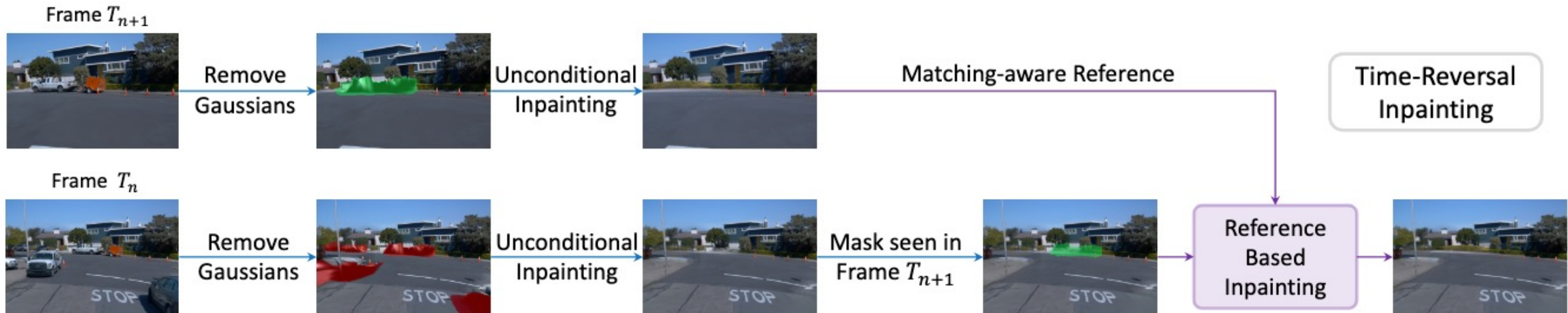


Removed object is more close in T_{n+1}

Observation

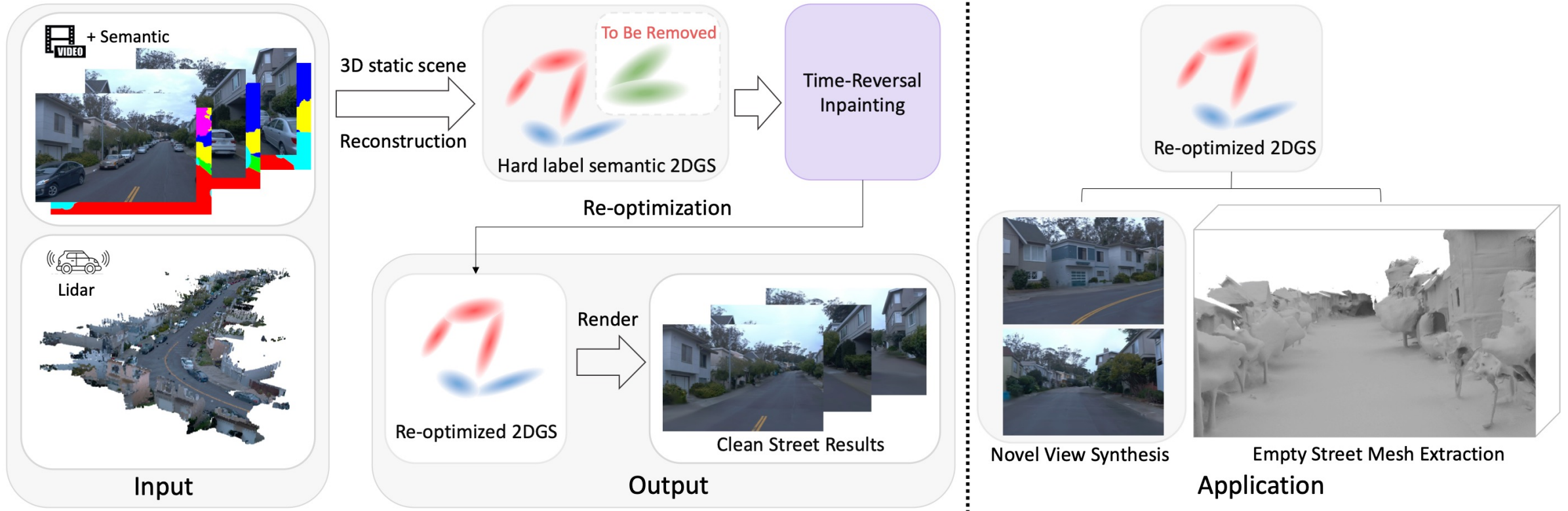


Time Reversal Inpainting



Inpaint T_n with T_{n+1} as reference

Overall Pipeline



Qualitative Results (with 2D Inpaint)



SDXL [Podell et.al 2023]

Qualitative Results (with Video Inpaint)



ProPainter [Zhou et.al 2023]

Qualitative Results (with 3D Inpaint)

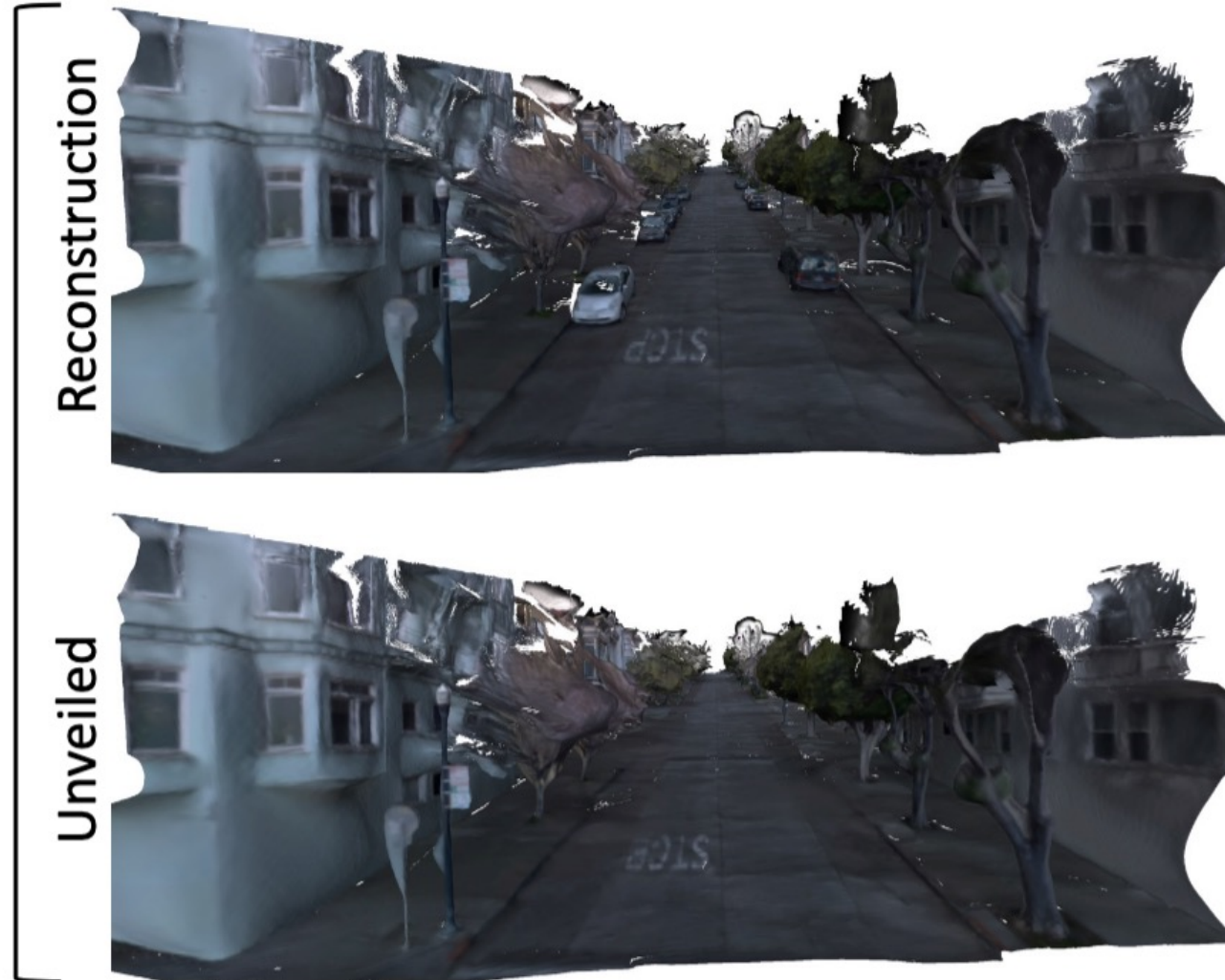


InFusion [Liu et.al 2024]

Novel View Synthesis Results



Empty Street Mesh Extraction



Thanks for watching!

Project Page: <https://streetunveiler.github.io/>

Code: <https://github.com/DavidXu-JJ/StreetUnveiler>