



# **3DGEER: 3D Gaussian Rendering Made Exact and Efficient *for Generic Cameras***

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Zixun Huang, Cho-Ying Wu, Yuliang Guo, Xinyu Huang, Liu Ren

***Bosch Research North America, Bosch Center for AI***

# Introduction & Motivation

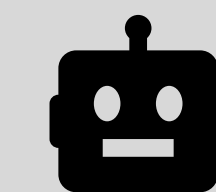
## 3D Gaussian Rendering Breaks in Real-World Settings



AR / VR



Autonomous Vehicles



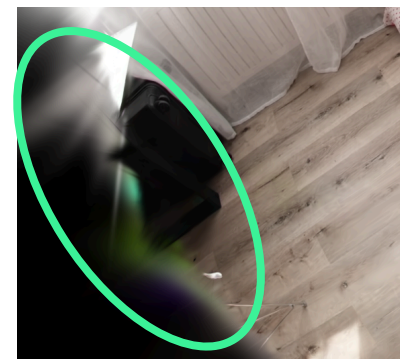
Robots

**The Real World Challenge:** Why Gaussian rendering breaks in autonomous and robotic systems.

# Introduction & Motivation

## 3D Gaussian Rendering Breaks in Real-World Settings

**FisheyeGS**



Limited FoV rendering

**3DGUT**

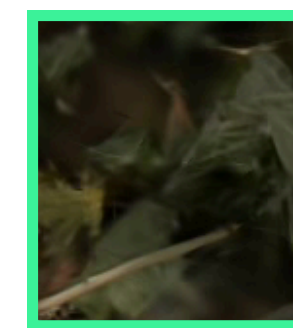


Gridline artifacts

**3DGRT**



GT



3DGRT

Missing geometry  
(e.g., entire leaves) / Slow

**EVER**

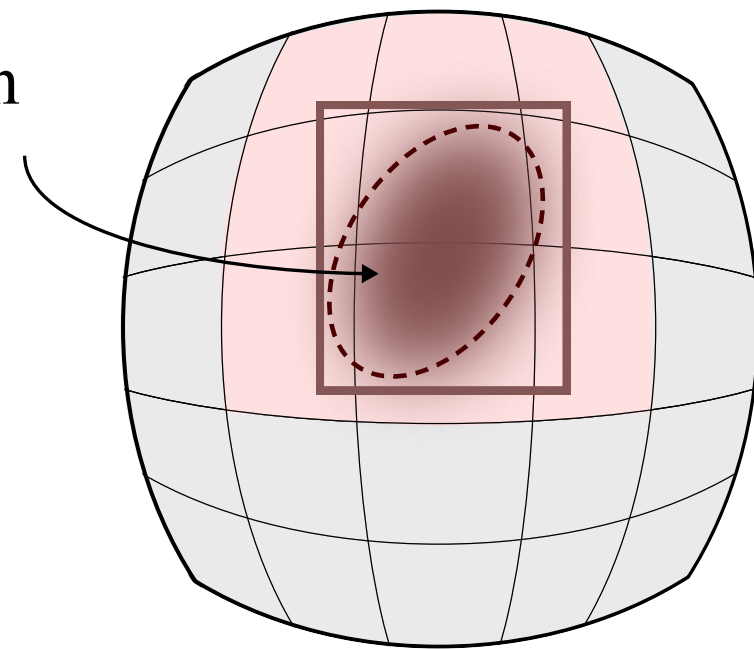


Sharp ellipsoid  
edge artifacts / Slow

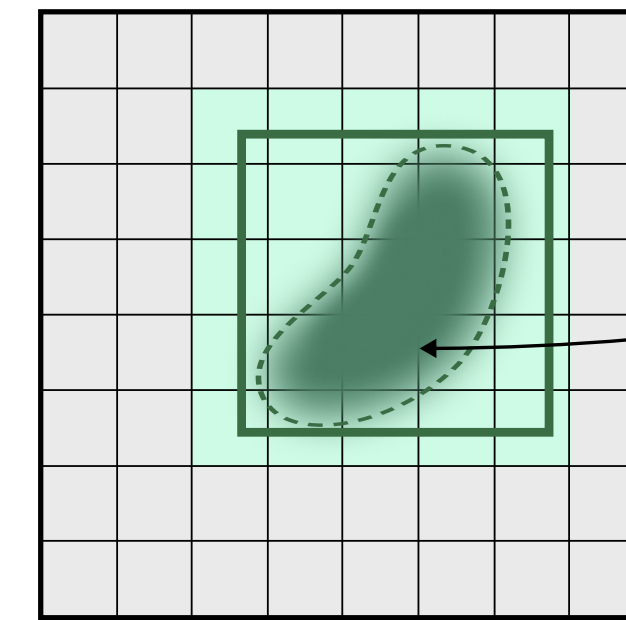
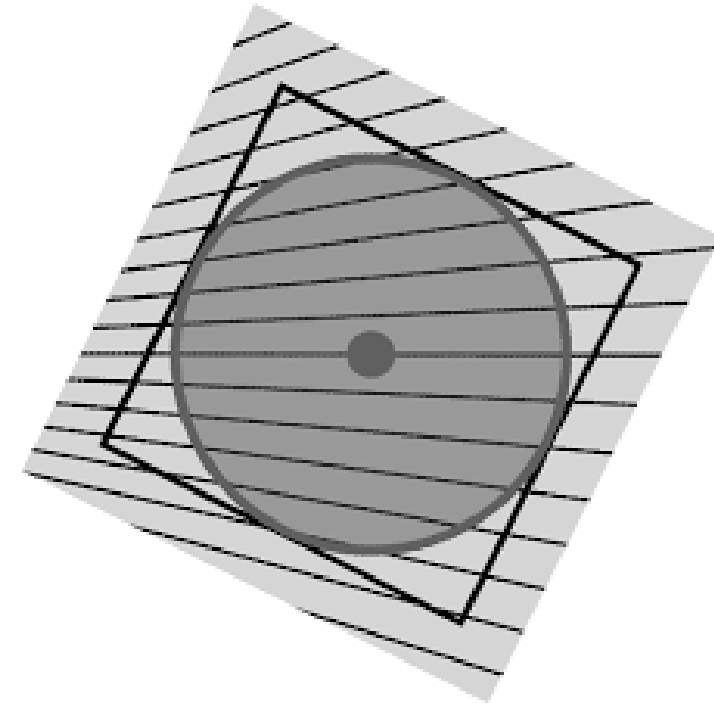
# Hidden Assumptions

## The Root Causes of Artifacts in Wide-FoV Rendering

Jacobian  
Approximation

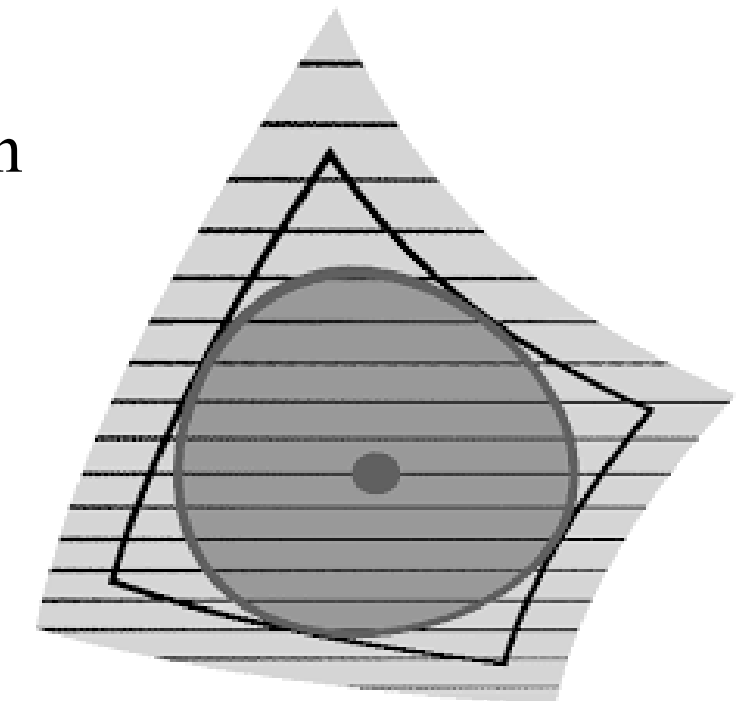


Splatting-Based  
Linear Projection



Ray-Integral-Based  
Non-Linear Projection

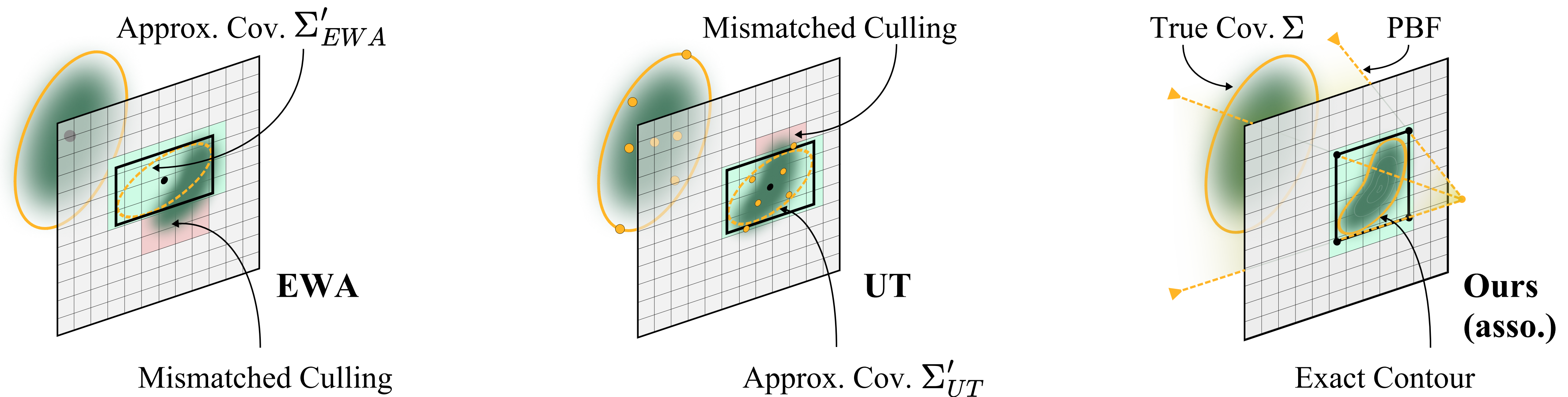
Actual Gaussian  
Density Projection



**Fatal Flaw 1:** Gaussian 3D-2D Projection is Locally Linear

# Hidden Assumptions

## The Root Causes of Artifacts in Wide-FoV Rendering



**Fatal Flaw 2:** Ray-Gaussian Association via Conic Culling

# Methodology

## Gaussian Rendering, Done Right

ATTACHMENT  
VIDEO HERE

**Key Insight 1:** Fixing the Math Behind Gaussian Projection

# Methodology

## Gaussian Rendering, Done Right

ATTACHMENT  
VIDEO HERE

**Key Insight 2:** Fixing the Math Behind Gaussian Association

# Methodology

## Gaussian Rendering, Done Right

ATTACHMENT  
VIDEO HERE

**Key Insight 3:** Optimizing the Ray Distribution  
Behind Pixel-wise Color Supervision

# Results

Accurate, Robust and Efficient under Wide FoV

Bedroom

Training Time FoV



(Original FoV)

FisheyeGS



Gaus.Num: 985k

3DGEER (Ours)



Gaus.Num: 664k

Laboratory



(Original FoV)



Gaus.Num: 840k



Gaus.Num: 582k

Kitchen

Training Time FoV



(Original FoV)

FisheyeGS



Gaus.Num: 760k

3DGEER (Ours)



Gaus.Num: 552k

OfficeRom



(Original FoV)



Gaus.Num: 1072k



Gaus.Num: 732k

Accurate and Efficient under Extreme FoV

# Results

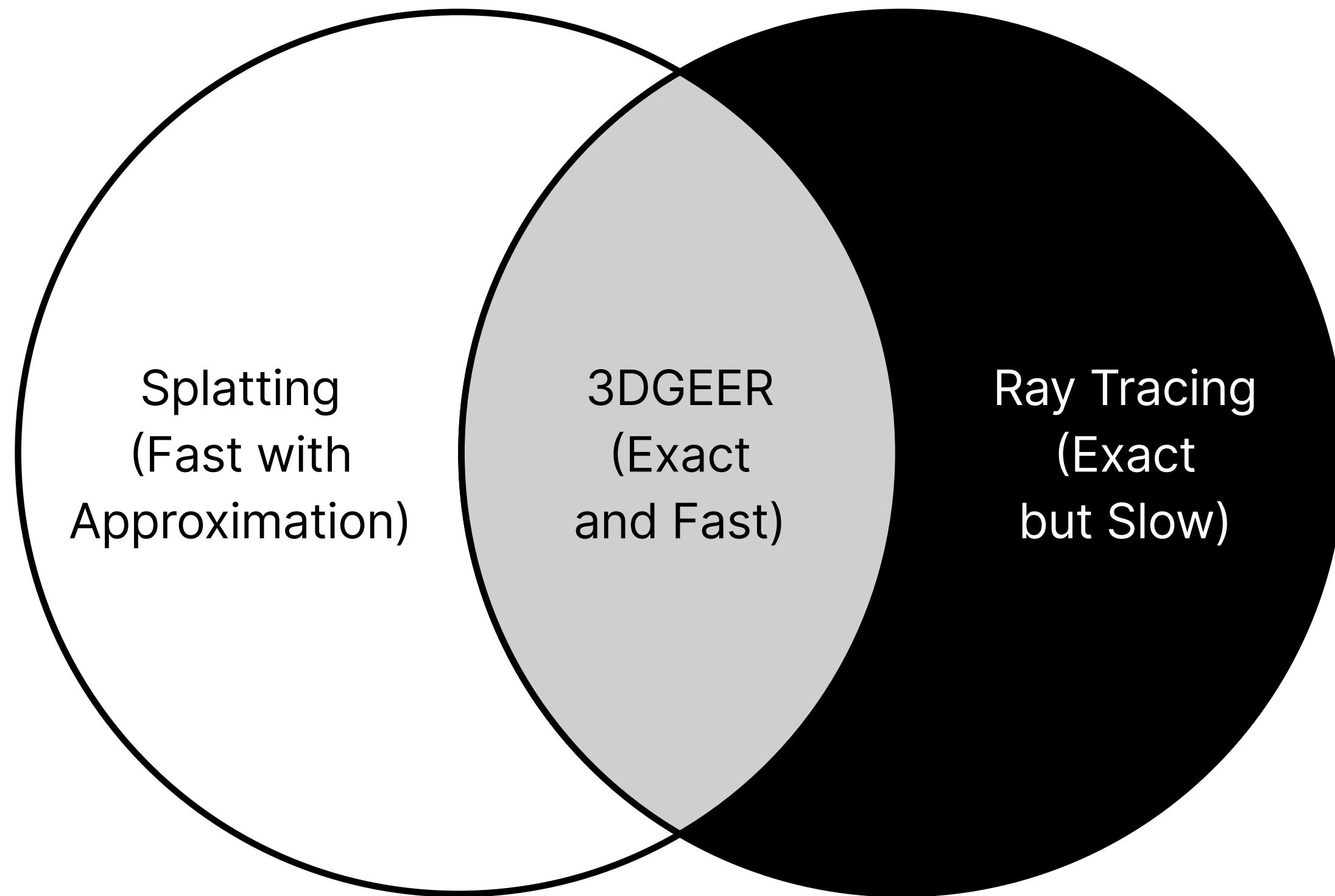
Accurate, Robust and Efficient under Wide FoV

ATTACHMENT  
VIDEO HERE

Association matters more than you expected

# Results

Accurate, Robust and Efficient under Wide FoV



Train Data Test Data Method	1/8 FE		1/8 FE		1/8 FE		1/4 PH		1/4 PH		1/4 PH	
	FE	PH	FE	PH	FE	PH	FE	PH	FE	PH	FE	PH
	PSNR $\uparrow$		SSIM $\uparrow$		LPIPS $\downarrow$		PSNR $\uparrow$		SSIM $\uparrow$		LPIPS $\downarrow$	
FisheyeGS	23.18	26.44	0.858	0.868	0.211	0.239	19.43	26.61	0.791	<b>0.889</b>	0.247	<b>0.212</b>
EVER	25.17	26.14	0.880	0.851	0.153	0.237	22.90	26.45	0.835	0.862	<b>0.207</b>	0.222
3DGUT	24.77	25.59	0.879	0.804	0.183	0.324	18.61	25.96	0.662	0.841	0.300	0.270
3DGEER (Ours)	<b>26.24</b>	<b>27.62</b>	<b>0.897</b>	<b>0.888</b>	<b>0.140</b>	<b>0.214</b>	<b>23.39</b>	<b>27.61</b>	<b>0.846</b>	0.863	0.209	0.254

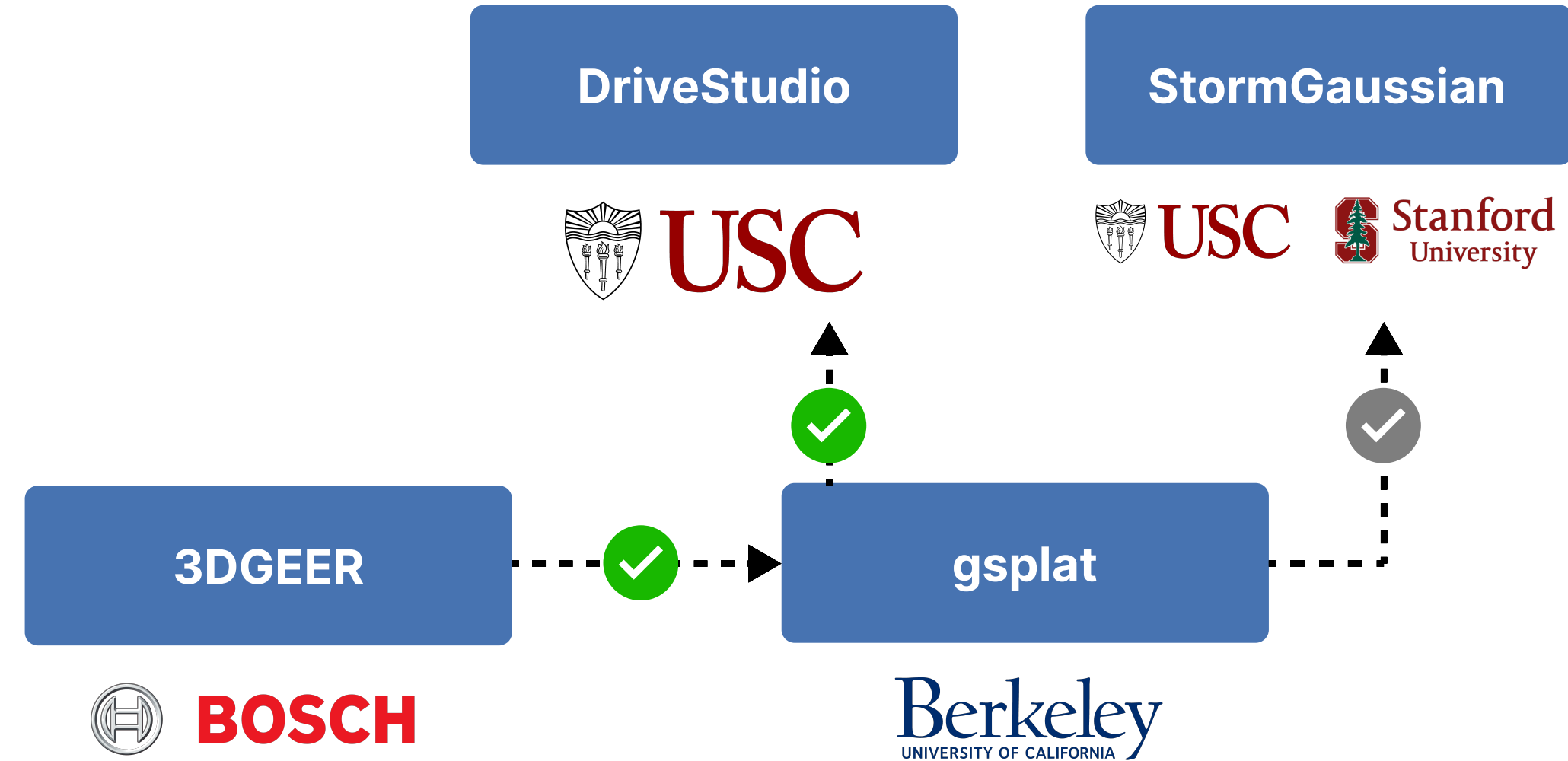
Generalize across camera models

Dataset	Method	Avg. Timings (ms) $\downarrow$				
		Prep.	Dup.	Sort	Render	Total
MipNeRF360	3DGS	0.32	0.27	0.65	1.40	2.92
	3DGEER (Ours)	0.37	0.17	0.27	2.10	3.06
ScanNet++	FisheyeGS	0.10	0.63	1.45	2.33	4.70
	3DGEER (Ours)	0.13	0.26	0.59	2.89	3.98

Maintaining competitive speed

# Open-source Community Support

<https://github.com/boschresearch/3dgeer>



3DGEER now supports dynamic outdoor scene rendering under wide-FoV fisheye cameras with the integration into DriveStudio.