Global Identifiability of Overcomplete Dictionary Learning via L1 and Volume Minimization

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Dictionary Learning

▶ Given data matrix X, find dictionary matrix $A_{m \times k}$ and sparse coefficients $S_{k \times n}$

$$x_i = As_i, \qquad i = 1, \dots, n \qquad \Rightarrow \qquad X = AS$$

- ▶ Completeness of the dictionary $A_{m \times k}$: usually assume $m \le k$:
 - complete DL: m = k
 - overcomplete DL: m < k (in this paper)
- Assume there exists a groundtruth generative model $X = A_{\natural}S_{\natural}$,

(unconstrained) matrix factorization not identifiable without additional assumption

$$X = AS = (AQ)(Q^{-1}S) = \widetilde{A}\widetilde{S}$$

Previous Work

 \bigstar Model is **identifiable** if for any (A_{\star}, S_{\star}) there exist permutation Π and diagonal D that

$$A_{\natural} = A_{\star} \boldsymbol{\Pi} \boldsymbol{D}, \quad S_{\natural} = \boldsymbol{D}^{-1} \boldsymbol{\Pi}^{\top} S_{\star}$$

- ▶ Identifiability of hard sparsity-constrained DL: $||s_i||_0 \le s$ for all i
 - sample size n is $O((k+1)\binom{k}{s})$ [Aharon et al., 2006],[Hillar and Sommer, 2015]
 - sample size $O(k^3/(k-s)^2)$ [Cohen and Gillis, 2019]

Previous Work

▶ Local identifiability with ℓ_1 regularization:

$$\underset{A.S}{\operatorname{minimize}} \quad \|S\|_1 \qquad \text{subject to} \quad X = AS, \|A_{:,c}\| \leq 1, c = 1, \dots, k$$

[Gribonval and Schnass, 2010],[Wu and Yu, 2017],[Wang et al., 2020]

- Sample size requirement has been down to $n = O(k \log(k))$.
- But the results are dominantly local.

Previous Work

- ► Global identifiability is achieved by Hu and Huang [2023], Sun and Huang [2024]
 - using a matrix volume criterion $|\det A|$ while constraining the ℓ_1 norms of the rows of S with same sample complexity $n = O(k \log(k))$
 - although as the criterion suggests it only applies to complete dictionaries

Identifiability

Definition: identifiability

Consider the generative model $X=A_{\natural}S_{\natural}$, where A_{\natural} and S_{\natural} are the groundtruth latent factors. Let (A_{\star},S_{\star}) be optimal for an identification criterion q

$$(A_{\star}, S_{\star}) = \underset{X=AS}{\operatorname{arg\,min}} q(A, S).$$

If A_{\natural} and/or S_{\natural} satisfy some condition such that for any (A_{\star}, S_{\star}) , there exist a permutation matrix $I\!\!I$ and a diagonal matrix $D\!\!I$ such that $A_{\natural} = A_{\star}DI\!\!I$, then we say A_{\natural} is essentially identifiable, up to permutation and scaling, under that condition; if we further have that $S_{\natural} = I\!\!I^{\top}\!\!D^{-1}S_{\star}$, then we say that the matrix factorization model is essentially identifiable, up to permutation and scaling, under that condition.

Our Work

★ Novel formulation for overcomplete dictionary

minimize
$$\frac{1}{2} \log \det \mathbf{A} \mathbf{A}^{\top} + \max_{\|\mathbf{d}\|_{2}^{2} = m} \sum_{c=1}^{k} d_{c} \|\mathbf{e}_{c}^{\top} \mathbf{S}\|_{1} \quad \text{subject to } \mathbf{X} = \mathbf{A} \mathbf{S}$$
(1)

- ▶ (1) is our identification criterion
- ▶ What are the conditions for the identifiability of A_{\flat} and S_{\flat} ?

Identifiability of A_b

Novel formulation for overcomplete dictionary

minimize
$$\frac{1}{2} \log \det \mathbf{A} \mathbf{A}^{\top} + \max_{\|\mathbf{d}\|_{2}^{2}=m} \sum_{c=1}^{k} d_{c} \|\mathbf{e}_{c}^{\top} \mathbf{S}\|_{1} \quad \text{subject to } \mathbf{X} = \mathbf{A} \mathbf{S}$$
(1)

▶ Optimal scaling: $d_{\star c}$ are the optimal weights that reach the maximum of $\sum_c d_c \| \boldsymbol{e}_c^{\top} \mathbf{S}_{\star} \|_1$.

$$\|\boldsymbol{e}_{c}^{\mathsf{T}}\boldsymbol{S}_{\star}\|_{1} = \sqrt{\left[\boldsymbol{A}_{\star}^{\mathsf{T}}\left(\boldsymbol{A}_{\star}\boldsymbol{A}_{\star}^{\mathsf{T}}\right)^{-1}\boldsymbol{A}_{\star}\right]_{cc}} = d_{\star c}, \qquad c = 1, \dots, k.$$
 (2)

Identifiability of A_{b}

Assumption 1:

The columns of A_{\natural} and rows of S_{\natural} are scaled to satisfy (2).

Assumption 2:

Rows of A_{\natural} and S_{\natural} are both linearly independent. Matrix A_{\natural} does not contain zero columns.

Assumption 3: *m*-strongly scattered in the *k*-hypercube

Identifiability of A_1

Assumption 3: *m***-strongly scattered in the** *k***-hypercube**

Let C_k denote the k-hypercube $C_k = \{x \in \mathbb{R}^k \mid ||x||_{\infty} \leq 1\}$. Define \mathcal{B}_m as the following set

$$\mathcal{B}_m = \{ \operatorname{Diag}(\|\boldsymbol{q}_1\|_2, \dots, \|\boldsymbol{q}_k\|_2)^{\dagger} \boldsymbol{Q} \boldsymbol{p} \mid \forall \boldsymbol{Q} \in \mathbb{R}^{k \times m} : \boldsymbol{Q}^{\top} \boldsymbol{Q} = \boldsymbol{I}, \, \boldsymbol{p} \in \mathbb{R}^m : \|\boldsymbol{p}\|_2 = 1 \},$$

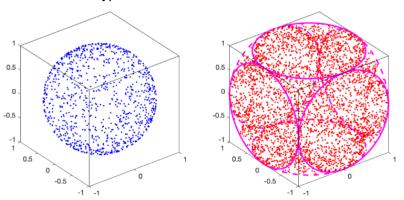
where q_c denotes the cth row of Q. A set S is m-strongly scattered in the k-hypercube if:

- ② $\partial \mathcal{B}_m \cap \partial \mathcal{S} = \{ \operatorname{Diag}(\|\boldsymbol{q}_1\|_2, \dots, \|\boldsymbol{q}_k\|_2)^{\dagger} \boldsymbol{Q} \boldsymbol{q} / \|\boldsymbol{q}\|_2 \}$, where \boldsymbol{q} are rows of \boldsymbol{Q} with $\boldsymbol{Q}^{\dagger} \boldsymbol{Q} = \boldsymbol{I}$ and ∂ denotes the boundary of the set.

Identifiability of A_{b}

Assumption 3: *m***-strongly scattered in the** *k***-hypercube**

► An illustration of sufficiently scattered and 2-strongly scattered in 3-hypercube:



Identifiability of A_{\flat}

Assumption 3: *m*-strongly scattered in the *k*-hypercube

- ★ Strong generalization of Sufficiently Scattered condition in Hu and Huang [2023].
- ★ A significant breakthrough not only in Dictionary Learning but also in general matrix factorization models when the ambient dimension is smaller than the latent dimension.

Identifiability of A_1

Theorom 1: Identifiability of A_{\natural}

An overcomplete dictionary A_{\natural} is identifiable if the groundtruth A_{\natural} and S_{\natural} satisfies Assumption 1, 2 and $\operatorname{cell}(\widetilde{S}_{\natural})$ satisfies Assumption 3.

It will be imposed on the cellular hull of S_{\natural} , which is defined as follows:

Definition (Cellular hull)

The cellular hull of a finite set of vectors $\{s_1, \ldots, s_n\}$, stacked as the columns of the matrix S, is

$$\operatorname{cell}(S) = \left\{ S\theta \mid \|\theta\|_{\infty} \leq 1 \right\}.$$

Identifiability of S_1

 \blacktriangleright With the knowledge of the dictionary, the identifiability of S_{\natural} has been studied extensively. A general condition for S_{\natural} is identifiable:

Assumption 4:

Every column of S_{\natural} contains at most s nonzeros. In addition, A_{\natural} is a dictionary such that for every s_0 with no more than s nonzeros, s_0 is the unique solution to the following optimization problem

$$\underset{s}{\text{minimize}} \quad \|s\|_1 \qquad \text{subject to} \quad A_{\natural} D_{\natural}^{-1} s = A_{\natural} D_{\natural}^{-1} s_0,$$

where D_{\natural} is a diagonal matrix with

$$[oldsymbol{D}_{
abla}]_{cc} = \sqrt{\left[oldsymbol{A}_{
abla}^{ op} \left(oldsymbol{A}_{
abla}^{ op}
ight)^{-1}oldsymbol{A}_{
abla}
ight]_{cc}}, \qquad c = 1, \ldots, k.$$

Identifiability Analysis

Theorom 1: Identifiability of A_{\natural}

An overcomplete dictionary A_{\natural} is identifiable if the groundtruth A_{\natural} and S_{\natural} satisfies Assumption 1, 2 and $\operatorname{cell}(\widetilde{S}_{\natural})$ satisfies Assumption 3.

Corollary:

Consider the overcomplete DL model $X=A_{\natural}S_{\natural}$, where $A_{\natural}\in\mathbb{R}^{m\times k}$ is the groundtruth mixing matrix and $S_{\natural}\in\mathbb{R}^{k\times n}$ is the groundtruth sparse coefficient matrix. Suppose A_{\natural} and S_{\natural} satisfies Assumptions 1–4. Then for any solution of (1), denoted as (A_{\star},S_{\star}) , there exist a permutation matrix $\boldsymbol{\varPi}$ and a diagonal matrix \boldsymbol{D} such that $A_{\natural}=A_{\star}\boldsymbol{D}\boldsymbol{\varPi}$ and $S_{\natural}=\boldsymbol{\varPi}^{\top}\boldsymbol{D}^{-1}S_{\star}$.

Sample Complexity Analysis

- ▶ Sparse-Gaussian model: $S \sim \mathcal{SG}(s)$ with parameter s < k, if every column of S is independently and identically distributed from the following process
 - a subset \mathcal{I} of size s is uniformly drawn from all size-s subsets of $\{1, \ldots, k\}$
 - let $s \in \mathbb{R}^k$ be such that $s_i = 0$ if $i \in \mathcal{I}$ and $s_i \sim \mathcal{N}(0, 1)$ if $i \notin \mathcal{I}$, where $\mathcal{N}(0, 1)$ stands for a standard normal distribution

Sample Complexity Analysis

▶ Sparse-Gaussian model: $S \sim SG(s)$ with parameter s < k.

Theorem 2:

Suppose $S \in \mathbb{R}^{k \times n}$ is generated from the sparse-Gaussian model $\mathcal{SG}(s)$, where s < m, and \widetilde{S} is obtained by scaling its rows to have unit ℓ_1 norm. Then

$$\Pr\left[\sup_{\substack{\|\boldsymbol{w}^{\top}\tilde{\mathbf{S}}\|_{1} \leq 1 \\ \boldsymbol{\mathcal{Q}}^{\top}\boldsymbol{\mathcal{Q}} = \boldsymbol{I}}} \|\boldsymbol{\mathcal{Q}}^{\top}\boldsymbol{D}^{\dagger}\boldsymbol{w}\| > 1\right] \leq 4\exp\left(\frac{k}{2}\log\frac{k^{2}}{m} - n\frac{s^{2}m}{k^{3}}\right). \quad (3)$$

The probability goes to zero exponentially fast as

$$n = O\left(\frac{k^2}{m}\log\frac{k^2}{m}\right).$$

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