

Explainability of Predictive Uncertainty Models Under Drift in the Telecom Domain

CAO Workshop – ICLR 2026

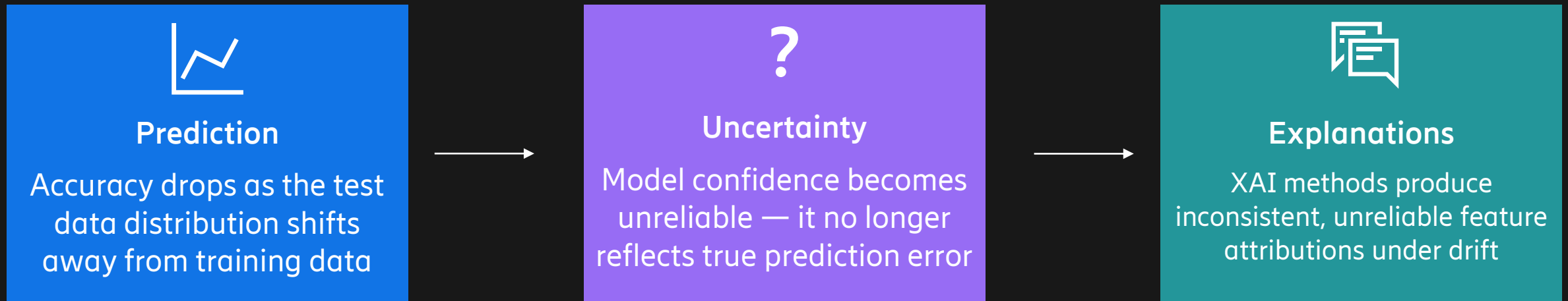
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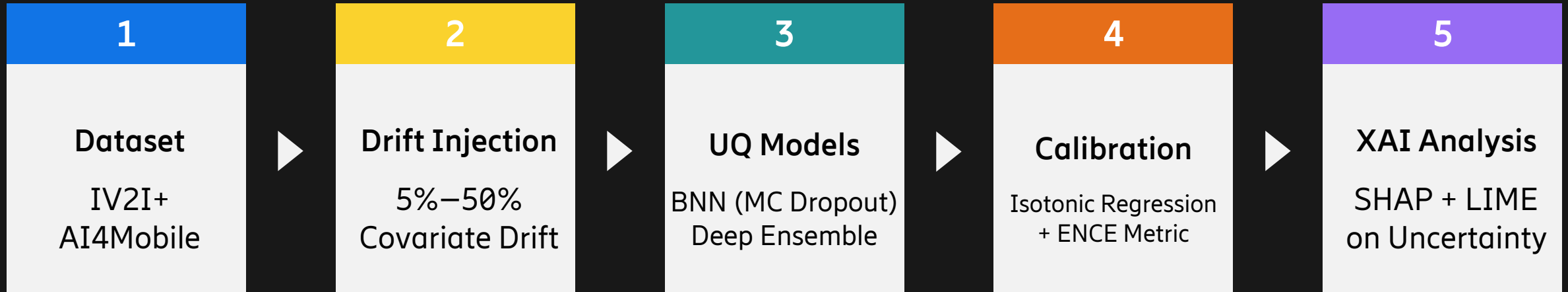
The Problem: When Models Meet the Real World







Gap in the Literature

No existing framework jointly addresses how uncertainty, calibration quality, and XAI attributions co-evolve under controlled covariate drift in a regression setting, especially in real-world telecom environments

Our Unified Framework

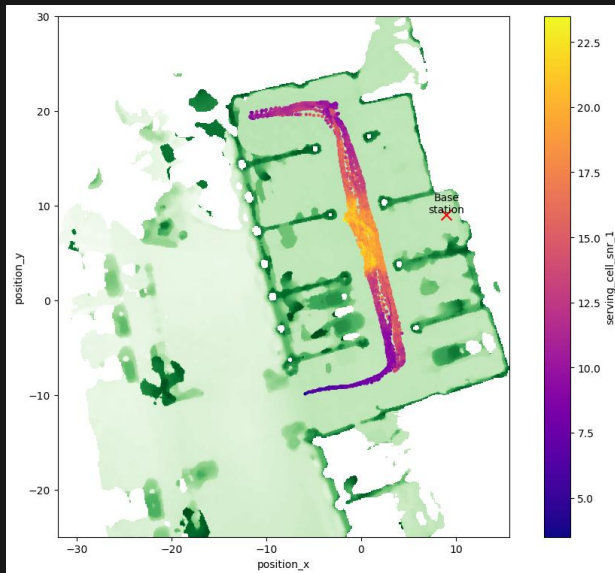


Key Design Choices

-  Drift injected into RSRP, RSRQ, RSSI, SNR only: controlled ground truth for validation
-  XAI applied to predicted uncertainty (variance), not to point predictions
-  Calibration quality assessed before AND after drift, using ENCE metric
-  SHAP (global attribution) + LIME (local explanations) used together for cross-validation

Dataset & Model Architecture

AI4Mobile Dataset



Model 1 – Bayesian Neural Network

Architecture: MLP (10 → 128 → 64 → 32 → 1)

UQ Method: Monte Carlo Dropout ($p=0.2$, T forward passes)

Output: Predictive mean and variance (μ, σ^2)

Model 2 – Deep Ensemble

Architecture: 5 × MLP (10 → 128 → 64 → 32 → 1), different seeds

UQ Method: Variance across ensemble member predictions

Output: Predictive mean and variance (μ, σ^2)

- Both models share the same base architecture for a fair comparison between Bayesian and ensemble approaches to uncertainty quantification
- Calibration via isotonic regression is applied post-hoc, aligning predicted variance with observed squared errors

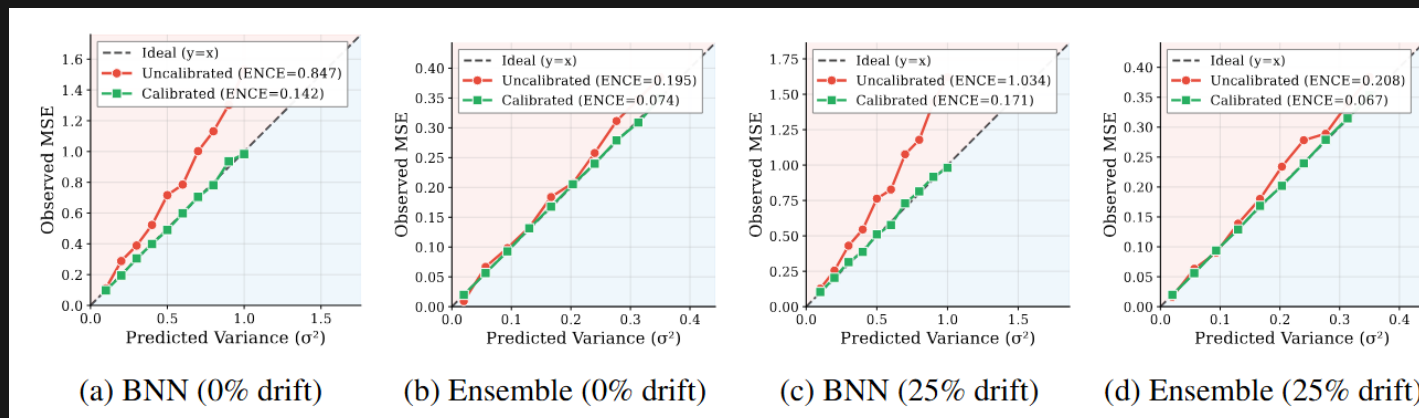
Results – Uncertainty & Calibration Under Drift

ENCE Values Across Drift Levels

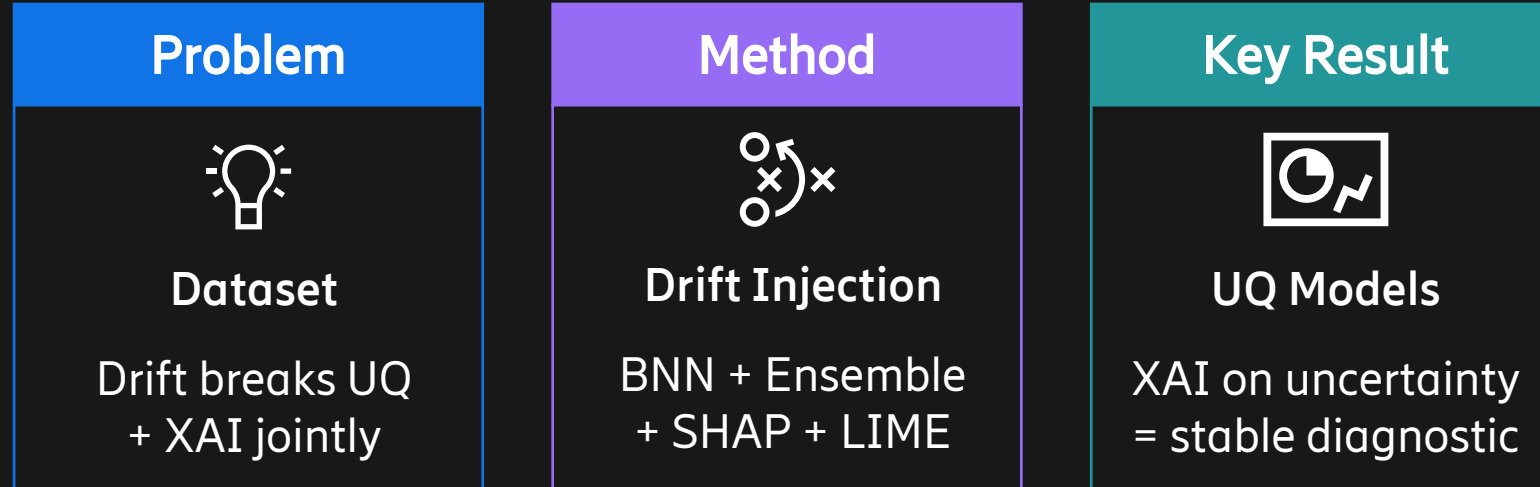
Drift Level	BNN Uncalib.	BNN Calib.	Ens. Uncalib.	Ens. Calib.
0% (baseline)	0.847	0.142	0.195	0.074
10%	0.912	0.158	0.199	0.069
25%	1.034	0.171	0.193	0.070
50%	1.256	0.203	0.208	0.067

Key Observations

- **BNN – Uncalibrated ENCE rises 0.847 → 1.256 (+48%), showing high sensitivity to drift**
- **Deep Ensemble – ENCE stays low and stable. More robust but less adaptive**
- **Calibration always helps — but degrades under drift**



Thank You!



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