



Yinuo Ren<sup>1</sup>, Haoxuan Chen<sup>1</sup>,  
Grant M. Rotskoff<sup>3,1</sup>, Lexing Ying<sup>2,1</sup>  
{yinuoren, haoxuanc, rotskoff, lexing}@stanford.edu

<sup>1</sup>ICME <sup>2</sup>Department of Mathematics <sup>3</sup>Department of Chemistry  
Stanford University

April 1, 2025

# How Discrete and Continuous Diffusion Meet:

*Comprehensive Analysis of Discrete Diffusion Models via  
a Stochastic Integral Framework*

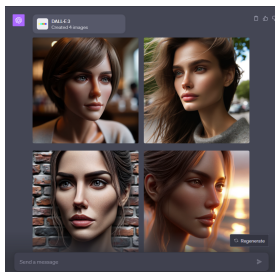
- 1 Diffusion Models: an Introduction
- 2 A Stochastic Integral Framework for Discrete DMs
- 3 Main Results: Theoretical Guarantees of Inference Algorithms

Section 1:

# Diffusion Models: an Introduction

# Diffusion Models

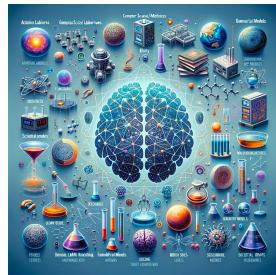
## Introduction



(a) DALL-E 3



(b) Stable Diffusion



(c) AI4Science

**Figure:** Diffusion and flow-based generative models have exerted huge impacts on scientific research in many fields.

# Problem Setting: Continuous Diffusion Models

---

- **Task:** Sample from data distribution  $p_0$  *accurately* and *efficiently*

# Problem Setting: Continuous Diffusion Models

- **Task:** Sample from data distribution  $p_0$  *accurately* and *efficiently*
- **Forward SDE:**

$$d\mathbf{x}_s = \boldsymbol{\beta}_s(\mathbf{x}_s)ds + \boldsymbol{\sigma}_s d\mathbf{w}_s, \quad \text{with } \mathbf{x}_0 \sim p_0$$

# Problem Setting: Continuous Diffusion Models

- **Task:** Sample from data distribution  $p_0$  *accurately* and *efficiently*
- **Forward SDE:**

$$d\mathbf{x}_s = \boldsymbol{\beta}_s(\mathbf{x}_s)ds + \boldsymbol{\sigma}_s d\mathbf{w}_s, \quad \text{with } \mathbf{x}_0 \sim p_0$$

- **Backward SDE:**

$$d\tilde{\mathbf{x}}_t = \left[ -\tilde{\boldsymbol{\beta}}_t(\tilde{\mathbf{x}}_t) + \frac{\tilde{\boldsymbol{\sigma}}_t \tilde{\boldsymbol{\sigma}}_t^\top + \tilde{\mathbf{v}}_t \tilde{\mathbf{v}}_t^\top}{2} \nabla \log \tilde{p}_t(\tilde{\mathbf{x}}_t) \right] dt + \tilde{\mathbf{v}}_t d\mathbf{w}_t$$

with  $\tilde{p}_0 = p_T \approx \mathcal{N}(\mathbf{0}, \mathbf{I})$  and  $\tilde{p}_T = p_0$

# Problem Setting: Continuous Diffusion Models

- **Task:** Sample from data distribution  $p_0$  *accurately* and *efficiently*
- **Forward SDE:**

$$d\mathbf{x}_s = \boldsymbol{\beta}_s(\mathbf{x}_s)ds + \boldsymbol{\sigma}_s d\mathbf{w}_s, \quad \text{with } \mathbf{x}_0 \sim p_0$$

- **Backward SDE:**

$$d\tilde{\mathbf{x}}_t = \left[ -\tilde{\boldsymbol{\beta}}_t(\tilde{\mathbf{x}}_t) + \frac{\tilde{\boldsymbol{\sigma}}_t \tilde{\boldsymbol{\sigma}}_t^\top + \tilde{\mathbf{v}}_t \tilde{\mathbf{v}}_t^\top}{2} \nabla \log \tilde{p}_t(\tilde{\mathbf{x}}_t) \right] dt + \tilde{\mathbf{v}}_t d\mathbf{w}_t$$

with  $\tilde{p}_0 = p_T \approx \mathcal{N}(\mathbf{0}, \mathbf{I})$  and  $\tilde{p}_T = p_0$

- **Score Function:**  $\mathbf{s}_t^\theta(\mathbf{x}_t) \approx \nabla \log p_t(\mathbf{x}_t)$  by optimizing

$$\mathcal{L}(\theta) = \int_0^T \psi_t \mathbb{E}_{\mathbf{x}_t \sim p_t} \left[ \|\nabla \log p_t(\mathbf{x}_t) - \mathbf{s}_t^\theta(\mathbf{x}_t)\|^2 \right] dt$$



# Problem Setting: Continuous Diffusion Models

- **Task:** Sample from data distribution  $p_0$  *accurately* and *efficiently*
- **Forward SDE:**

$$d\mathbf{x}_s = \boldsymbol{\beta}_s(\mathbf{x}_s)ds + \boldsymbol{\sigma}_s d\mathbf{w}_s, \quad \text{with } \mathbf{x}_0 \sim p_0$$

- **Backward SDE:**

$$d\tilde{\mathbf{x}}_t = \left[ -\tilde{\boldsymbol{\beta}}_t(\tilde{\mathbf{x}}_t) + \frac{\tilde{\boldsymbol{\sigma}}_t \tilde{\boldsymbol{\sigma}}_t^\top + \tilde{\mathbf{v}}_t \tilde{\mathbf{v}}_t^\top}{2} \nabla \log \tilde{p}_t(\tilde{\mathbf{x}}_t) \right] dt + \tilde{\mathbf{v}}_t d\mathbf{w}_t$$

with  $\tilde{p}_0 = p_T \approx \mathcal{N}(\mathbf{0}, \mathbf{I})$  and  $\tilde{p}_T = p_0$

- **Score Function:**  $\mathbf{s}_t^\theta(\mathbf{x}_t) \approx \nabla \log p_t(\mathbf{x}_t)$  by optimizing

$$\mathcal{L}(\theta) = \int_0^T \psi_t \mathbb{E}_{\mathbf{x}_t \sim p_t} \left[ \|\nabla \log p_t(\mathbf{x}_t) - \mathbf{s}_t^\theta(\mathbf{x}_t)\|^2 \right] dt$$

- **Implementations:** SDE ( $\mathbf{v}_t = \boldsymbol{\sigma}_t$ ), Probability Flow ODE (PF-ODE,  $\mathbf{v}_t \equiv \mathbf{0}$ )

# Error Analysis: Continuous Diffusion Models

Take  $\beta_s(\mathbf{x}_s) = -0.5\mathbf{x}_s$  and  $\sigma_s = \mathbf{I}$ :

- Forward SDE:  $d\mathbf{x}_s = -\frac{1}{2}\mathbf{x}_s ds + d\mathbf{w}_s$  with  $\mathbf{x}_0 \sim p_0$

# Error Analysis: Continuous Diffusion Models

Take  $\beta_s(\mathbf{x}_s) = -0.5\mathbf{x}_s$  and  $\sigma_s = \mathbf{I}$ :

- Forward SDE:  $d\mathbf{x}_s = -\frac{1}{2}\mathbf{x}_s ds + d\mathbf{w}_s$  with  $\mathbf{x}_0 \sim p_0$
- Backward SDE:  $d\tilde{\mathbf{x}}_t = \left[ \frac{1}{2}\tilde{\mathbf{x}}_t + \frac{1+v^2}{2}\nabla \log \tilde{p}_t(\tilde{\mathbf{x}}_t) \right] dt + v d\mathbf{w}_t$ , with  $\tilde{p}_0 = p_T \approx \mathcal{N}(\mathbf{0}, \mathbf{I})$  and  $\tilde{p}_T = p_0$

# Error Analysis: Continuous Diffusion Models

Take  $\beta_s(\mathbf{x}_s) = -0.5\mathbf{x}_s$  and  $\sigma_s = \mathbf{I}$ :

- Forward SDE:  $d\mathbf{x}_s = -\frac{1}{2}\mathbf{x}_s ds + d\mathbf{w}_s$  with  $\mathbf{x}_0 \sim p_0$
- Backward SDE:  $d\tilde{\mathbf{x}}_t = \left[ \frac{1}{2}\tilde{\mathbf{x}}_t + \frac{1+v^2}{2}\nabla \log \tilde{p}_t(\tilde{\mathbf{x}}_t) \right] dt + v d\mathbf{w}_t$ , with  $\tilde{p}_0 = p_T \approx \mathcal{N}(\mathbf{0}, \mathbf{I})$  and  $\tilde{p}_T = p_0$

## Theorem (Error Analysis of Continuous Diffusion Models)

Suppose  $t_0 = 0 \leq \dots \leq t_N = T - \delta$  satisfies  $t_{k+1} - t_k \leq \kappa(T - t_{k+1})$  and

$$\sum_{k=0}^{N-1} (s_{k+1} - s_k) \mathbb{E}_{\tilde{\mathbf{x}}_{s_k} \sim \tilde{p}_{s_k}} \left[ \left\| \nabla \log \tilde{p}_{s_k}(\tilde{\mathbf{x}}_{s_k}) - \tilde{\mathbf{s}}_{s_k}^{\theta}(\mathbf{x}_{s_k}) \right\|^2 \right] \leq \epsilon.$$

Then with

$$T = \mathcal{O}(\log(d\epsilon^{-1})), \quad \kappa = \mathcal{O}(d^{-1}\epsilon \log^{-1}(d\epsilon^{-1})), \quad N = \mathcal{O}(d\epsilon^{-1} \log^2(d\epsilon^{-1})),$$

we have

$$D_{\text{KL}}(p_{\delta} \parallel \hat{q}_{t_N}) \lesssim d\epsilon^{-T} + \epsilon + d\kappa T \lesssim \epsilon.$$

# Error Analysis: Continuous Diffusion Models

## Theorem (Error Analysis of Continuous Diffusion Models)

With

$$T = \mathcal{O}(\log(d\epsilon^{-1})), \quad \kappa = \mathcal{O}(d^{-1}\epsilon \log^{-1}(d\epsilon^{-1})), \quad N = \mathcal{O}(d\epsilon^{-1} \log^2(d\epsilon^{-1})),$$

we have

$$D_{\text{KL}}(p_\delta \| \hat{q}_{t_N}) \lesssim de^{-T} + \epsilon + d\kappa T \lesssim \epsilon.$$

# Error Analysis: Continuous Diffusion Models

## Theorem (Error Analysis of Continuous Diffusion Models)

With

$$T = \mathcal{O}(\log(d\epsilon^{-1})), \quad \kappa = \mathcal{O}(d^{-1}\epsilon \log^{-1}(d\epsilon^{-1})), \quad N = \mathcal{O}(d\epsilon^{-1} \log^2(d\epsilon^{-1})),$$

we have

$$D_{\text{KL}}(p_\delta \| \hat{q}_{t_N}) \lesssim de^{-T} + \epsilon + d\kappa T \lesssim \epsilon.$$

- **Truncation Error:** Error caused by approximating  $p_T$  by  $p_\infty$ , of the order  $\mathcal{O}(d \exp(-T))$ ;

# Error Analysis: Continuous Diffusion Models

## Theorem (Error Analysis of Continuous Diffusion Models)

With

$$T = \mathcal{O}(\log(d\epsilon^{-1})), \quad \kappa = \mathcal{O}(d^{-1}\epsilon \log^{-1}(d\epsilon^{-1})), \quad N = \mathcal{O}(d\epsilon^{-1} \log^2(d\epsilon^{-1})),$$

we have

$$D_{\text{KL}}(p_\delta \| \hat{q}_{t_N}) \lesssim de^{-T} + \epsilon + d\kappa T \lesssim \epsilon.$$

- **Truncation Error:** Error caused by approximating  $p_T$  by  $p_\infty$ , of the order  $\mathcal{O}(d \exp(-T))$ ;
- **Approximation Error:** Error caused by approximating  $\nabla \log p_t(\mathbf{x}_t)$  by NN  $\hat{\mathbf{s}}_t^\theta(\mathbf{x}_t)$ , assumed to be of  $\mathcal{O}(\epsilon)$ ;

# Error Analysis: Continuous Diffusion Models

## Theorem (Error Analysis of Continuous Diffusion Models)

With

$$T = \mathcal{O}(\log(d\epsilon^{-1})), \quad \kappa = \mathcal{O}(d^{-1}\epsilon \log^{-1}(d\epsilon^{-1})), \quad N = \mathcal{O}(d\epsilon^{-1} \log^2(d\epsilon^{-1})),$$

we have

$$D_{\text{KL}}(p_\delta \parallel \hat{q}_{t_N}) \lesssim de^{-T} + \epsilon + d\kappa T \lesssim \epsilon.$$

- **Truncation Error:** Error caused by approximating  $p_T$  by  $p_\infty$ , of the order  $\mathcal{O}(d \exp(-T))$ ;
- **Approximation Error:** Error caused by approximating  $\nabla \log p_t(\mathbf{x}_t)$  by NN  $\hat{\mathbf{s}}_t^\theta(\mathbf{x}_t)$ , assumed to be of  $\mathcal{O}(\epsilon)$ ;
- **Discretization Error:** Error caused by numerically solving the backward SDE



# Problem Setting: Discrete Diffusion Models

- **Task:** Sample from discrete data distribution  $p_0 \in \Delta^{|\mathcal{X}|}$

# Problem Setting: Discrete Diffusion Models

- **Task:** Sample from discrete data distribution  $p_0 \in \Delta^{|\mathcal{X}|}$
- **Forward Continuous Time Markov Chain (CTMC):**

$$\frac{d\mathbf{p}_t}{dt} = \mathbf{Q}_t \mathbf{p}_t, \text{ with } Q_t(x, x) = - \sum_{y \neq x} Q_t(y, x) \text{ and } Q_t(x, y) \geq 0 \ (x \neq y)$$

# Problem Setting: Discrete Diffusion Models

- Task: Sample from discrete data distribution  $p_0 \in \Delta^{|\mathcal{X}|}$
- Forward Continuous Time Markov Chain (CTMC):

$$\frac{d\mathbf{p}_t}{dt} = \mathbf{Q}_t \mathbf{p}_t, \text{ with } Q_t(x, x) = - \sum_{y \neq x} Q_t(y, x) \text{ and } Q_t(x, y) \geq 0 \ (x \neq y)$$

- Backward CTMC:

$$\frac{d\tilde{\mathbf{p}}_s}{ds} = \overline{\mathbf{Q}}_s \tilde{\mathbf{p}}_s, \text{ with } \overline{Q}_s(y, x) = \begin{cases} \frac{\tilde{p}_s(y)}{\tilde{p}_s(x)} \tilde{Q}_s(x, y), & \forall x \neq y \in \mathbb{X}, \\ - \sum_{y' \neq x} \overline{Q}_s(y', x), & \forall x = y \in \mathbb{X}. \end{cases}$$

with  $\mathbf{p}_0 = \mathbf{p}_T \approx \text{Unif}(\Delta)$  and  $\tilde{\mathbf{p}}_T = \mathbf{p}_0$

# Problem Setting: Discrete Diffusion Models

- **Task:** Sample from discrete data distribution  $p_0 \in \Delta^{|\mathcal{X}|}$
- **Forward Continuous Time Markov Chain (CTMC):**

$$\frac{d\mathbf{p}_t}{dt} = \mathbf{Q}_t \mathbf{p}_t, \text{ with } Q_t(x, x) = -\sum_{y \neq x} Q_t(y, x) \text{ and } Q_t(x, y) \geq 0 \ (x \neq y)$$

- **Backward CTMC:**

$$\frac{d\tilde{\mathbf{p}}_s}{ds} = \overline{\mathbf{Q}}_s \tilde{\mathbf{p}}_s, \text{ with } \overline{Q}_s(y, x) = \begin{cases} \frac{\tilde{p}_s(y)}{\tilde{p}_s(x)} \tilde{Q}_s(x, y), & \forall x \neq y \in \mathbb{X}, \\ -\sum_{y' \neq x} \overline{Q}_s(y', x), & \forall x = y \in \mathbb{X}. \end{cases}$$

with  $\mathbf{p}_0 = \mathbf{p}_T \approx \text{Unif}(\Delta)$  and  $\tilde{\mathbf{p}}_T = \mathbf{p}_0$

- **Score Function:**  $\mathbf{s}_t(x) = (s_t(x, y))_{y \in \mathbb{X}} = \frac{\mathbf{p}_t}{p_t(x)}$  by optimizing

$$\int_0^T \psi_t \mathbb{E}_{x_t \sim p_t} \left[ \sum_{y \neq x} \left( -\log \frac{\hat{s}_t^\theta(x, y)}{s_t(x, y)} - 1 + \frac{\hat{s}_t^\theta(x, y)}{s_t(x, y)} \right) s_t(x, y) Q_t(x, y) \right] dt$$

# Problem Setting: Discrete Diffusion Models

- **Task:** Sample from discrete data distribution  $p_0 \in \Delta^{|\mathcal{X}|}$
- **Forward Continuous Time Markov Chain (CTMC):**

$$\frac{d\mathbf{p}_t}{dt} = \mathbf{Q}_t \mathbf{p}_t, \text{ with } Q_t(x, x) = -\sum_{y \neq x} Q_t(y, x) \text{ and } Q_t(x, y) \geq 0 \ (x \neq y)$$

- **Backward CTMC:**

$$\frac{d\tilde{\mathbf{p}}_s}{ds} = \overline{\mathbf{Q}}_s \tilde{\mathbf{p}}_s, \text{ with } \overline{Q}_s(y, x) = \begin{cases} \frac{\tilde{p}_s(y)}{\tilde{p}_s(x)} \tilde{Q}_s(x, y), & \forall x \neq y \in \mathbb{X}, \\ -\sum_{y' \neq x} \overline{Q}_s(y', x), & \forall x = y \in \mathbb{X}. \end{cases}$$

with  $\mathbf{p}_0 = \mathbf{p}_T \approx \text{Unif}(\Delta)$  and  $\tilde{\mathbf{p}}_T = \mathbf{p}_0$

- **Score Function:**  $\mathbf{s}_t(x) = (s_t(x, y))_{y \in \mathbb{X}} = \frac{\mathbf{p}_t}{p_t(x)}$  by optimizing

$$\int_0^T \psi_t \mathbb{E}_{x_t \sim p_t} \left[ \sum_{y \neq x} \left( -\log \frac{\hat{s}_t^\theta(x, y)}{s_t(x, y)} - 1 + \frac{\hat{s}_t^\theta(x, y)}{s_t(x, y)} \right) s_t(x, y) Q_t(x, y) \right] dt$$

- **Implementations:**  $\tau$ -leaping scheme ([Gil01, CBDB<sup>+</sup>22]), uniformization ([VD92, CY24])

Section 2:

## A Stochastic Integral Framework for Discrete DMs

# Mathematical Preliminaries

## Poisson Random Measure with Evolving Intensity

$(\Omega, \mathcal{F}, \mathcal{P})$ : probability space

$(\mathbb{X}, \mathcal{B}, \nu)$ : measure space

$\lambda_t(y)$ : a non-negative predictable process on  $\mathbb{R}^+ \times \mathbb{X} \times \Omega$  satisfying

$$\int_0^T \int_{\mathbb{X}} 1 \vee |y| \vee |y|^2 \lambda_t(y) \nu(dy) dt < \infty, \text{ a.s..}$$

for any  $T > 0$ , The random measure  $N[\lambda](dt, dy)$  on  $\mathbb{R}^+ \times \mathbb{X}$  is called a *Poisson random measure with evolving intensity*  $\lambda_t(y)$  if

# Mathematical Preliminaries

## Poisson Random Measure with Evolving Intensity

$(\Omega, \mathcal{F}, \mathcal{P})$ : probability space

$(\mathbb{X}, \mathcal{B}, \nu)$ : measure space

$\lambda_t(y)$ : a non-negative predictable process on  $\mathbb{R}^+ \times \mathbb{X} \times \Omega$  satisfying

$$\int_0^T \int_{\mathbb{X}} 1 \vee |y| \vee |y|^2 \lambda_t(y) \nu(dy) dt < \infty, \text{ a.s..}$$

for any  $T > 0$ , The random measure  $N[\lambda](dt, dy)$  on  $\mathbb{R}^+ \times \mathbb{X}$  is called a *Poisson random measure with evolving intensity*  $\lambda_t(y)$  if

- 1 For any  $B \in \mathcal{B}$  and  $0 \leq s < t$ ,  $N[\lambda]((s, t] \times B) \sim \mathcal{P} \left( \int_s^t \int_B \lambda_\tau(y) \nu(dy) d\tau \right)$ ;

Interpretation: the number of jumps of magnitude  $y$  during the infinitesimal time interval  $(t, t + dt]$  is Poisson distributed with mean  $\lambda_t(y) \nu(dy) dt$ .



# Mathematical Preliminaries

## Poisson Random Measure with Evolving Intensity

$(\Omega, \mathcal{F}, \mathcal{P})$ : probability space

$(\mathbb{X}, \mathcal{B}, \nu)$ : measure space

$\lambda_t(y)$ : a non-negative predictable process on  $\mathbb{R}^+ \times \mathbb{X} \times \Omega$  satisfying

$$\int_0^T \int_{\mathbb{X}} 1 \vee |y| \vee |y|^2 \lambda_t(y) \nu(dy) dt < \infty, \text{ a.s..}$$

for any  $T > 0$ , The random measure  $N[\lambda](dt, dy)$  on  $\mathbb{R}^+ \times \mathbb{X}$  is called a *Poisson random measure with evolving intensity*  $\lambda_t(y)$  if

- 1 For any  $B \in \mathcal{B}$  and  $0 \leq s < t$ ,  $N[\lambda]((s, t] \times B) \sim \mathcal{P} \left( \int_s^t \int_B \lambda_\tau(y) \nu(dy) d\tau \right)$ ;

Interpretation: the number of jumps of magnitude  $y$  during the infinitesimal time interval  $(t, t + dt]$  is Poisson distributed with mean  $\lambda_t(\nu) \gamma(d\nu) dt$ .

- 2 For any  $t \geq 0$  and disjoint sets  $\{B_i\}_{i \in [n]} \subset \mathcal{B}$ ,  $\{N_t[\lambda](B_i) := N[\lambda]((0, t] \times B_i)\}_{i \in [n]}$  are independent stochastic processes.

# Stochastic Integral Formulation: True Processes

Forward Process:

$$x_t = x_0 + \int_0^t \int_{\mathbb{X}} (y - x_{\tau-}) N[\lambda](d\tau, dy), \text{ with } \lambda_{\tau}(y) = \tilde{Q}_{\tau}(y, x_{\tau-}),$$

True Backward Process ( $\tilde{s}_t$  denotes the true score):

$$\tilde{x}_t = \tilde{x}_0 + \int_0^t \int_{\mathbb{X}} (y - \tilde{x}_{\tau-}) N[\mu](d\tau, dy), \text{ with } \mu_{\tau}(y) = \tilde{s}_{\tau}(\tilde{x}_{\tau-}, y) \overline{Q}_{\tau}(\tilde{x}_{\tau-}, y),$$

# Stochastic Integral Formulation: $\tau$ -Leaping Scheme

Notation: time discretizations  $(s_i)_{i \in [0:N]}$  with  $s_0 = 0$  and  $s_N = T - \delta$ ,  $\lfloor \tau \rfloor = s_n$  for any  $\tau \in [s_n, s_{n+1})$

$\tau$ -leaping inference scheme:

$$\hat{y}_{s_{n+1}} \leftarrow \hat{y}_{s_n} + \sum_{y \in \mathbb{X}} (y - \hat{y}_{s_n}) \mathcal{P}(\hat{\mu}_{s_n}^\theta(y)(s_{n+1} - s_n))$$

with the evolving intensity  $\hat{\mu}_{\lfloor \tau \rfloor}^\theta(y) = \tilde{s}_{\lfloor \tau \rfloor}^\theta(\hat{y}_{\lfloor \tau \rfloor -}, y) \bar{Q}_{\lfloor \tau \rfloor}(\hat{y}_{\lfloor \tau \rfloor -}, y) = \hat{\mu}_{s_n}^\theta(y)$

Approximate Backward Process (equivalent to  $\tau$ -leaping)

$$\hat{y}_s = \hat{y}_0 + \int_0^s \int_{\mathbb{X}} (y - \hat{y}_{\lfloor \tau \rfloor -}) N[\hat{\mu}_{\lfloor \cdot \rfloor}^\theta](d\tau, dy)$$

# Stochastic Integral Formulation: Uniformization Scheme

Notation: time discretization  $(s_b)_{b \in [0, N]}$  with  $s_0 = 0$  and  $s_N = T - \delta$   
 Uniformization inference scheme:

$M \sim \mathcal{P}(\bar{\lambda}_{s_{b+1}}(s_{b+1} - s_b))$ ,  $\sigma_m \sim \text{Unif}([0, 1])$  for  $m \in [M]$

$$\hat{y}_{s_b + \sigma_{(m)}} \leftarrow \begin{cases} y, & \text{w.p. } \hat{\mu}_{s_b + \sigma_{(m)}}^{\theta}(y) / \bar{\lambda}_{s_{b+1}}, \text{ for } y \in \mathbb{X}, \\ \hat{y}_{s_b}, & \text{w.p. } 1 - \sum_{y \in \mathbb{X}} \hat{\mu}_{s_b + \sigma_{(m)}}^{\theta}(y) / \bar{\lambda}_{s_{b+1}}; \end{cases}$$

with the evolving intensity  $\hat{\mu}_s^{\theta}(y) = \tilde{s}_s^{\theta}(\hat{y}_{s-}, y) \bar{Q}_s(\hat{y}_{s-}, y)$

Approximate Backward Process (equivalent to uniformization)

$$y_s = y_0 + \int_0^s \int_{\mathbb{X}} \int_{\mathbb{R}} (y - y_{s-}) \mathbf{1}_{0 \leq \xi \leq \int_{\mathbb{X}} \hat{\mu}_s^{\theta}(y) \nu(dy)} N[\hat{\mu}^{\theta}](ds, dy, d\xi)$$

# Assumptions for Discrete DMs

- **Regularity of rate matrix  $\mathbf{Q}$ :** (i)  $Q(x, y) \leq C$  and  $\underline{D} \leq -Q(x, x) \leq \overline{D}$ ,  $\forall x, y \in \mathbb{X}$ , where  $C, \underline{D}, \overline{D} > 0$ ; (ii)  $\rho(\mathbf{Q}) \geq \rho > 0$  for the modified log-Sobolev constant  $\rho(\mathbf{Q})$  of the rate matrix  $\mathbf{Q}$ .

# Assumptions for Discrete DMs

- **Regularity of rate matrix  $\mathbf{Q}$ :** (i)  $Q(x, y) \leq C$  and  $\underline{D} \leq -Q(x, x) \leq \overline{D}$ ,  $\forall x, y \in \mathbb{X}$ , where  $C, \underline{D}, \overline{D} > 0$ ; (ii)  $\rho(\mathbf{Q}) \geq \rho > 0$  for the modified log-Sobolev constant  $\rho(\mathbf{Q})$  of the rate matrix  $\mathbf{Q}$ .
- **Boundedness of true score  $s_t$  and learned score  $\hat{s}_t$ :**  $s_t(x, y) \lesssim 1 \vee t^{-1}$  and  $\hat{s}_s^\theta(x, y) \in (0, M]$ ,  $\forall x, y \in \mathbb{X}$ .

# Assumptions for Discrete DMs

- Regularity of rate matrix  $\mathbf{Q}$ :** (i)  $Q(x, y) \leq C$  and  $\underline{D} \leq -Q(x, x) \leq \overline{D}$ ,  $\forall x, y \in \mathbb{X}$ , where  $C, \underline{D}, \overline{D} > 0$ ; (ii)  $\rho(\mathbf{Q}) \geq \rho > 0$  for the modified log-Sobolev constant  $\rho(\mathbf{Q})$  of the rate matrix  $\mathbf{Q}$ .
- Boundedness of true score  $s_t$  and learned score  $\hat{s}_t$ :**  $s_t(x, y) \lesssim 1 \vee t^{-1}$  and  $\hat{s}_s^\theta(x, y) \in (0, M]$ ,  $\forall x, y \in \mathbb{X}$ .
- Continuity of true score** For any  $t > 0$  and  $y \in \mathbb{X}$  such that  $Q(x_{t-}, y) > 0$ , we have  $\left| \frac{\mu_{t+}(y)}{\mu_t(y)} \right| := \left| \frac{p_t(x_{t-})Q(x_{t-}, y)}{p_t(x_t)Q(x_t, y)} - 1 \right| \lesssim 1 \vee t^{-\gamma}$  for some exponent  $\gamma \in [0, 1]$ .

# Assumptions for Discrete DMs

- Regularity of rate matrix  $\mathbf{Q}$ :** (i)  $Q(x, y) \leq C$  and  $\underline{D} \leq -Q(x, x) \leq \overline{D}$ ,  $\forall x, y \in \mathbb{X}$ , where  $C, \underline{D}, \overline{D} > 0$ ; (ii)  $\rho(\mathbf{Q}) \geq \rho > 0$  for the modified log-Sobolev constant  $\rho(\mathbf{Q})$  of the rate matrix  $\mathbf{Q}$ .
- Boundedness of true score  $s_t$  and learned score  $\hat{s}_t$ :**  $s_t(x, y) \lesssim 1 \vee t^{-1}$  and  $\hat{s}_s^\theta(x, y) \in (0, M]$ ,  $\forall x, y \in \mathbb{X}$ .
- Continuity of true score** For any  $t > 0$  and  $y \in \mathbb{X}$  such that  $Q(x_{t-}, y) > 0$ , we have  $\left| \frac{\mu_{t+}(y)}{\mu_t(y)} \right| := \left| \frac{p_t(x_{t-})Q(x_{t-}, y)}{p_t(x_t)Q(x_t, y)} - 1 \right| \lesssim 1 \vee t^{-\gamma}$  for some exponent  $\gamma \in [0, 1]$ .
- $\delta$ -accurate score estimation:**

$$\sum_{n=0}^{N-1} (s_{n+1} - s_n) \mathbb{E} \left[ \int_{\mathbb{X}} K \left( \frac{\tilde{s}_{s_n}^\theta(\tilde{x}_{s_n^-}, y)}{\tilde{s}_{s_n}(\tilde{x}_{s_n^-}, y)} \right) \tilde{s}_{s_n}(\tilde{x}_{s_n^-}, y) \tilde{Q}(\tilde{x}_{s_n^-}, y) \nu(dy) \right] \leq \delta.$$



# Assumptions for Continuous DMs (for Comparison)

- **Regularity of data distribution:**  $p_0$  has finite second moment and is normalized, i.e.,  $\text{cov}_{p_0}(\mathbf{x}_0) = \mathbf{I}_d$

# Assumptions for Continuous DMs (for Comparison)

- **Regularity of data distribution:**  $p_0$  has finite second moment and is normalized, i.e.,  $\text{cov}_{p_0}(\mathbf{x}_0) = \mathbf{I}_d$
- **Bounded learned score:** The learned score  $\mathbf{s}_t^\theta$  has bounded  $C^1$  norm with Lipschitz const  $L_s$ .

# Assumptions for Continuous DMs (for Comparison)

- **Regularity of data distribution:**  $p_0$  has finite second moment and is normalized, i.e.,  $\text{cov}_{p_0}(\mathbf{x}_0) = \mathbf{I}_d$
- **Bounded learned score:** The learned score  $\mathbf{s}_t^\theta$  has bounded  $C^1$  norm with Lipschitz const  $L_s$ .
- $\delta$ -accurate score estimation:

# Assumptions for Continuous DMs (for Comparison)

- **Regularity of data distribution:**  $p_0$  has finite second moment and is normalized, i.e.,  $\text{cov}_{p_0}(\mathbf{x}_0) = \mathbf{I}_d$
- **Bounded learned score:** The learned score  $\mathbf{s}_t^\theta$  has bounded  $C^1$  norm with Lipschitz const  $L_s$ .
- **$\delta$ -accurate score estimation:**  
SDE The learned score  $\mathbf{s}_t^\theta$  is  $L^2([0, t_N])$   $\delta$ -accurate:

$$\sum_{j=0}^{N-1} (t_{j+1} - t_j) \mathbb{E}_{\tilde{p}_{t_j}} \left[ \left\| \mathbf{s}_{t_j}^\theta(\tilde{\mathbf{x}}_{t_j}) - \nabla \log \tilde{p}_{t_j}(\tilde{\mathbf{x}}_{t_j}) \right\|^2 \right] \leq \delta_2^2.$$

# Assumptions for Continuous DMs (for Comparison)

- **Regularity of data distribution:**  $p_0$  has finite second moment and is normalized, i.e.,  $\text{cov}_{p_0}(\mathbf{x}_0) = \mathbf{I}_d$
- **Bounded learned score:** The learned score  $\mathbf{s}_t^\theta$  has bounded  $C^1$  norm with Lipschitz const  $L_s$ .
- **$\delta$ -accurate score estimation:**  
 SDE The learned score  $\mathbf{s}_t^\theta$  is  $L^2([0, t_N])$   $\delta$ -accurate:

$$\sum_{j=0}^{N-1} (t_{j+1} - t_j) \mathbb{E}_{\tilde{p}_{t_j}} \left[ \left\| \mathbf{s}_{t_j}^\theta(\tilde{\mathbf{x}}_{t_j}) - \nabla \log \tilde{p}_{t_j}(\tilde{\mathbf{x}}_{t_j}) \right\|^2 \right] \leq \delta_2^2.$$

PF-ODE The learned score  $\mathbf{s}_t^\theta$  is  $L^\infty([0, T - \delta])$   $\delta$ -accurate:

$$\mathbb{E}_{\tilde{p}_{t_j}} \left[ \left\| \mathbf{s}_{t_j}^\theta(\tilde{\mathbf{x}}_{t_j}) - \nabla \log \tilde{p}_{t_j}(\tilde{\mathbf{x}}_{t_j}) \right\|^2 \right] \leq \delta_\infty^2.$$

# Assumptions for Continuous DMs (for Comparison)

- **Regularity of data distribution:**  $p_0$  has finite second moment and is normalized, i.e.,  $\text{cov}_{p_0}(\mathbf{x}_0) = \mathbf{I}_d$
- **Bounded learned score:** The learned score  $\mathbf{s}_t^\theta$  has bounded  $C^1$  norm with Lipschitz const  $L_s$ .
- **$\delta$ -accurate score estimation:**

**SDE** The learned score  $\mathbf{s}_t^\theta$  is  $L^2([0, t_N])$   $\delta$ -accurate:

$$\sum_{j=0}^{N-1} (t_{j+1} - t_j) \mathbb{E}_{\tilde{p}_{t_j}} \left[ \left\| \mathbf{s}_{t_j}^\theta(\tilde{\mathbf{x}}_{t_j}) - \nabla \log \tilde{p}_{t_j}(\tilde{\mathbf{x}}_{t_j}) \right\|^2 \right] \leq \delta_2^2.$$

**PF-ODE** The learned score  $\mathbf{s}_t^\theta$  is  $L^\infty([0, T - \delta])$   $\delta$ -accurate:

$$\mathbb{E}_{\tilde{p}_{t_j}} \left[ \left\| \mathbf{s}_{t_j}^\theta(\tilde{\mathbf{x}}_{t_j}) - \nabla \log \tilde{p}_{t_j}(\tilde{\mathbf{x}}_{t_j}) \right\|^2 \right] \leq \delta_\infty^2.$$

- **Continuity of true score (PF-ODE):** The true score  $\nabla \log p_t$  has bounded  $C^1$  norm with Lipschitz const  $L_p$ .

Section 3:

## Main Results: Theoretical Guarantees of Inference Algorithms

# Convergence Guarantee for $\tau$ -leaping

## Theorem (Theoretical Guarantees for $\tau$ -Leaping)

Take time discretization scheme  $(s_i)_{i \in [0, N]}$  satisfying  $s_0 = 0$ ,  $s_N = T - \delta$  and  $s_{k+1} - s_k \leq \kappa (1 \vee (T - s_{k+1})^{1+\gamma-\eta})$  for  $k \in [0 : N - 1]$ . Under aforementioned assumptions and the following choices of parameters

$$T = \mathcal{O} \left( \frac{\log(\epsilon^{-1} \log |\mathbb{X}|)}{\rho} \right), \quad \kappa = \mathcal{O} \left( \frac{\epsilon \rho}{\overline{D}^2 \log(\epsilon^{-1} \log |\mathbb{X}|)} \right), \quad \delta = \begin{cases} 0, & \gamma < 1, \\ \Omega(e^{-\sqrt{T}}), & \gamma = 1, \end{cases}$$

we have the following error bound with probability  $1 - O(\epsilon)$

$$D_{\text{KL}}(p_\delta \| \hat{q}_{T-\delta}) \lesssim \exp(-\rho T) \log |\mathbb{X}| + \epsilon + \overline{D}^2 \kappa T \lesssim \epsilon,$$

and the total number of neural network evaluations is

$$N = \kappa^{-1} T = \mathcal{O} \left( \frac{\overline{D}^2 \rho^2 \log^2(\epsilon^{-1} \log |\mathbb{X}|)}{\epsilon} \right)$$



# Convergence Guarantee for Uniformization

## Theorem (Theoretical Guarantees for Uniformization)

Take block discretization scheme  $(s_b)_{b \in [0, N]}$  satisfying  $s_0 = 0, s_N = T - \delta$  and  $s_{k+1} - s_k \leq \kappa (1 \vee (T - s_{k+1}))$  for  $k \in [0 : N - 1]$ . Under aforementioned assumptions and the following choices of parameters

$$T = \mathcal{O} \left( \frac{\log(\epsilon^{-1} \log |\mathbb{X}|)}{\rho} \right), \delta = \Omega(e^{-T})$$

we have the following error bound

$$D_{\text{KL}}(p_\delta \| q_{T-\delta}) \lesssim \exp(-\rho T) \log |\mathbb{X}| + \epsilon \lesssim \epsilon,$$

and the total number  $N$  of neural network evaluations satisfies

$$\mathbb{E}[N] = \mathcal{O} \left( \frac{\bar{D} \log(\epsilon^{-1} \log |\mathbb{X}|)}{\rho} \right)$$

.

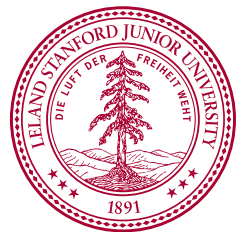
# Major technique: Change of Measure for Poisson Random Measure

## Theorem (Generalized Girsanov's Theorem for Poisson Random Measure)

Let  $N[\lambda](dt, dy)$  be a Poisson random measure with evolving intensity  $\lambda_t(y)$  in the probability space  $(\Omega, \mathcal{F}, \mathbb{P})$ , and

$$\log \frac{d\mathbb{Q}}{d\mathbb{P}} \Big|_{\mathcal{F}_t} = \int_0^t \int_{\mathbb{X}} \log h_t(y) N[\lambda](dt \times dy) - \int_0^t \int_{\mathbb{X}} (h_t(y) - 1) \lambda_t(y) \nu(dy).$$

Then  $N[\lambda](dt, dy)$  under  $\mathbb{Q}$  is a Poisson random measure with evolving intensity  $\lambda_t(y)h_t(y)$ .



Thank you for your attention!

# References I

---



Andrew Campbell, Joe Benton, Valentin De Bortoli, Thomas Rainforth, George Deligiannidis, and Arnaud Doucet, *A continuous time framework for discrete denoising models*, Advances in Neural Information Processing Systems **35** (2022), 28266–28279.



Hongrui Chen and Lexing Ying, *Convergence analysis of discrete diffusion model: Exact implementation through uniformization*, arXiv preprint arXiv:2402.08095 (2024).



Daniel T Gillespie, *Approximate accelerated stochastic simulation of chemically reacting systems*, The Journal of chemical physics **115** (2001), no. 4, 1716–1733.



Nico M Van Dijk, *Uniformization for nonhomogeneous markov chains*, Operations research letters **12** (1992), no. 5, 283–291.