

Continuous Multinomial Logistic Regression for neural decoding

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ICLR

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Background: Multinomial Logistic Regression (MLR) for neural decoding

neural population activity



sensory/behavioral variables



continuous

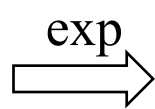
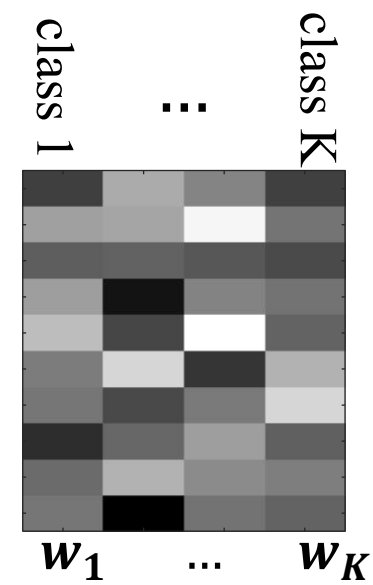
Multinomial Logistic Regression (MLR)

input feature vector

$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_D \end{bmatrix}$$

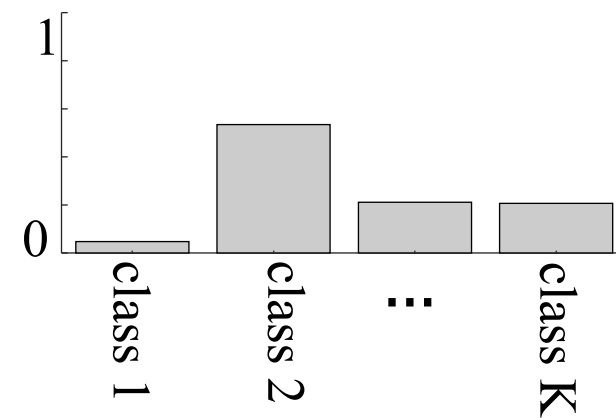
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decoding weight matrix



output distribution

$$p(Y = k|\mathbf{x}) \propto \exp(\mathbf{w}_k^T \mathbf{x})$$

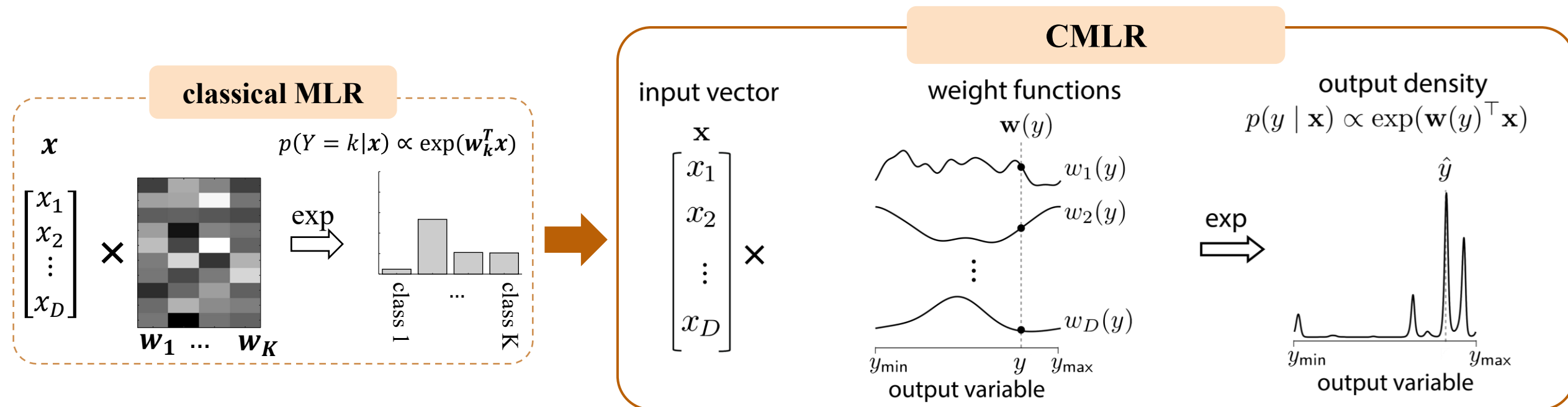


C
M
L
R

discrete

Limitation: MLR requires **output discretization**, reducing accuracy

Continuous Multinomial Logistic Regression (CMLR) model



- **Gaussian Process (GP) priors:** induce smoothness in the decoding weight functions

$$w_d(y) \sim \mathcal{GP}(\mathbf{0}, K_d) \quad K_d(y', y'') = \rho_d \exp\left(-\frac{(y' - y'')^2}{2\ell_d^2}\right)$$

- **Conditional Density Estimation (CDE):** CMLR defines an output conditional density

$$p(Y = y | \mathbf{x}) = \frac{\exp(\mathbf{w}(y)^T \mathbf{x})}{\int_{\Omega} \exp(\mathbf{w}(y')^T \mathbf{x}) dy'}$$

CMLR model inference and output prediction

➤ Stochastic Variational Inference (SVI): scalable frequency domain implementation

- observations $\{\mathbf{x}_n, y_n\}_{n=1:N} \rightarrow$ infer weight functions $\mathbf{w}(y) = \{w_d(y)\}_{d=1:D}$

➤ Output prediction: decode outputs at any desired resolution

- test sample $\mathbf{x}_n \rightarrow$ compute the posterior over an output grid $\{\tilde{y}_j\}_{j=1:J}$

$$p(y_n = \tilde{y}_j \mid \mathbf{x}_n, \mathbf{w}(y)) = \frac{\exp(\mathbf{w}(\tilde{y}_j)^\top \mathbf{x}_n)}{\sum_{j'=1}^J \exp(\mathbf{w}(\tilde{y}_{j'})^\top \mathbf{x}_n)}$$

posterior mean

$$\hat{y}_{\text{mean}} = \sum_{j=1}^J \tilde{y}_j \cdot p(y_n = \tilde{y}_j \mid \mathbf{x}_n, \mathbf{w}(y))$$

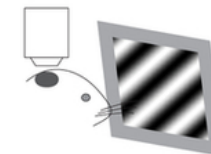
regression-style tasks

posterior mode

$$\hat{y}_{\text{mode}} = \arg \max_{j \in \{1:J\}} p(y_n = \tilde{y}_j \mid \mathbf{x}_n, \mathbf{w}(y))$$

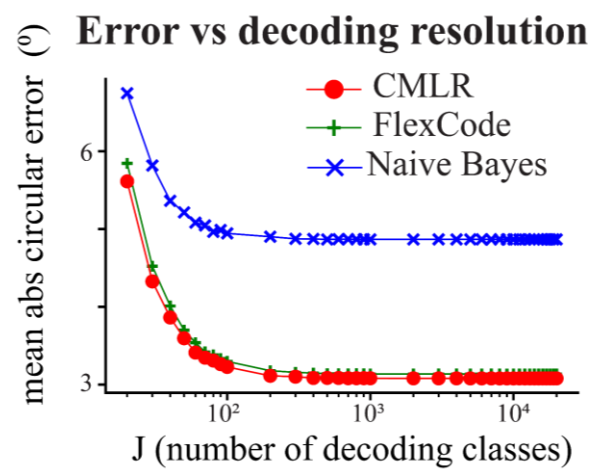
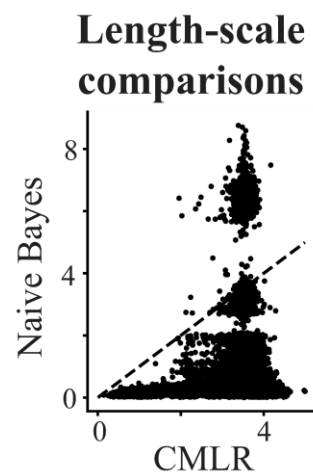
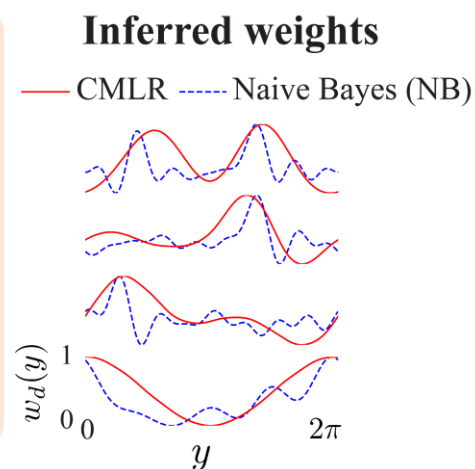
classification-style tasks

Mouse primary visual cortex (V1): decoding drifting grating orientation



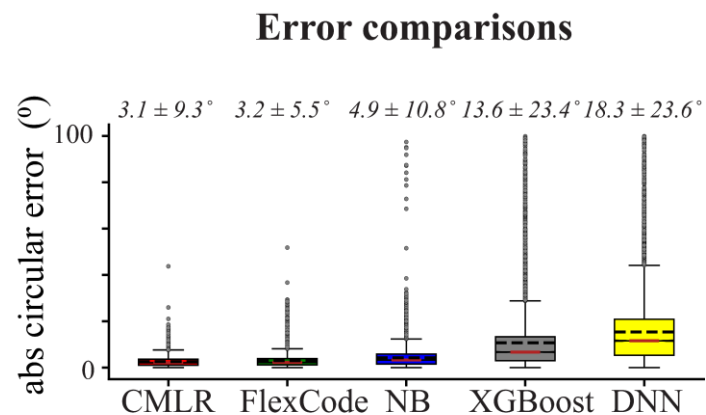
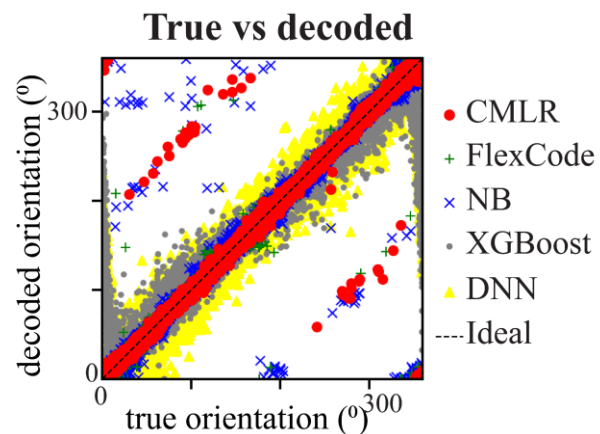
- **Input:** 3 calcium imaging datasets of mouse V1 [Stringer et al., 2021]
- **Output:** orientations $y \in [0, 2\pi)$, $D \sim 10^4$ neurons, $N \sim 4000$ samples

Comparing with
Naïve Bayes



Neural correlations
boosts performance

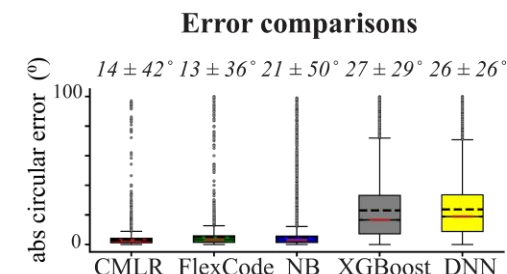
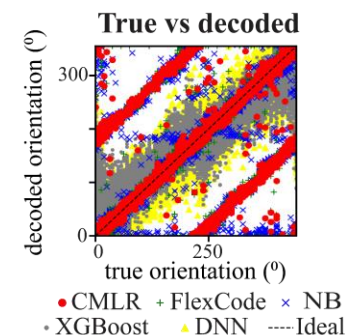
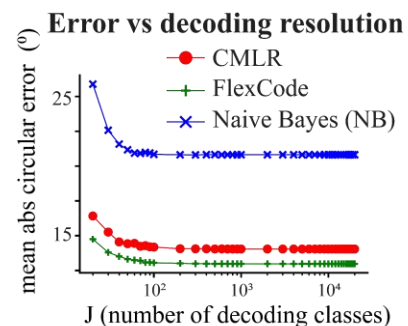
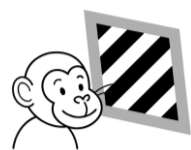
Comparing with
all baselines



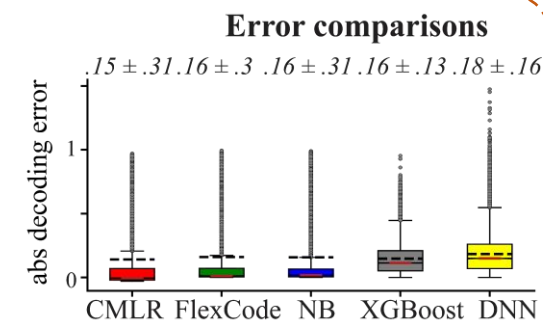
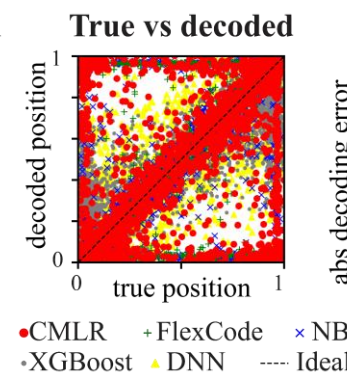
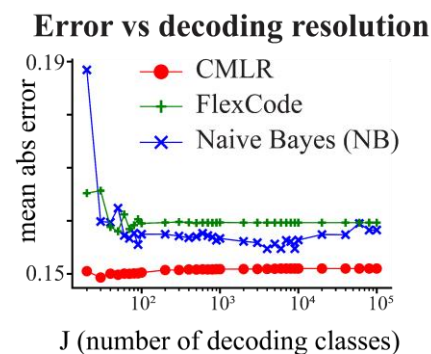
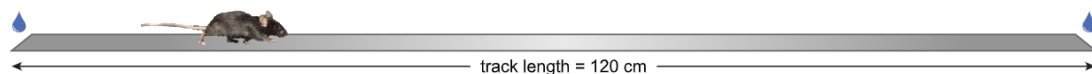
Consistent gains over
strong baselines

CMLR decoding applications...

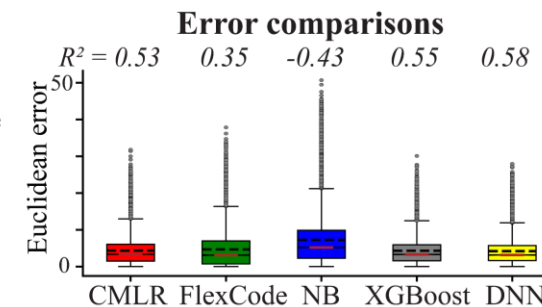
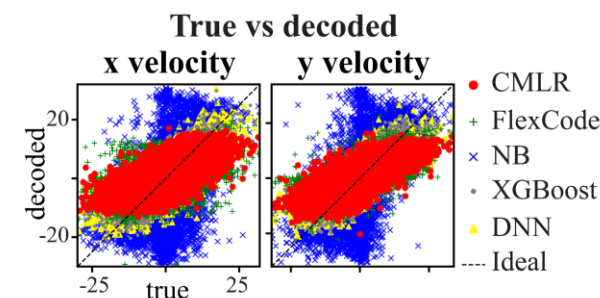
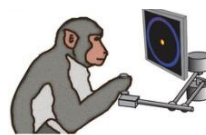
➤ **Macaque V1:**
decoding **discrete** grating orientation



➤ **Hippocampus CA1:**
decoding **position** during navigation



➤ **Motor Cortex:**
decoding **2D velocity** in a reaching task



Conclusions

- **Continuous Multinomial Logistic Regression (CMLR):**
extends MLR to continuous decoding variables
- **Gaussian process tuning functions:**
smooth and interpretable neuron-specific weights
- **Flexible conditional density estimation (CDE):**
captures circular, multimodal, and asymmetric distributions
- **Strong empirical performance:**
outperforms Naive Bayes, XGBoost, DNNs, and FlexCode across datasets

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Data sources:

- Stringer et al., 2021 (mouse V1 datasets)
- Graf et al., 2011 (macaque V1 datasets)
- Hazon et al., 2022 (mouse CA1 datasets)
- Glaser et al., 2018 (monkey MC dataset)

