

# IDER: IDempotent Experience Replay for Reliable Continual Learning

Zhanwang Liu \*, Yuting Li \*, Haoyuan Gao, Yexin Li,  
Linghe Kong Lichao Sun, Weiran Huang †

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SJTU MIFA LAB



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# Motivation

- Continual Learning suffers from **recency bias** and models deployed in real-world scenarios benefit from **uncertainty awareness**.
- Our analysis reveals a strong **positive correlation** between improved calibration and higher accuracy.
- This motivates us to introduce the **idempotent property** into rehearsal-based continual learning for more **reliable prediction**.

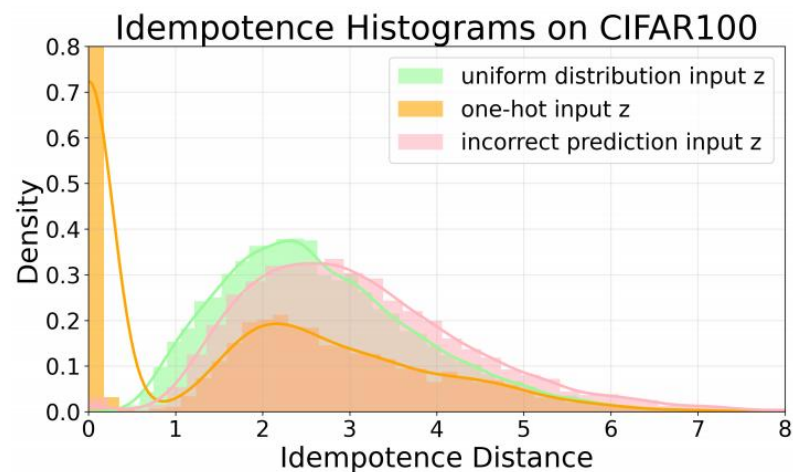
# Idempotent property

- **Formulation:**

$$f(f(x)) = f(x)$$

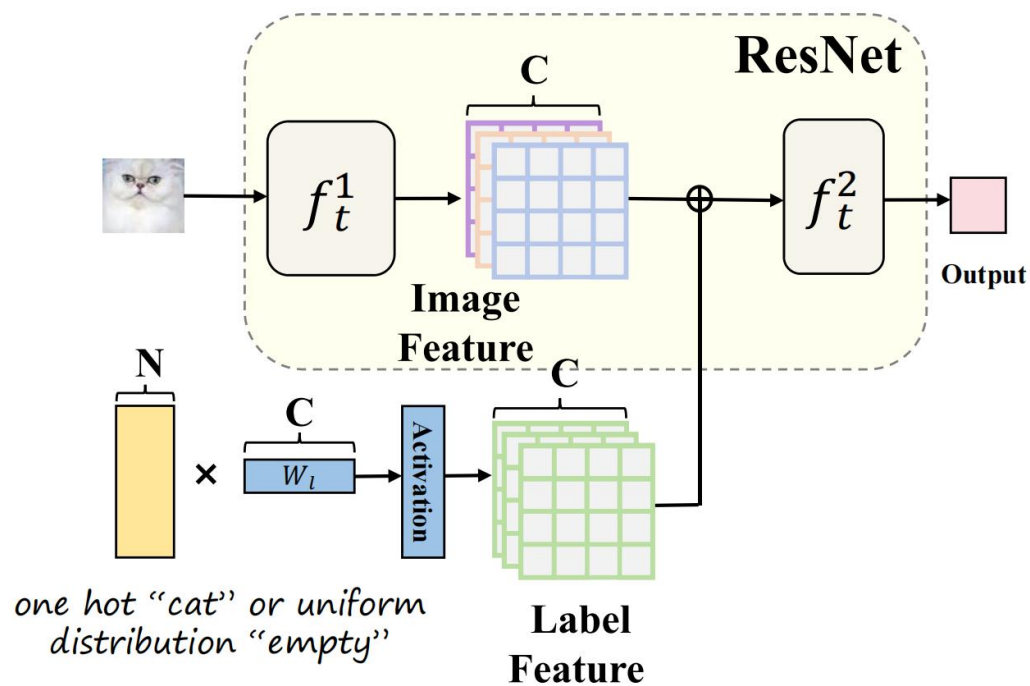
$$f(x, 0) = f(x, y) = y$$

- **It can be used to measure prediction reliability.**



# Methods

We introduce **idempotence** into continual learning by modifying the backbone to **accept a second input** in addition to the image.



# Methods

**IDER** contains two aspects:

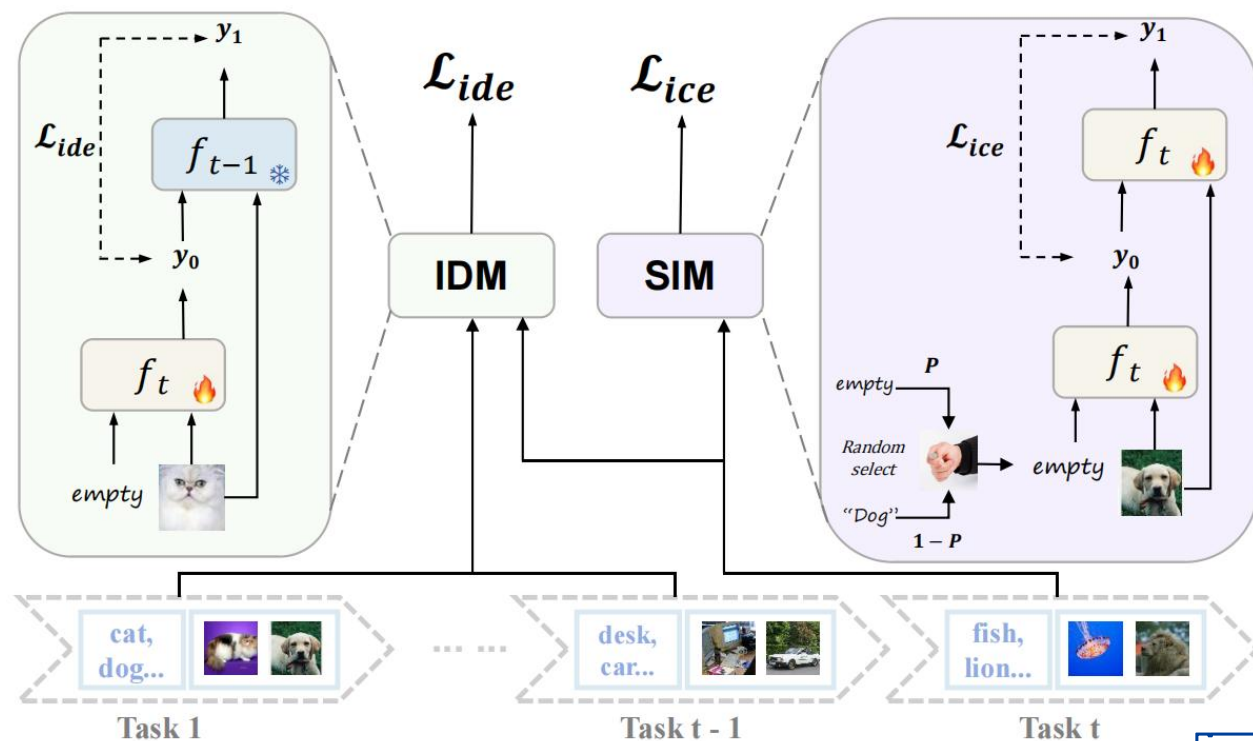
- Idempotent learning on current-task data

$$\mathcal{L}_{ice} = \sum_{(x,y) \in \mathcal{T}_t} [\mathcal{L}_{ce}(f_t(x, y^*), y) + \mathcal{L}_{ce}(f_t(x, f_t(x, y^*)), y)]$$

- Idempotent distillation from the previous model

$$\mathcal{L}_{ide} = \sum_{(x,y) \in \mathcal{T}_t, M} \|f_t(x, 0) - f_{t-1}(x, f_t(x, 0))\|_2^2$$

$$\mathcal{L}_{rep-ice} = \sum_{(x,y) \in M} [\mathcal{L}_{ce}(f_t(x, y^*), y) + \mathcal{L}_{ce}(f_t(x, f_t(x, y^*)), y)]$$



# Main Experiments

We evaluate our method on class-incremental learning setting.

Method	CIFAR-10		CIFAR-100		Tiny-ImageNet	
	Buffer 200	Buffer 500	Buffer 500	Buffer 2000	Buffer 500	Buffer 4000
Joint (upper bound)	91.93±0.29		71.15±0.51		59.52±0.33	
iCaRL (Rebuffi et al., 2017)	58.37±3.51	62.49±5.42	46.81±0.41	52.51±0.44	22.53±0.62	26.38±0.23
ER (Riemer et al., 2019)	44.46±2.87	58.84±3.85	23.41±1.15	40.47±0.95	10.13±0.39	25.12±0.56
BiC (Wu et al., 2019)	52.61±5.37	71.95±1.82	37.82±1.67	47.17±1.17	15.36±1.31	18.67±0.57
LUCIR (Hou et al., 2019)	49.18±7.61	65.26±2.54	37.91±1.18	50.42±0.76	28.79±0.51	31.64±0.51
DER (Buzzega et al., 2020)	57.92±1.91	68.65±1.82	34.83±2.09	50.12±0.75	15.14±1.29	20.35±0.35
DER++ (Buzzega et al., 2020)	62.19±1.94	70.10±1.65	37.69±0.97	51.82±1.04	19.43±1.63	36.89±1.16
ER-ACE (Caccia et al., 2021)	62.19±1.67	71.15±1.08	37.81±0.54	49.77±0.34	20.42±0.39	37.76±0.53
XDER (Boschini et al., 2022)	64.10±1.08	67.42±2.16	48.14±0.34	57.57±0.84	29.12±0.47	46.12±0.46
CLS-ER (Arani et al., 2022)	64.56±2.63	74.27±0.81	43.92±0.62	54.84±1.30	30.91±0.59	45.17±0.89
SCoMMER (Sarfranz et al., 2023)	66.95±1.52	73.64±0.43	39.05±0.79	49.42±0.85	21.47±0.54	37.2±0.70
BFP (Gu et al., 2023)	68.64±2.23	73.51±1.54	46.70±1.45	57.39±0.75	28.71±0.55	43.17±1.89
SARL (Sarfranz et al., 2025)	68.87±1.37	73.98±0.46	46.69±0.79	57.06±0.48	28.44±2.30	38.83±0.81
<b>ER+ID(Ours)</b>	<b>71.02±1.98</b>	74.74±0.42	44.82±0.85	56.59±0.35	29.88±1.15	43.05±1.40
<b>BFP+ID (Ours)</b>	<b>71.99±0.98</b>	<b>76.65±0.63</b>	<b>48.53±0.95</b>	<b>57.74±0.64</b>	30.62±0.47	43.51±0.59
<b>CLS-ER+ID (Ours)</b>	70.32±1.12	<b>75.48±0.91</b>	47.44±2.0	56.36±0.78	<b>31.62±0.57</b>	<b>46.17±0.22</b>

# Further Experiments

We evaluate our method on generalized class-incremental learning setting.

Method	Uniform				Longtail			
	Buffer 200	$\Delta$	Buffer 500	$\Delta$	Buffer 200	$\Delta$	Buffer 500	$\Delta$
Joint (upper bound)			58.36 $\pm$ 1.02				56.94 $\pm$ 1.56	
DER++ (Buzzega et al., 2020)	19.36 $\pm$ 0.65		33.66 $\pm$ 0.96		27.05 $\pm$ 1.11		25.98 $\pm$ 0.81	
SCoMMER (Sarfraz et al., 2023)	28.56 $\pm$ 2.26		35.70 $\pm$ 0.86		28.47 $\pm$ 1.12		32.99 $\pm$ 0.49	
ER (Riemer et al., 2019)	16.34 $\pm$ 0.74		28.76 $\pm$ 0.66		19.55 $\pm$ 0.69		20.02 $\pm$ 1.05	
<b>Ours (ER+ID)</b>	26.66 $\pm$ 0.63	<b>+10.32</b>	40.54 $\pm$ 0.46	<b>+11.78</b>	30.04 $\pm$ 0.58	<b>+10.49</b>	35.92 $\pm$ 0.35	<b>+15.90</b>
CLS-ER (Arani et al., 2022)	22.37 $\pm$ 0.48		36.80 $\pm$ 0.34		28.34 $\pm$ 0.99		28.35 $\pm$ 0.72	
<b>Ours (CLS-ER+ID)</b>	31.17 $\pm$ 1.62	<b>+8.80</b>	37.57 $\pm$ 1.81	<b>+0.77</b>	34.08 $\pm$ 0.45	<b>+5.74</b>	36.75 $\pm$ 0.62	<b>+8.40</b>
SARL (Sarfraz et al., 2025)	36.20 $\pm$ 0.46		38.73 $\pm$ 0.66		34.13 $\pm$ 1.07		34.64 $\pm$ 0.49	
<b>Ours (SARL+ID)</b>	36.45 $\pm$ 0.37	<b>+0.25</b>	39.65 $\pm$ 0.43	<b>+0.92</b>	35.04 $\pm$ 0.54	<b>+0.91</b>	35.67 $\pm$ 0.74	<b>+1.03</b>

# Further Experiments

Idempotence improves prediction reliability.

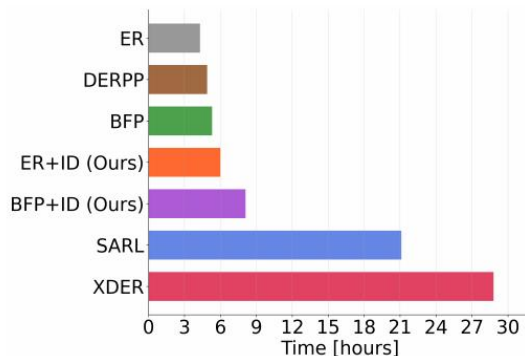
Method	CIFAR-10				CIFAR-100				Tiny-ImageNet			
	Buffer 200	$\Delta$	Buffer 500	$\Delta$	Buffer 500	$\Delta$	Buffer 2000	$\Delta$	Buffer 500	$\Delta$	Buffer 4000	$\Delta$
DER (Buzzega et al., 2020)	29.91		16.20		24.84		10.79		22.80		10.52	
NPCL (Jha et al., 2023)	21.03		-		19.95		-		-		-	
RC (Li et al., 2024a)	16.39		12.84		19.43		19.31		21.32		16.49	
T-CIL (Hwang et al., 2025)	22.50		10.51		15.79		8.67		14.50		10.30	
ER (Riemer et al., 2018)	45.53		32.69		64.59		45.64		67.50		51.37	
<b>Ours (ER+ID)</b>	12.36	<b>-33.17</b>	11.73	<b>-20.96</b>	13.65	<b>-50.94</b>	12.87	<b>-32.77</b>	21.55	<b>-49.45</b>	11.14	<b>-40.23</b>
BFP (Gu et al., 2023)	9.83		9.40		11.93		9.28		9.45		8.25	
<b>Ours (BFP+ID)</b>	9.30	<b>-0.53</b>	8.63	<b>-0.77</b>	8.92	<b>-3.01</b>	8.29	<b>-0.99</b>	7.77	<b>-1.68</b>	6.35	<b>-1.9</b>

# Further Analysis

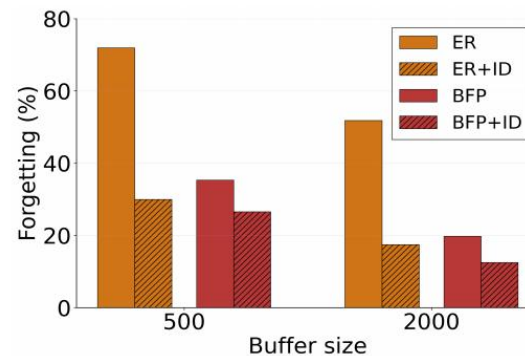
The modified backbone has **negligible** impact on the performance.

Model	Method	Accuracy (%)	Forgetting (%)
Normal ResNet-18	Finetune	8.29	90.52
	ER	24.36	71.30
Modified ResNet-18	Finetune	8.23	90.58
	ER	24.73	70.61

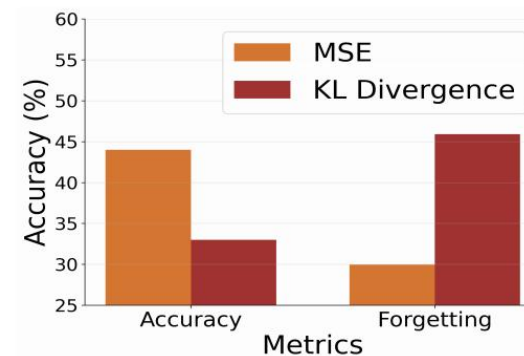
IDER substantially **reduces forgetting** with **minimal additional training cost**, while **MSE** outperforms KL divergence.



(a) Training Times



(b) Forgetting on CIFAR-100



(c) Distance Metrics





# Thank you

## Paper



## Github

