



# Causal Discovery via Bayesian Optimization

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#### Problem

Score-based causal discovery (SCD):

$$\mathcal{G}^* = \underset{\mathcal{G} \in DAGs}{\operatorname{arg max}} S\left(\mathcal{D}, \mathcal{G}\right).$$

- Challenges:
  - 1. Constraint: the graphs must be acyclic.
  - 2. Scalability: high-dim & many trials.
  - **3. Sample-efficiency**: score calculation can be expensive.



## Introduction

#### Existing approaches

- Greedy search (e.g., GES)
  - Slow exploration: add/remove one edge at a time.
- Continuous optimization (e.g., NOTEARS, DAGMA, etc.)
  - Lack exploration: only follow the gradient direction.
- Reinforcement learning (e.g., RL-BIC, CORL, ALIAS, etc.)
  - Inefficient exploration: blindly explore random DAGs without pre-examining their potential.

# A

### Introduction

#### Motivation

- By modelling the explored DAG scores to detect promising exploration candidates, we may arrive at better solutions earlier
- → Bayesian Optimization (BO)
- Applying BO directly to SCD is hard:
  - SCD is usually **high-dim** and **constrained**, while BO works well **low-dim** and **unconstrained**.
  - BO scales poorly with #trials, while we may need thousands or more trials for SCD.
  - Acquisition function optimization in BO is itself a SCD problem, thus requiring to be very efficient to be practical.
- → we propose the **first BO-based SCD method** for sample-efficiency by making several innovations.



## Introduction

#### Our work

- 4 innovations to specifically adapt BO to SCD:
  - 1. Low-rank unconstrained search space → addressing acyclicity & dimensionality.
  - 2. Replacing GPs with Dropout networks for surrogate modelling → addressing **scalability**.
  - 3. Indirect DAG score modelling → addressing surrogate modelling accuracy.
  - 4. Continual model training → addressing **scalability**.
- These enables accurate and sample-efficient SCD, as verified through extensive experiments and ablations.

# A

## Introduction

### Our findings

- DrBO is highly accurate & sample-efficient compared with existing SOTAs.
  - Accuracy: SHD ≈ 0 for linear & nonlinear data, dense & large graphs, synthetic & real data.
  - Sample-efficiency: SHD ≈ 0 is reached earlier than other methods in both number of DAG evaluations & time.
- Ablations confirm that:
  - Lower rank = better sample-efficiency.
  - Dropout nets scale better than GPs.
  - Indirect DAG modelling = more accuracy.
  - Continual training = linear scalability.



#### Low-dim unconstrained search space

 We turn the constrained optimization problem to an easier unconstrained problem with low-dim search space:

$$\mathcal{G}^* = \operatorname*{arg\,max}_{\mathcal{G} \in \mathsf{DAGs}} S\left(\mathcal{D}, \mathcal{G}\right) \Longleftrightarrow \mathbf{z}^* = \operatorname*{arg\,max}_{\mathbf{z} \in \mathbb{R}^{d(1+k)}} S\left(\mathcal{D}, \tau\left(\mathbf{z}\right)\right)$$

• The map  $\tau$  turns unconstrained continuous-value parameters to a **DAG**:

$$\tau\left(\mathbf{p},\mathbf{R}\right) := \underbrace{H\left(\operatorname{grad}\left(\mathbf{p}\right)\right)}_{\text{ensures acyclitiy}} \underbrace{\underbrace{H\left(\mathbf{R}\cdot\mathbf{R}^{\top}\right)}_{\text{low-rank connectivity}}}$$

where  $R \in \mathbb{R}^{d \times k}$   $(k \ll d)$  is an embedding matrix and z is concatenation of p and R.

- This is a low-rank adaptation of Vec2DAG (Duong et al., 2024).
- $\rightarrow$  Search dimensionality scales linearly with d and allows generating more diverse DAGs.



#### Acquisition function optimization

- Acquisition function optimization = SCD with acquisition function values as scores → sampling-based approach for efficiency:
  - Trust-region sampling: random  $\{\mathbf{z}^{(j)}\}_{j=1}^{C}$  are generated from a hypercube centred at best solution so far  $\mathbf{z}^*$ .
  - Then, top-*B* candidates with highest acquisition function values are chosen.
- Larger *C* = higher-quality candidates → acquisition function evaluation must scale very well.



Surrogate Modelling with Dropout Networks

- GPs scale cubically with number of datapoints, both in training and sampling.
- Dropout nets = approximate Bayesian inference (Gal & Ghahramani, 2016).

$$\operatorname{DropoutNN}\left(\mathbf{x}\right) := \mathbf{W}_{2}^{\top} \left( \operatorname{BatchNorm}\left( \operatorname{ReLU}\left( \frac{1}{1-p} \left( \left( 1 - \mathbf{m} \right) \circ \left( \mathbf{W}_{1}^{\top} \mathbf{x} + \mathbf{b}_{1} \right) \right) \right) \right) + b_{2}.$$

- A forward pass  $y \sim DropoutNN(x) \approx$  sampling from P(y|x, X, y) = Thompson sampling as acquisition function.
- → constant-time acquisition function evaluation.



#### Indirect Surrogate Modelling

- Naïve approach: train a network predicting S(D, G) directly from G.
- However, partial scores are not well exploited. E.g.:

$$S_{\text{BIC-EV}}(\mathcal{D}, \mathcal{G}) := -nd \ln \frac{\sum_{i=1}^{d} \text{MSE}_i \left( \text{pa}_i^{\mathcal{G}} \right)}{d} - |\mathcal{G}| \ln n.$$

 $\rightarrow$  we use the evaluation data  $\left\{\left(\operatorname{pa}_{i}^{\mathcal{G}^{(j)}},\operatorname{MSE}_{i}\left(\operatorname{pa}_{i}^{\mathcal{G}^{(j)}}\right)\right)\right\}$  to train **separate dropout networks**, then combine the predictions:

$$\hat{S}_{\mathrm{BIC-EV}}\left(\mathcal{D},\mathcal{G}\right) := -nd\ln\frac{\sum_{i=1}^{d}\widehat{\mathrm{MSE}_{i}}\left(\mathrm{pa}_{i}^{\mathcal{G}}\right)}{d} - |\mathcal{G}|\ln n.$$

Now all information is fully exploited → accurate score estimates.



#### **Continual Model Training**

- Retraining the neural nets every BO iteration is costly, which prevents scaling to many trials.
- → we instead train them continually: each iteration apply several gradient steps on the new data combined with a random batch of past data.
- → constant-time model update.



#### Overall Algorithm

#### Algorithm 1 The DrBO method for causal discovery.

**Require:** Dataset  $\mathcal{D} = \left\{\mathbf{x}^{(j)} \in \mathbb{R}^d\right\}_{j=1}^n$  of d nodes and n observations, score function  $S(\mathcal{D},\cdot)$ , DAG rank k, batch size B, no. of preliminary candidates C, and total no. of evaluations T.

**Ensure:** A DAG  $\hat{\mathcal{G}}$  that maximizes  $S(\mathcal{D}, \mathcal{G})$ .

- 1: Initialize empty experience  $\mathcal{H} := \emptyset$  and node-wise dropout neural nets:  $\{\text{DropoutNN}_i\}_{i=1}^d$ .
- 2: while  $|\mathcal{H}| < T$  do
- 3: Generate random DAGs:  $\{\mathcal{G}^{(j)} := \tau(\mathbf{z}^{(j)})\}_{i=1}^{C}$  where  $\mathbf{z} \in [-1, 1]^{d(1+k)}$ .  $\triangleright$  Secs. 4.1 & 4.2.
- 4: Sample local scores:  $\left\{ \left\{ l_i^{(j)} \sim \text{DropoutNN}_i \left( \text{pa}_i^{\mathcal{G}^{(j)}} \right) \right\}_{i=1}^d \right\}_{j=1}^C$ .  $\triangleright \underline{\text{Sec. 4.3}}$ .
- 5: Combine local scores:  $\left\{ AF^{(j)} := Combine \left( l_1^{(j)}, \dots, l_d^{(j)} \right) \right\}_{j=1}^{C}$ .  $\triangleright \underline{Sec. 4.4}$ .
- 6: Select top B candidates with highest AF values:  $j_1, \ldots, j_B := \underset{j=1,\ldots,C}{\operatorname{argtop}} \operatorname{AF}^{(j)}$ .  $\triangleright \underline{\operatorname{Sec. 4.2}}$ .
- 7: Evaluate these candidates and update experience:  $\mathcal{H} := \mathcal{H} \cup \left\{ \left( \mathcal{G}^{(j)}, S\left(\mathcal{D}, \mathcal{G}^{(j)}\right) \right) \right\}_{j=j_1, \dots, j_B}$
- 8: Update the neural nets on new  $\mathcal{H}$ .  $\triangleright$  Sec. 4.5
- 9: end while
- 10: Get highest-scoring DAG so far:  $\hat{\mathcal{G}} := \arg \max_{\mathcal{G} \in \mathcal{H}} S(\mathcal{D}, \mathcal{G})$ .
- 11: Prune  $\hat{\mathcal{G}}$  if needed.

⊳ <u>Sec. 4.6</u>.



# Experiments

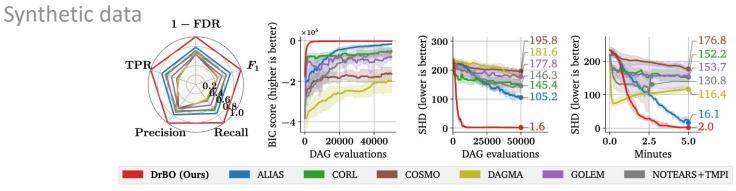


Figure 1. Linear-Gaussian data with dense graphs (30-node ER-8).

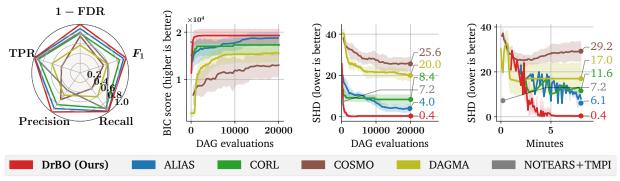


Figure 2. Non-linear data.



# Experiments

Real data

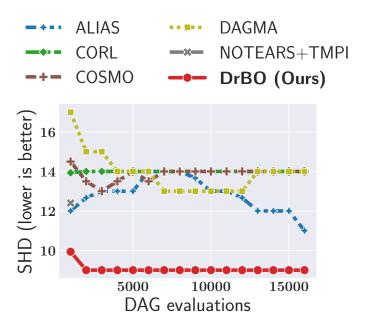
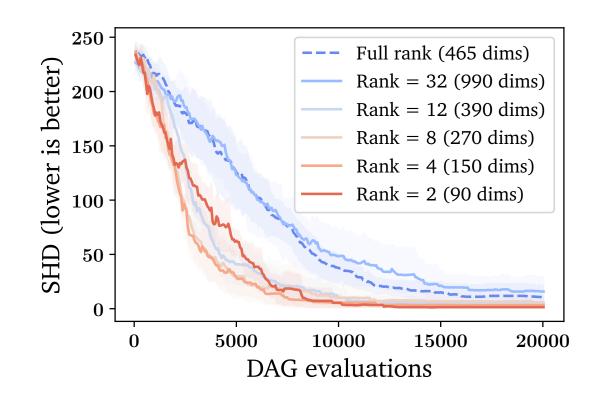


Figure. Causal Discovery performance on the Sachs dataset



Lower rank = more sample-efficiency





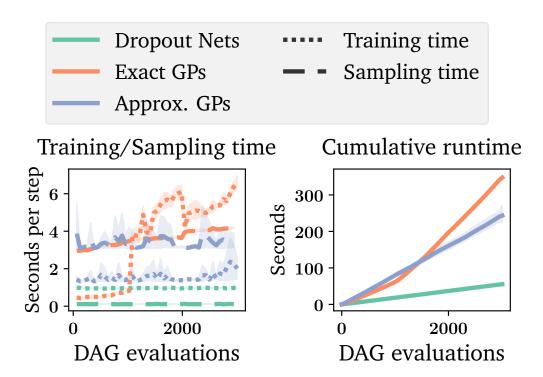
Lower rank = more diverse candidates

Table 5: **Effect of DAG Rank on Exploration Diversity.** We generate 1,000 DAGs with d=30 nodes using  $\mathcal{G}:=\tau\left(\mathbf{z}\right)$ ,  $\mathbf{z}\in\left[-1,1\right]^{d\cdot(1+k)}$  with different k. The numbers are mean  $\pm$  std over 10 simulations.

Rank $k$ in Eq. (4)	Number of dimensions	Number of unique 30-node DAGs over $1{,}000$ random DAGs
2	90	$926.7 \pm \ \ 7.0$
4	150	$779.2 \pm 12.7$
8	270	$493.5\pm12.3$
12	390	$332.4 \pm 10.8$
32	990	$90.7 \pm 9.5$
Full rank (Vec2DAG, Duong et al., 2024)	465	$421.9 \pm 13.8$

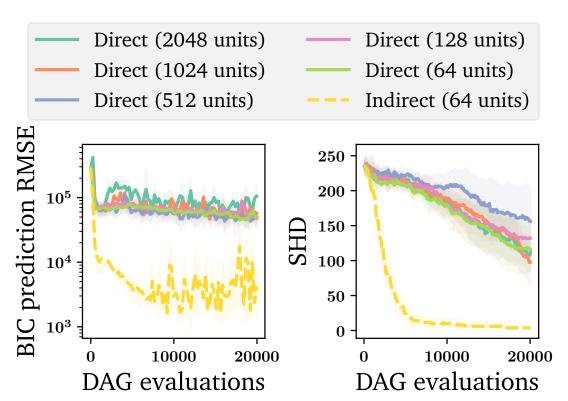


Dropout Nets scale much better than GPs



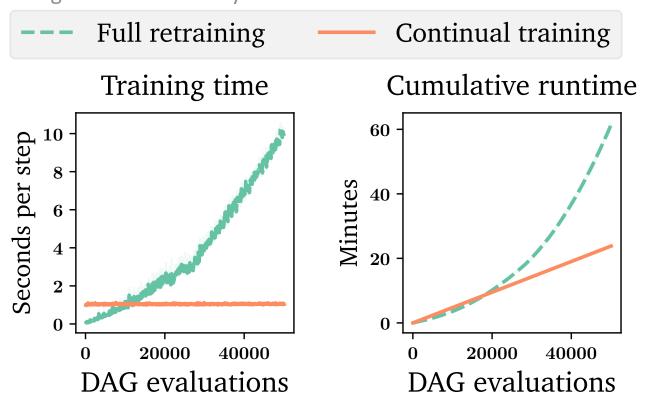


Indirect DAG Modelling = more accuracy





Continual Training = linear scalability





# Key takeaways

- We propose to the use of Bayesian optimization for sample-efficient scorebased causal discovery.
- 4 innovations to specifically adapt BO to SCD:
  - 1. Low-rank unconstrained search space.
  - 2. Replacing GPs with Dropout networks for surrogate modelling.
  - 3. Indirect DAG score modelling.
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