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ICLR

Distributionally Robust Optimization Via Generative Ambiguity Modeling

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- **Generalization For Generative Models**
 - **Reality Gap**
 - Generative environment \neq Real-world
 - Unseen real-world environments introduce distribution shift
 - **Robustness Limitation**
 - Generative models fail to capture worst-case scenarios
 - **Deployment Challenge**
 - Critical barrier for safety-critical systems



- **Limitation For Traditional DRO**

Distributionally Robust Optimization (DRO):

$$w = \min_{w \in \mathcal{W}} \max_{P \in \mathcal{B}(P_0, \epsilon)} \mathbb{E}_{x \sim P} [f(w, x)]$$

- $f(w, x)$: the objective with the decision variable $w \in \mathcal{W}$ and input x
- $\mathcal{B}(P_0, \epsilon)$: $\mathcal{B}(P_0, \epsilon) = \{P \mid D(P, P_0) < \epsilon\}$ the ambiguity set with budget ϵ .
- $P_0(x)$: the nominal distribution

- **ϕ -Divergence DRO**: Enforce absolute continuity ($P \ll P_0$), preventing support shift and leading to weak robustness under distribution drift.
- **Wasserstein DRO**: Suffer from computational intractability and conservative approximations, limiting its effectiveness.

- **Our Goal:**

- Bridge generative models and DRO via Generative Ambiguity Modeling
- Address the challenge of modeling expressive adversarial distributions
- Maintain computational tractability

- **Generative Ambiguity Modeling**

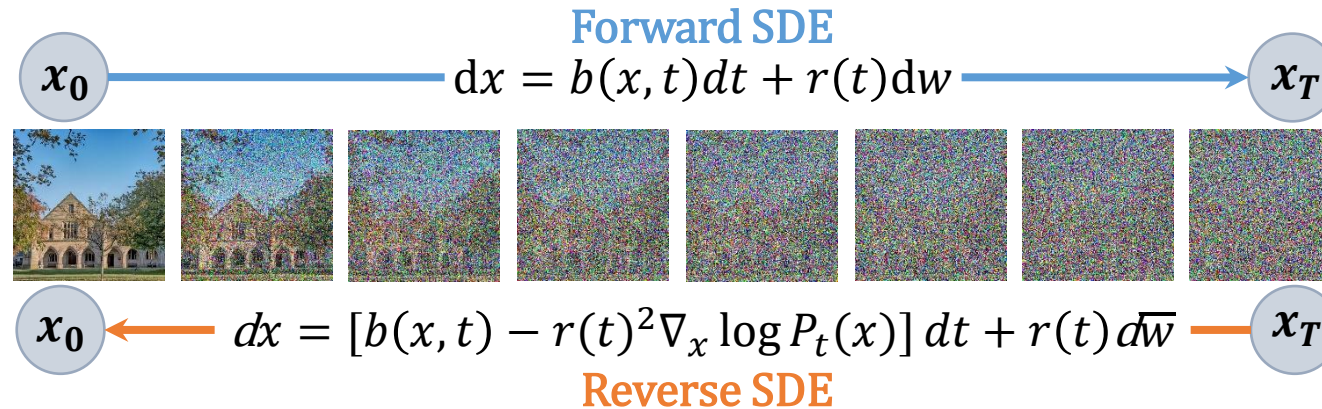
- Well-trained generative models approximate the nominal distribution, while their perturbations induce controlled deviations.
- A generative model that can be used for generative ambiguity modeling if it satisfies:

Lemma 1 The *inclusive* KL-divergence between the nominal distribution P_0 and the sampling distribution P_θ of a likelihood-based generative model can be bounded as

$$D_{KL}(P_0 || P_\theta) \leq J(\theta, P_0) + R(p', P_0) + C_1$$

- $J(\theta, P_0)$: A reconstruction loss (e.g., Diffusion or VAE)
- $R(p', P_0)$: A prior matching term independent of θ
- C_1 : A constant term unrelated to θ .

- Modeling For Diffusion:



- Score Matching Loss:** The reverse process relies on a model $s_\theta(x, t)$, trained via a score-matching loss J_{SM} to approximate $\nabla_x \log P_t(x)$.

$$J_{SM}(\theta) = \int_0^T \mathbb{E}_{P_t(x)} [\iota(t) \|\nabla_x \log P_t(x) - s_\theta(x, t)\|^2] dt$$

- Inclusive KL-divergence Bound:**

$$D_{KL}(P_0(x_0) || P_\theta(x_0)) \leq \underbrace{J_{SM}(\theta, P_0)} + \underbrace{\mathbb{E}_{P_0(x)} [D_{KL}[q(x_T | x_0) || p(x_T)]]} + \underbrace{[d \log(\sqrt{2\pi\sigma_1}) - H(P_0)]}$$



- **Modeling For VAE:**

- **Reconstruction Loss:** The reconstruction loss encourages the learned model to regenerate data that is consistent with the original data distribution.

$$J_{VAE}(\theta, P_0) = \mathbb{E}_{x \sim P_0} [\mathbb{E}_{q_\varphi(z|x)} [-\ln p_\theta(x|z)]]$$

- **Inclusive KL-divergence Bound:**

$$\begin{aligned} & D_{KL}(P_0(x_0) || P_\theta(x_0)) \\ & \leq \underbrace{\mathbb{E}_{P_0(x)} \mathbb{E}_{q_\varphi(z|x)} [-\log_{p_\theta}(x|z)]}_{\text{orange dashed}} + \underbrace{\mathbb{E}_{P_0(x)} [D_{KL}[q_\varphi(z|x) || p'(z)]]}_{\text{green dashed}} \underbrace{[-H(P_0(x))]}_{\text{blue dashed}} \end{aligned}$$



- **Design Goals of GAS**

- **Expressive Robustness:** Capture adversarial distributions beyond the nominal support
- **Tractable Optimization:** Enable efficient inner maximization in the generative parameter space

- **GAS-DRO Objective**

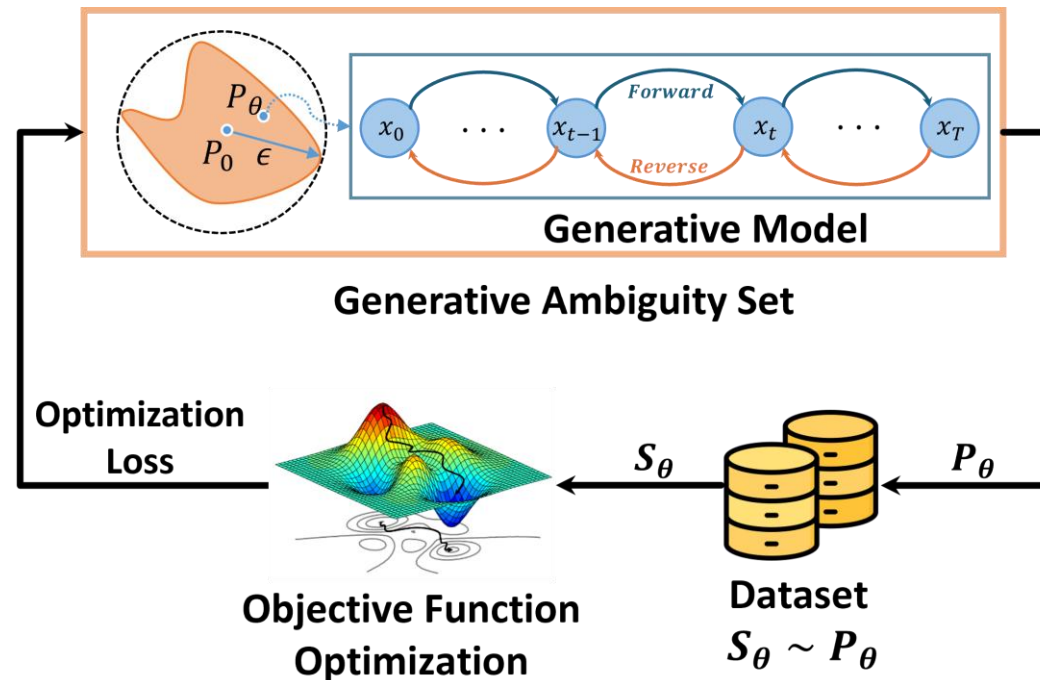
$$\min_{w \in \mathcal{W}} \max_{\theta \in \Theta} \mathbb{E}_{x \sim P_\theta} [f(w, x)], \quad \text{s. t. } J(\theta, P_0) \leq \epsilon$$

- **Generative-Based Inner Maximization**

- **Dual Learning:**

- We solve the inner maximization by converting the constraint into a Lagrangian relaxed objective and updating the dual variable μ to enforce $J(\theta, P_0) \leq \epsilon$.

$$\max_{\theta} \mathbb{E}_{x \sim P_{\theta}} [f(w, x)] - \mu \cdot J(\theta, P_0) \quad \mu \leftarrow \max\{ 0, \mu + \eta \cdot (J(\theta, P_0) - \epsilon) \}$$

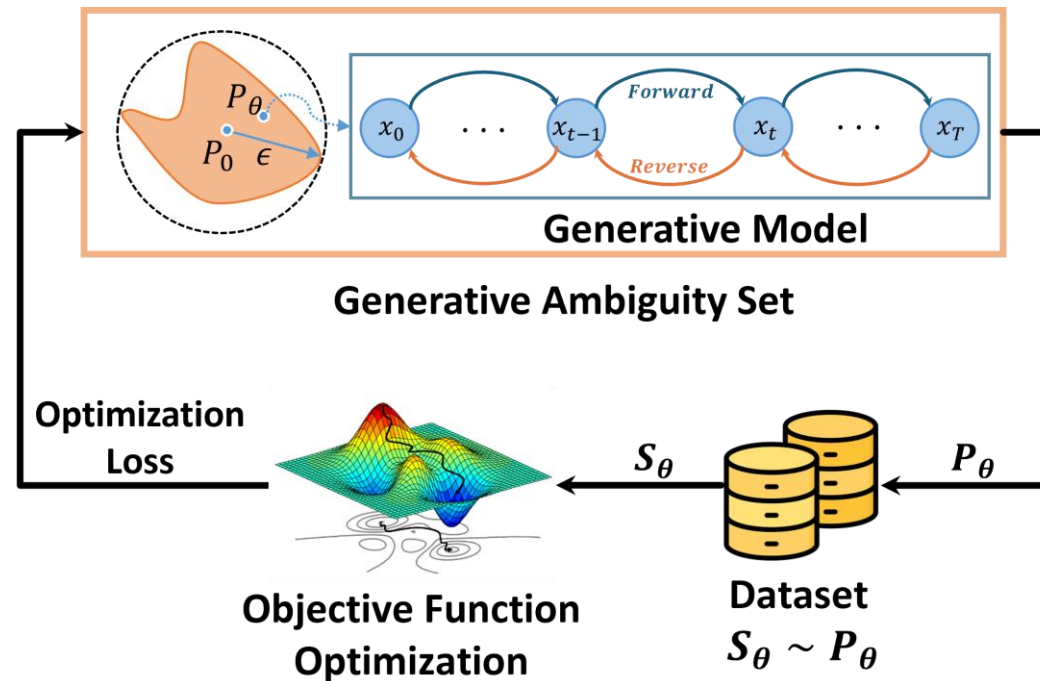


- **Generative-Based Inner Maximization**

- **Policy Optimization:**

- We apply Proximal Policy Optimization (PPO) to get a tractable form.

$$\max_{\theta} \widehat{\mathbb{E}}_{P_{\theta_{old}}}(x_{0:T}) \left[\min(r_{\theta}(x_{0:T})f(w, x_0), \text{clip}(r_{\theta}(x_{0:T}), 1 - k, 1 + k)f(w, x_0)) \right] - \mu \cdot J(\theta, P_0)$$



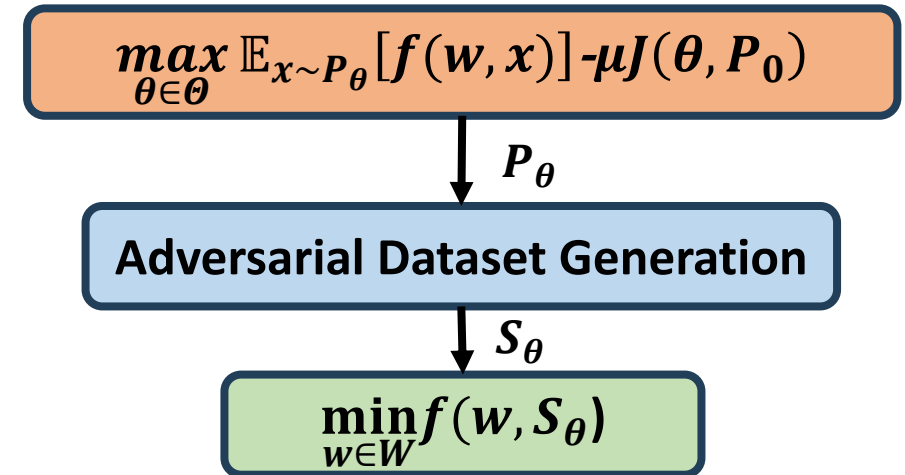
- **GAS-DRO Algorithm**

- **Inner Maximization for Worst-Case Searching:**

- Identify the worst-case generative model P_θ for the current w .

- **Adversarial Update of w**

- Generate adversarial samples from P_θ to update w , with convergence guaranteed.



• Convergence of Inner Maximization

Theorem 1 [informal] Let P_{θ^*} be the optimal generative model for the inner maximization problem and P_{θ_k} be the generative model in the k -th loop, the expected reward gap between P_{θ^*} and P_{θ_k} diminishes with K . The inner maximization error holds:

$$\Delta' := \mathbb{E}_{P_{\theta^*}}[f] - \mathbb{E}_{k \in [K]} \mathbb{E}_{P_{\theta_k}}[f] \sim O\left(\frac{1}{\sqrt{K}}\right)$$

The reversed KL divergence between P_0 and P_{θ_k} is bounded:

$$\mathbb{E}_{k \in [K]} D_{KL}(P_0 \parallel P_{\theta_k}) \leq \epsilon + D_{KL}(P_T \parallel \pi) + C_1 + O\left(\frac{1}{\sqrt{K}}\right)$$

- **Convergence:** With sufficient iterations K , the inner maximization error becomes negligible.
- **Consistent Worst-Case:**
 - $D_{KL}(P_0 \parallel P_{\theta})$ is bounded by: ϵ , prior matching error $R(\pi, P_0)$, and constant C_1
 - GAS-DRO finds worst-case distributions that remain consistent with the nominal distribution via ϵ

• Convergence of GAS-DRO

Theorem 2 [informal] If $f(w, x)$ is β – smooth, L – Lipschitz and is upper bounded by \bar{f} , GAS-DRO converges to a near-stationary point of the smoothed robust objective $\phi(w) = \max_{\theta} \mathbb{E}_{P_{\theta}} [f(w, x)]$. The average norm of Moreau envelope of $\phi(w)$ satisfies:

$$\mathbb{E}_{j,k} \left[\left\| \nabla \phi_{\frac{1}{2\beta}}(w) \right\|^2 \right] \leq 4\beta\Delta' + \frac{V_1}{\sqrt{n}} + \frac{V_2}{\sqrt{H}}$$

$$V_1 = 8\beta\bar{f}\sqrt{\log(2/\delta)} \quad V_2 = 4L \sqrt{(\phi_{\frac{1}{2\beta}}(w_1) - \min_w \phi(w))\beta}$$

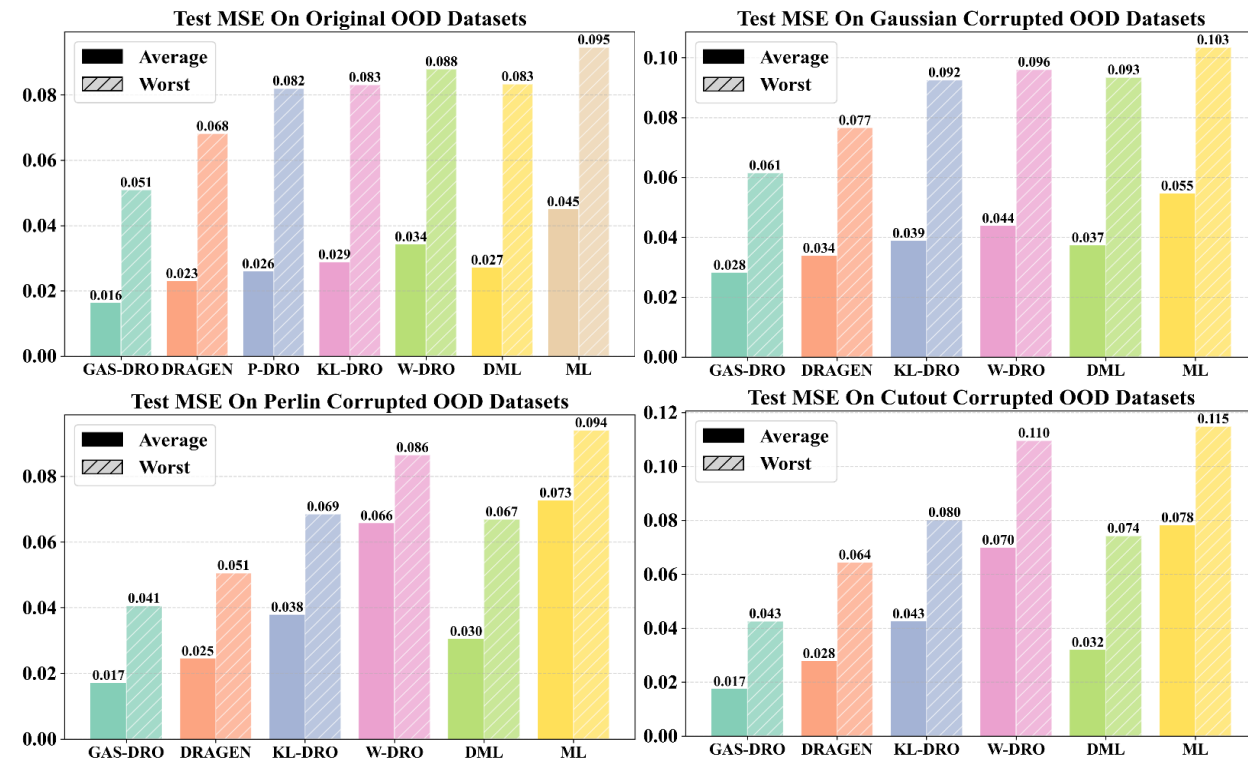
- **Bounded Gradient:** With large outer minimization iteration H and sample size n , the gradient norm $\| \nabla \phi_{1/(2\beta)}(w) \|$ is controlled by the inner error Δ' .
- **Vanishing Error:** As inner maximization iteration $K \uparrow$, $\Delta' \downarrow \Rightarrow$ gradient norm becomes sufficiently small.
- **Approximate Stationarity:** Small gradient \Rightarrow existence of nearby \hat{w} that is an approximately stationary solution

- **Task 1 - Carbon Intensity Time Series Prediction**

- **Datasets:** Original & Corrupted carbon-intensity data from Electricity Maps.

- **Results:**

- All methods outperform ML, with GAS-DRO achieving the largest gain (63.7%), followed by DRAGEN (48.9%), P-DRO (42.4%), and DML (39.7%).
- KL-DRO and W-DRO are limited by support constraints or overly conservative adversaries.
- The ablation study on GAS-DRO, DML, and ML shows that the diffusion contribute a 39.7% performance gain, while DRO provides an additional 24% improvement.

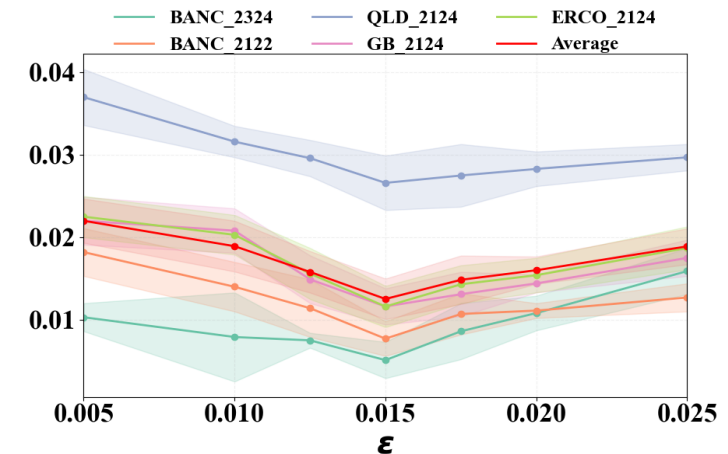
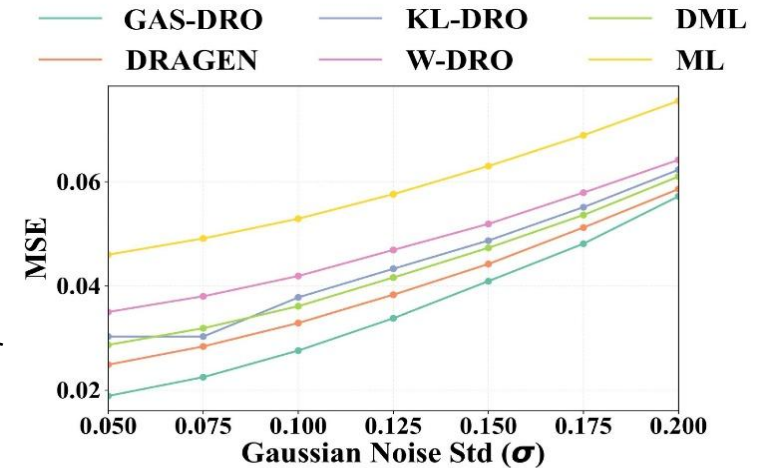


- **Task 1 - Carbon Intensity Time Series Prediction**

- **Datasets:** Original & Corrupted carbon-intensity data from Electricity Maps.

- **Results:**

- GAS-DRO consistently outperforms all baseline across varying levels of Gaussian noise corrupted datasets
- GAS-DRO performs best at our chosen budget of $\epsilon = 0.015$, which strikes the optimal balance—smaller values hurt generalization while larger ones lead to overly conservative optimization.



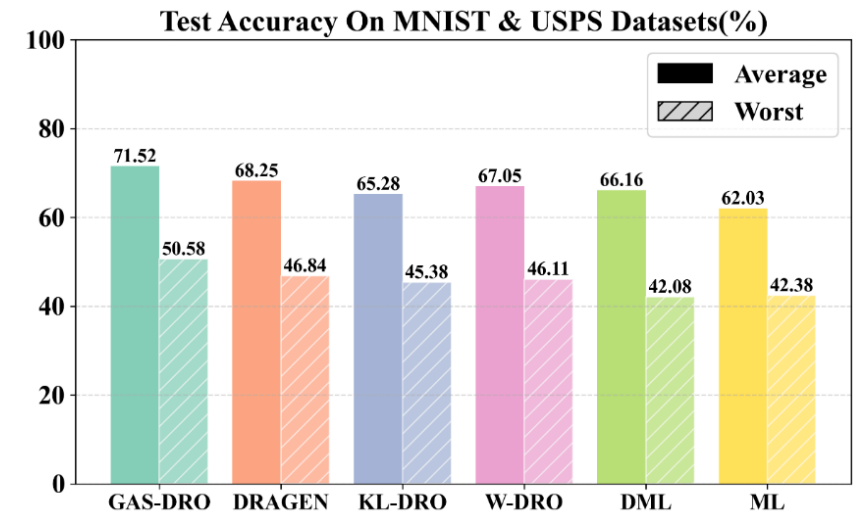
- **Task 2 – Handwritten Digit Classification**

- **Datasets:** Original & Corrupted MNIST & USPS datasets.

Note: Here, GAS-DRO employs a VAE as the generative model, the same as DRAGEN.

- **Results:**

- GAS-DRO significantly outperforms all baselines, demonstrating strong generalization and robustness.
- GAS-DRO outperforms prior methods even with the same VAE backbone as DRAGEN, demonstrating that its gains stem from ambiguity set design rather than the generative model itself.



We propose GAS-DRO, which models ambiguity sets in the parameter space of generative models:

- It enable consistent, expressive, and tractable optimization.
- It explores diverse worst-case distributions with theoretical guarantees and strong performance.

► Advantages

- Capture the data distribution, ensuring consistency with the nominal distribution.
- Generate diverse samples beyond the nominal support to discovery worst-case distribution.
- Enables tractable optimization in a finite, parameterized space via policy optimization.



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