

MULTIMAT

Multimodal Program Synthesis for Procedural Materials using Large Multimodal Models

Jonas Belouadi Tamy Boubekeur Adrien Kaiser

Adobe Research University of Mannheim

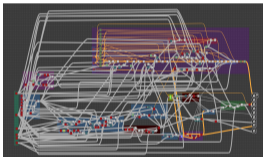
March 30, 2026

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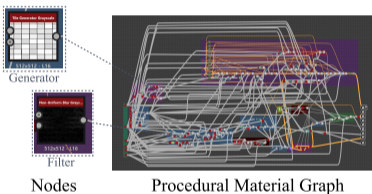


Procedural Material Graph

- acyclic node graphs that describe appearances

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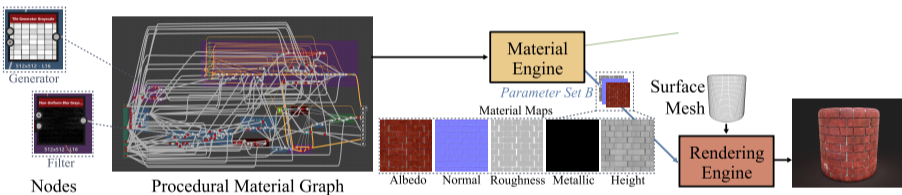
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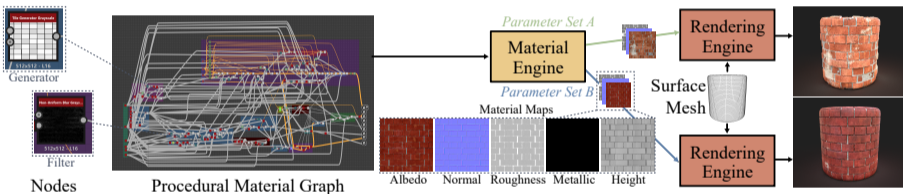
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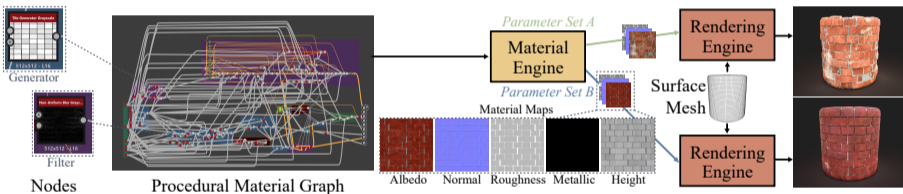
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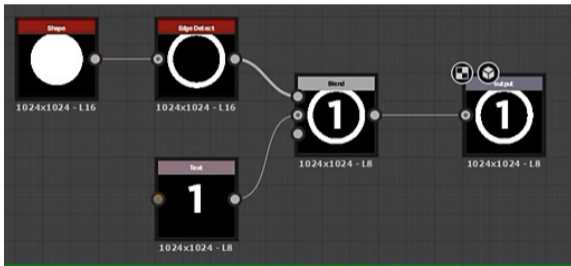
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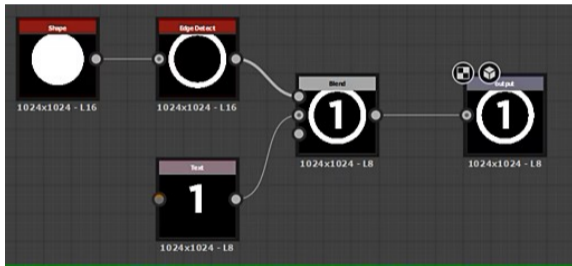
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- we target the **Adobe Substance Designer** node graph system

PROPERTIES OF PROCEDURAL MATERIALS



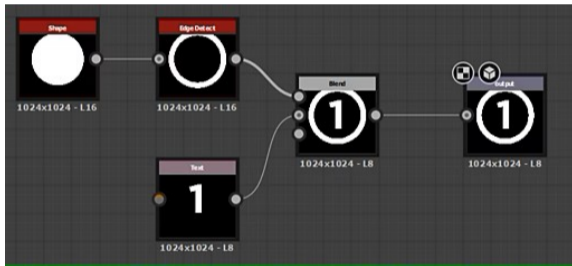
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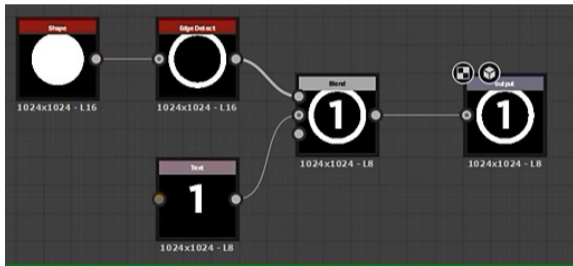
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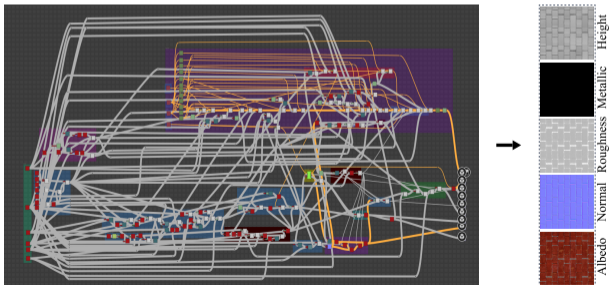
PROPERTIES OF PROCEDURAL MATERIALS



- humans edit procedural material programs **visual-spatially**
 - different from text-based programming paradigms
- node graphs are **compositional**
 - if we traverse graphs topologically we can **inspect intermediate states**

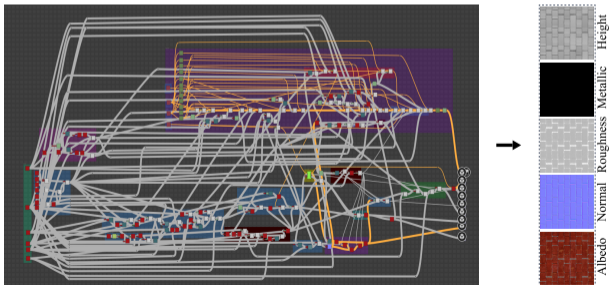
THE PROBLEM

- creating these node graphs manually can become challenging very fast



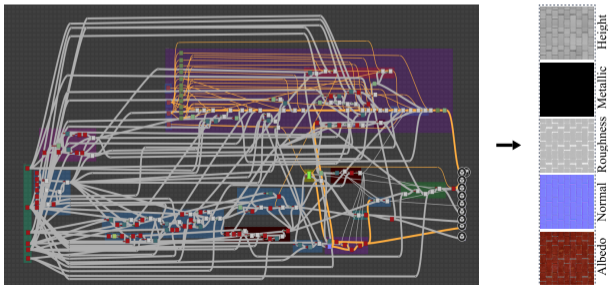
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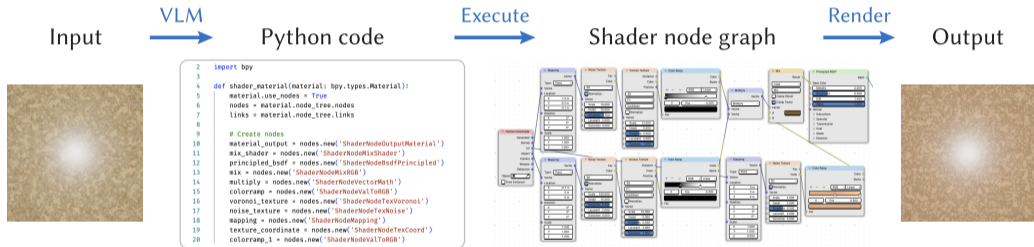


THE PROBLEM

- **creating** these **node graphs** manually can become **challenging** very fast
- requires **professional training**
- **automated synthesis** of procedural materials (e.g., conditioned on images) could **aid users**

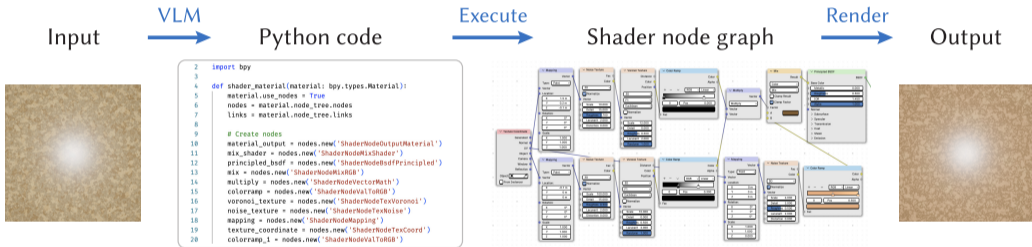


RESEARCH GAP



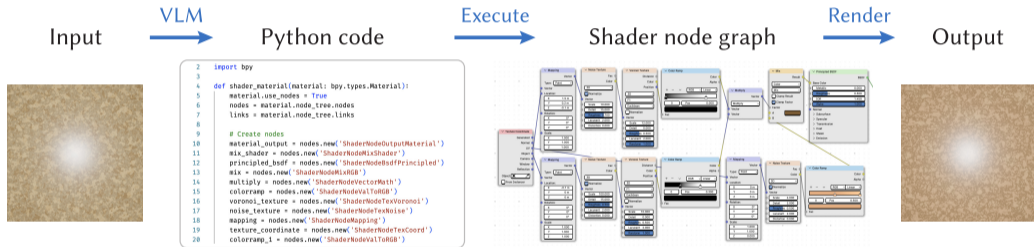
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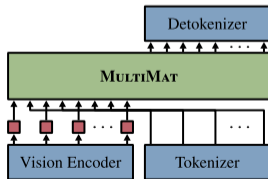
RESEARCH GAP



- past approaches (e.g., VLMATERIAL) generate materials solely as **textual programs**
- fails to capture inherent **visual-spatial** nature that makes them accessible to humans
- we aim to **bridge the gap** between **procedural material synthesis** and the **human workflow**

PRESENTING MULTIMAT

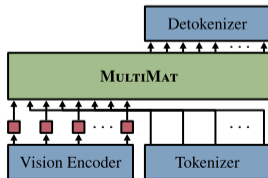
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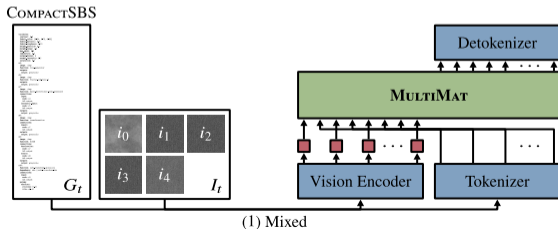
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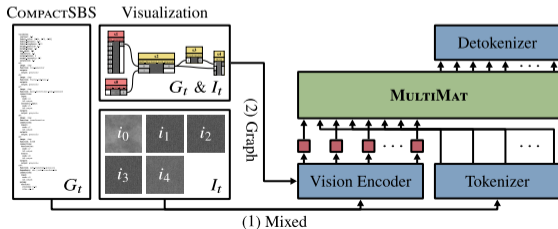
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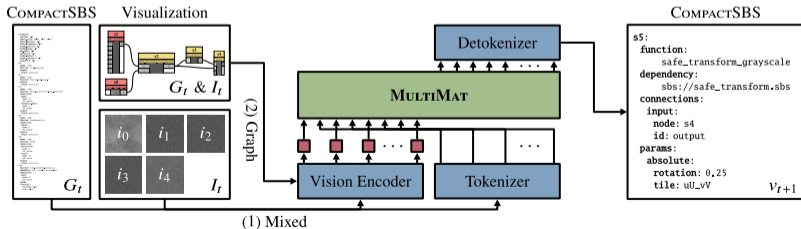
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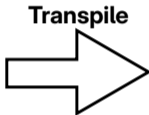
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 - graph: As **visualized graphs** like in human-targeted user interfaces
- iteratively** generates nodes in **topological order** and updates context



CUSTOM INTERMEDIATE REPRESENTATION



Original Format

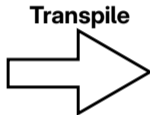


COMPACTSBS

```
s5:  
  function:  
    safe_transform_grayscale  
  dependency:  
    sbs://safe_transform.sbs  
  connections:  
    input:  
      node: s4  
      id: output  
  params:  
    absolute:  
      rotation: 0.25  
      tile: uU_vV
```

V_{f+1}

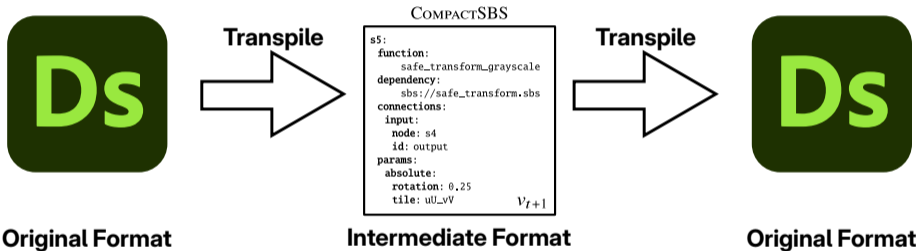
Intermediate Format



Original Format

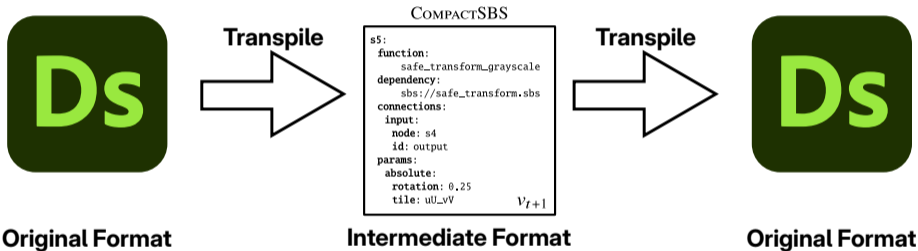
- MultiMat generates outputs in an **intermediate representation**

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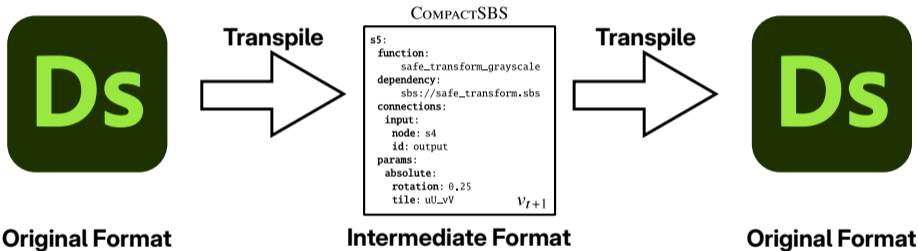
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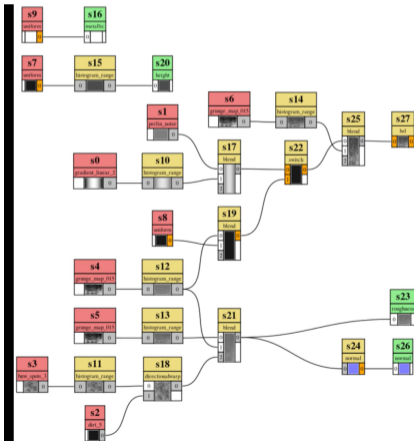
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- MultiMat generates outputs in an **intermediate representation**
 - original Substance Designer format not suitable for language modeling
- we define a new, **human-readable** format that is more than **80% shorter**
 - and implement an **accompanying transpiler** to compile between formats as needed

EXAMPLE



```

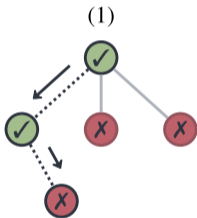
s28:
function: levels
connections:
input:
node: s27
id: output
params:
parent:
levelinlow:
f0:
function: const_float1
f1:
function: const_float1
params:
const_float1: 0.5
f2:
function: get_float1
params:
get_float1: contrast
f3:
function: max
connections:
b: f0
a: f2
f4:
function: mul
connections:
a: f3
b: f1
f5:
function: vector2
connections:
componentsin: f4
componentslast: f4
f6:
function: vector2
connections:
componentsin: f4
  
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IMMEDIATE ERROR HANDLING

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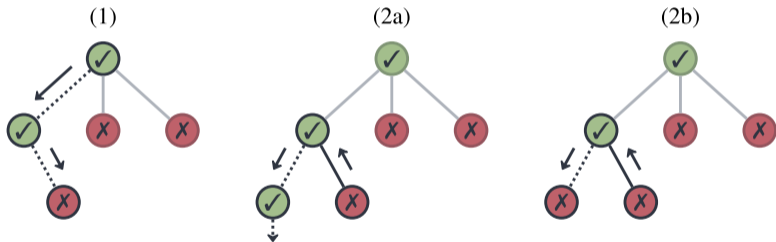
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- **backtrack** immediately in case of errors and find **valid output subspaces**

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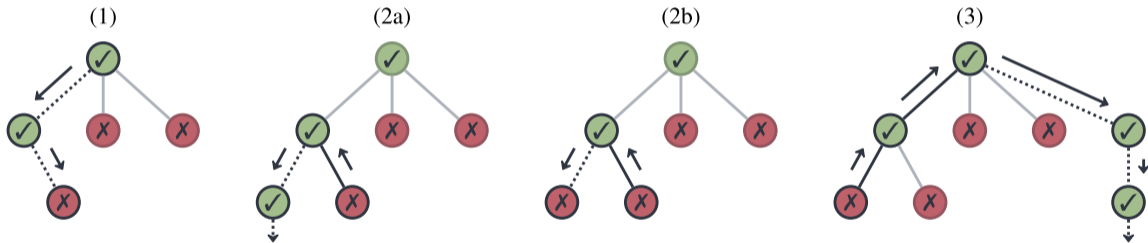
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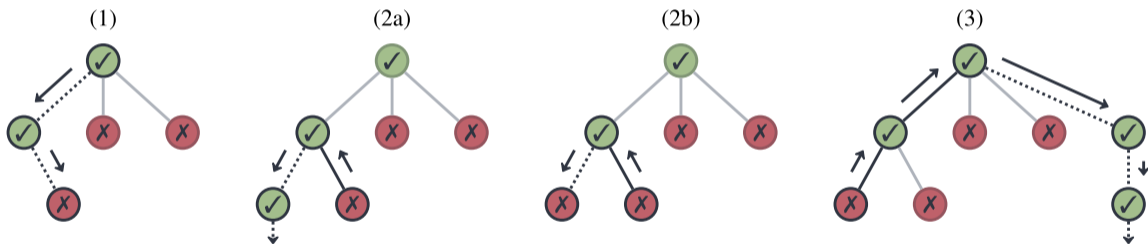
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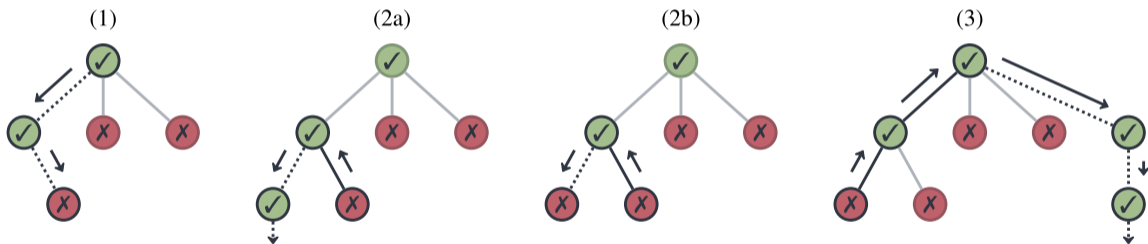
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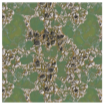
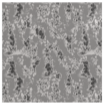
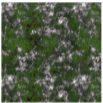




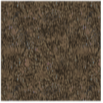



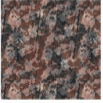




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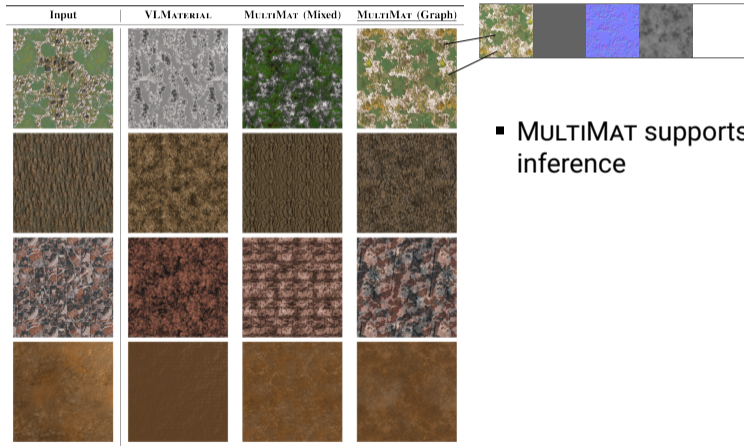
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 - transforms inference step into a **tree search**

RESULTS

Input	VL MATERIAL	MULTIMAT (Mixed)	MULTIMAT (Graph)
			
			
			
			

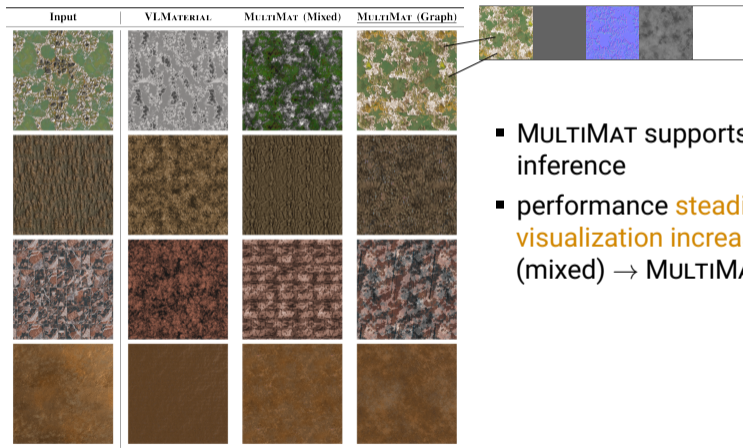
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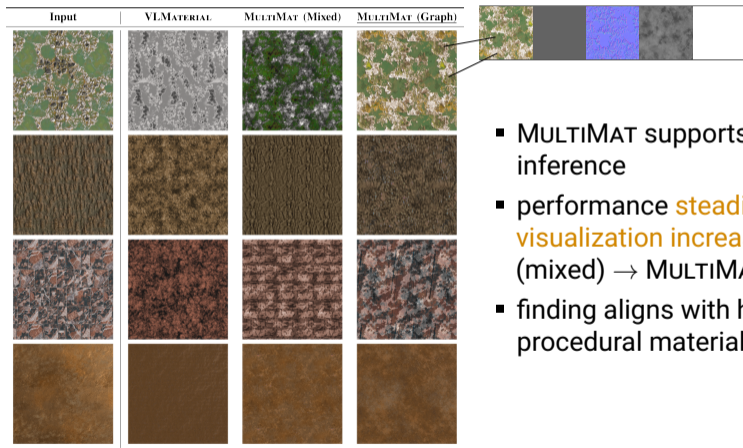
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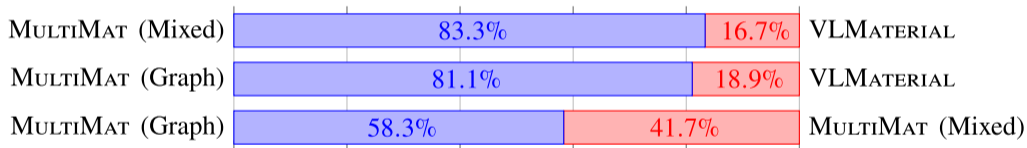
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- MULTIMAT supports **conditional** and **unconditional** inference
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- finding aligns with how **humans** interact with procedural materials

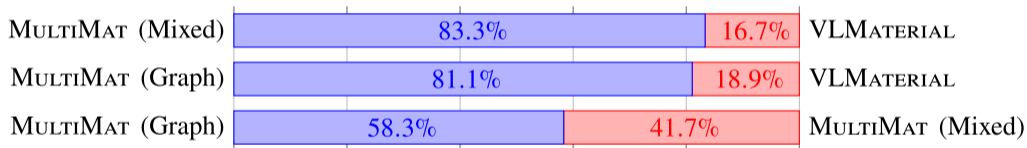
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Humans receive **triplets** of rendered generated materials from each model and identify which output **best and least** resembles the input image and preferences are visualized as a **diverging bar chart**.



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According to humans, **MULTIMAT (Graph)** is the **most preferred model** overall, while VLMATERIAL is consistently the least preferred.

INTERESTED? THERE'S MORE!



In our paper, we additionally conduct an **automatic evaluation** including for **unconditional models**, discuss our **training data collection**, show that MULTIMAT is **less susceptible to errors** than its baseline, and showcase many **more examples** and **also failure cases**.